

SURVEILLANCE REQUIREMENTS

NOTES

1. Refer to Table 3.3.8.1-1 to determine which SRs apply for each LOP Function.
2. When a channel is placed in an inoperable status solely for performance of required Surveillances, entry into associated Conditions and Required Actions may be delayed for up to 2 hours provided the associated Function maintains DG initiation capability.

SURVEILLANCE		FREQUENCY
SR 3.3.8.1.1	Perform CHANNEL CHECK.	12 hours
SR 3.3.8.1.2	Perform CHANNEL FUNCTIONAL TEST.	31 days
SR 3.3.8.1.3	Perform CHANNEL CALIBRATION.	18 months
SR 3.3.8.1.4	Perform LOGIC SYSTEM FUNCTIONAL TEST.	18 months

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Table 3.3.8.1-1 (page 1 of 1)
 Loss of Power Instrumentation

FUNCTION	REQUIRED CHANNELS PER DIVISION	SURVEILLANCE REQUIREMENTS	ALLOWABLE VALUE
1. Divisions 1 and 2 - 4.16 kV Emergency Bus Undervoltage			
a. Loss of Voltage - 4.16 kV basis	6	SR 3.3.8.1.3 SR 3.3.8.1.4	$\geq 2345 \text{ V}$ and $\leq 3395 \text{ V}$
b. Loss of Voltage - Time Delay	6	SR 3.3.8.1.3 SR 3.3.8.1.4	$\leq 10 \text{ seconds}$ <u>$\geq 3876 \text{ V}$ (a)</u>
c. Degraded Voltage - 4.16 kV basis	2	SR 3.3.8.1.4 SR 3.3.8.1.2 SR 3.3.8.1.3 SR 3.3.8.1.4	$\geq 2762 \text{ V}$ and $\leq 3032 \text{ V}$
d. Degraded Voltage - Time Delay	1	SR 3.3.8.1.2 SR 3.3.8.1.3 SR 3.3.8.1.4	$\geq 14 \text{ seconds}$ and $\leq 16 \text{ seconds}$
2. Division 3 - 4.16 kV Emergency Bus Undervoltage			
a. Loss of Voltage - 4.16 kV basis	4	SR 3.3.8.1.3 SR 3.3.8.1.4	$\geq 2345 \text{ V}$ and $\leq 2730 \text{ V}$
b. Loss of Voltage - Time Delay	1	SR 3.3.8.1.3 SR 3.3.8.1.4	$\leq 3.0 \text{ seconds}$ <u>$\geq 3876 \text{ V}$ (a)</u>
c. Degraded Voltage - 4.16 kV basis	<u>2 (b)</u>	SR 3.3.8.1.4 SR 3.3.8.1.2 SR 3.3.8.1.3 SR 3.3.8.1.4	$\geq 2762 \text{ V}$ and $\leq 3032 \text{ V}$
d. Degraded Voltage - Time Delay	1	SR 3.3.8.1.2 SR 3.3.8.1.3 SR 3.3.8.1.4	$\geq 14 \text{ seconds}$ and $\leq 16 \text{ seconds}$

- (a) This value is to be used after Release For Operations (RFO) of the corresponding plant modification. Until RFO of the corresponding plant modification the Degraded Voltage - 4.16 kV basis Allowable Value shall be $\geq 3762 \text{ V}$ and $\leq 3832 \text{ V}$.
- (b) This value is to be used after RFO of the corresponding plant modification. Until RFO of the corresponding plant modification the Degraded Voltage - 4.16 kV basis Required Channels per Division shall be 3.

ACTIONS (continued)

CONDITION	REQUIRED ACTION	COMPLETION TIME
G. Three or more required AC sources inoperable.	G.1 Enter LCO 3.0.3.	Immediately

SURVEILLANCE REQUIREMENTS

SURVEILLANCE		FREQUENCY
SR 3.8.1.1	Verify correct breaker alignment and indicated power availability for each offsite circuit.	7 days
SR 3.8.1.2	<p>-----NOTES-----</p> <ol style="list-style-type: none"> 1. Performance of SR 3.8.1.7 satisfies this SR. 2. All DG starts may be preceded by an engine prelube period and followed by a warmup period prior to loading. 3. A modified DG start involving idling and gradual acceleration to synchronous speed may be used for this SR as recommended by the manufacturer. When modified start procedures are not used, the time, voltage, and frequency tolerances of SR 3.8.1.7 must be met. <p>-----</p> <p>3870 Verify each DG starts from standby conditions and achieves steady state voltage ≥ 3740 V and ≤ 4580 V and frequency ≥ 58.8 Hz and ≤ 61.2 Hz.</p>	As specified in Table 3.8.1-1

(continued)

SURVEILLANCE REQUIREMENTS (continued)

SURVEILLANCE	FREQUENCY
<p>SR 3.8.1.7 -----NOTE----- All DG starts may be preceded by an engine prelube period. -----</p> <p>3870 Verify each DG starts from standby condition and achieves, in ≤ 12 seconds, voltage ≥ 2740 V and ≤ 4580 V and frequency ≥ 58.8 Hz and ≤ 61.2 Hz.</p>	<p>184 days</p>
<p>SR 3.8.1.8 -----NOTE----- This Surveillance shall not be performed in MODE 1 or 2. However, credit may be taken for unplanned events that satisfy this SR. -----</p> <p>Verify automatic and manual transfer of unit power supply from the normal offsite circuit to the alternate offsite circuit.</p>	<p>18 months</p>
<p>SR 3.8.1.9 -----NOTES-----</p> <ol style="list-style-type: none"> 1. This Surveillance shall not be performed in MODE 1 or 2. However, credit may be taken for unplanned events that satisfy this SR. 2. If performed with DG synchronized with offsite power, it shall be performed at a power factor ≤ 0.9. <p>-----</p> <p>Verify each DG rejects a load greater than or equal to its associated single largest post accident load and following load rejection, the engine speed is maintained less than nominal plus 75% of the difference between nominal speed and the overspeed trip setpoint or 15% above nominal, whichever is lower.</p>	<p>18 months</p>

(continued)

SURVEILLANCE REQUIREMENTS (continued)

SURVEILLANCE	FREQUENCY
<p>SR 3.8.1.11 -----NOTES-----</p> <ol style="list-style-type: none"> 1. All DG starts may be preceded by an engine prelube period. 2. This Surveillance shall not be performed in MODE 1, 2, or 3. However, credit may be taken for unplanned events that satisfy this SR. <p>-----</p> <p>Verify on an actual or simulated loss of offsite power signal:</p> <ol style="list-style-type: none"> a. De-energization of emergency buses; b. Load shedding from emergency buses for Divisions 1 and 2; and c. DG auto-starts from standby condition and: <ol style="list-style-type: none"> 1. energizes permanently connected loads in ≤ 12 seconds, 2. energizes auto-connected shutdown loads, 3. maintains steady state voltage ≥ 3740 V and ≤ 4580 V, 4. maintains steady state frequency ≥ 58.8 Hz and ≤ 61.2 Hz, and 5. supplies permanently connected and auto-connected shutdown loads for ≥ 5 minutes. 	<p>18 months</p>

(continued)

SURVEILLANCE REQUIREMENTS (continued)

SURVEILLANCE	FREQUENCY
<p>SR 3.8.1.12 -----NOTES-----</p> <ol style="list-style-type: none"> 1. All DG starts may be preceded by an engine prelube period. 2. This Surveillance shall not be performed in MODE 1 or 2. However, credit may be taken for unplanned events that satisfy this SR. <p>-----</p> <p>Verify on an actual or simulated Emergency Core Cooling System (ECCS) initiation signal each DG auto-starts from standby condition and:</p> <ol style="list-style-type: none"> a. In ≤ 12 seconds after auto-start and during tests, achieves voltage ≥ 3740 V and ≤ 4580 V; b. In ≤ 12 seconds after auto-start and during tests, achieves frequency ≥ 58.8 Hz and ≤ 61.2 Hz; and c. Operates for ≥ 5 minutes. 	<p>18 months</p> <p>3870</p>
<p>SR 3.8.1.13 -----NOTE-----</p> <p>This Surveillance shall not be performed in MODE 1, 2, or 3. However, credit may be taken for unplanned events that satisfy this SR.</p> <p>-----</p> <p>Verify each DG's automatic trips are bypassed on an actual or simulated ECCS initiation signal except:</p> <ol style="list-style-type: none"> a. Engine overspeed; b. Generator differential current; and c. Overcrank for DG 1A and DG 1B. 	<p>18 months</p>

(continued)

AC Sources—Operating
 3.8.1

SURVEILLANCE REQUIREMENTS (continued)

SURVEILLANCE	FREQUENCY
<p>SR 3.8.1.14 -----NOTES-----</p> <ol style="list-style-type: none"> 1. Momentary transients outside the load and power factor ranges do not invalidate this test. 2. This Surveillance shall not be performed in MODE 1 or 2. However, credit may be taken for unplanned events that satisfy this SR. <p>-----</p> <p>Verify each DG operating at a power factor ≤ 0.9 operates for ≥ 24 hours:</p> <ol style="list-style-type: none"> a. For ≥ 2 hours loaded ≥ 4256 kW for DG 1A, ≥ 4263 kW for DG 1B, and ≥ 2420 kW for DG 1C; and b. For the remaining hours of the test loaded ≥ 3869 kW for DG 1A, ≥ 3875 kW for DG 1B, and ≥ 2200 kW for DG 1C. 	<p>18 months</p>
<p>SR 3.8.1.15 -----NOTES-----</p> <ol style="list-style-type: none"> 1. This Surveillance shall be performed within 5 minutes of shutting down the DG after the DG has operated ≥ 1 hour loaded ≥ 3869 kW for DG 1A, ≥ 3875 kW for DG 1B, and ≥ 2200 kW for DG 1C. <p>Momentary transients outside of the load range do not invalidate this test.</p> <ol style="list-style-type: none"> 2. All DG starts may be preceded by an engine prelube period. <p>-----</p> <p>Verify each DG starts and achieves, in ≤ 12 seconds, voltage ≥ 3740 V and ≤ 4580 V and frequency ≥ 58.8 Hz and ≤ 61.2 Hz.</p>	<p>18 months</p>

(continued)

SURVEILLANCE REQUIREMENTS (continued)

SURVEILLANCE	FREQUENCY
<p>SR 3.8.1.19 -----NOTES-----</p> <ol style="list-style-type: none"> 1. All DG starts may be preceded by an engine prelube period. 2. This Surveillance shall not be performed in MODE 1, 2, or 3. However, credit may be taken for unplanned events that satisfy this SR. <p>-----</p> <p>Verify, on an actual or simulated loss of offsite power signal in conjunction with an actual or simulated ECCS initiation signal:</p> <ol style="list-style-type: none"> a. De-energization of emergency buses; b. Load shedding from emergency buses for Divisions 1 and 2; and c. DG auto-starts from standby condition and: <ol style="list-style-type: none"> 1. energizes permanently connected loads in ≤ 12 seconds, 2. energizes auto-connected emergency loads, 3. achieves steady state voltage ≥ 3740 V and ≤ 4580 V, 4. achieves steady state frequency ≥ 58.8 Hz and ≤ 61.2 Hz, and 5. supplies permanently connected and auto-connected emergency loads for ≥ 5 minutes. 	<p>18 months</p>

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SURVEILLANCE REQUIREMENTS (continued)

SURVEILLANCE	FREQUENCY
<p>SR 3.8.1.20 -----NOTE----- All DG starts may be preceded by an engine prelube period.</p> <p>3870 Verify, when started simultaneously from standby condition, each DG achieves, in ≤ 12 seconds, voltage ≥ 3740 V and ≤ 4580 V and frequency ≥ 58.8 Hz and ≤ 61.2 Hz.</p>	10 years

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Pages of the Technical Specification Bases

B 3.3 INSTRUMENTATION

B 3.3.8.1 Loss of Power (LOP) Instrumentation

BASES

BACKGROUND

Successful operation of the required safety functions of the Emergency Core Cooling Systems (ECCS) is dependent upon the availability of adequate power sources for energizing the various components such as pump motors, motor operated valves, and the associated control components. The LOP instrumentation monitors the 4.16 kV emergency buses. Offsite power is the preferred source of power for the 4.16 kV emergency buses. If the monitors determine that insufficient power is available, the buses are disconnected from the offsite power sources and connected to the onsite diesel generator (DG) power sources.

Each 4.16 kV emergency bus has its own independent LOP instrumentation and associated trip logic. The voltage for the Division 1, 2, and 3 buses is monitored at two levels, which can be considered as two different undervoltage functions: loss of voltage and degraded voltage.

The LOP instrumentation causes various bus transfers and disconnects. Each Division 1 and 2 emergency bus Loss of Voltage Function is monitored by two undervoltage relays on the emergency bus and two undervoltage relays on each of the two offsite power sources. The outputs of these relays are arranged in a two-out-of-two taken three times logic configuration. Each of these relays is an inverse time delay relay. Each Division 1 and Division 2 emergency bus Degraded Voltage Function is monitored by two undervoltage relays for each emergency bus whose outputs are arranged in a two-out-of-two logic configuration. The output of this logic inputs to a time delay relay (Ref. 1). The Division 3 emergency bus Loss of Voltage Function is monitored by

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Each Division 1, Division 2, and Division 3 emergency bus Degraded Voltage Function is monitored by two undervoltage relays for each emergency bus whose outputs are arranged in a two-out-of-two logic configuration. The output of this logic inputs to a time delay relay (Ref. 1).

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BACKGROUND (continued)

four undervoltage relays whose outputs are arranged in a one-out-of-two taken twice logic configuration. The output of this logic inputs to a time delay relay. ~~The Division 3 emergency bus Degraded Voltage Function is monitored by one undervoltage relay with three output contacts arranged in a three-out-of-three logic configuration. The output of this logic inputs to a time delay relay.~~

APPLICABLE SAFETY ANALYSES, LCO, and APPLICABILITY

The LOP instrumentation is required for the Engineered Safety Features to function in any accident with a loss of offsite power. The required channels of LOP instrumentation ensure that the ECCS and other assumed systems powered from the DGs provide plant protection in the event of any of the analyzed accidents in References 2, 3, and 4 in which a loss of offsite power is assumed. The initiation of the DGs on loss of offsite power, and subsequent initiation of the ECCS, ensure that the fuel peak cladding temperature remains below the limits of 10 CFR 50.46.

Accident analyses credit the loading of the DG based on the loss of offsite power during a loss of coolant accident (LOCA). The diesel starting and loading times have been included in the delay time associated with each safety system component requiring DG supplied power following a loss of offsite power.

The LOP instrumentation satisfies Criterion 3 of the NRC Policy Statement.

The OPERABILITY of the LOP instrumentation is dependent upon the OPERABILITY of the individual instrumentation channel Functions specified in Table 3.3.8.1-1. Each Function must have a required number of OPERABLE channels per 4.16 kV emergency bus, with their setpoints within the specified Allowable Values. A channel is inoperable if its actual trip setpoint is not within its required Allowable Value. The actual setpoint is calibrated consistent with applicable setpoint methodology assumptions.

The Allowable Values are specified for each Function in the Table. Nominal trip setpoints are specified in the setpoint calculations. The nominal setpoints are selected to ensure that the setpoint does not exceed the Allowable Value between CHANNEL CALIBRATIONS. Operation with a trip setpoint less conservative than the nominal trip setpoint,

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1.a, 1.b, 2.a, 2.b. 4.16 kV Emergency Bus Undervoltage
(Loss of Voltage) (continued)

required equipment. The time delay specified for the Divisions 1 and 2 4.16 kV Emergency Bus Loss of Voltage Functions corresponds to a voltage at the 120-volt Basis trip setpoint of ≥ 67 volts and ≤ 97 volts. Lower voltage conditions will result in decreased trip times. The Division 3 4.16 kV Emergency Bus Loss of Voltage Function 120-volt Basis trip setpoint is ≥ 67 volts and ≤ 78 volts.

Six channels of 4.16 kV Emergency Bus Undervoltage (Loss of Voltage) Function per associated emergency bus for Divisions 1 and 2 and four channels for Division 3 are only required to be OPERABLE when the associated DG is required to be OPERABLE to ensure that no single instrument failure can preclude the DG function. (Six channels input to each of the Division 1 and Division 2 DGs and four channels input to the Division 3 DG. Each of the six channels for Division 1 and six channels for Division 2 is an inverse time delay relay. Each of these time delays are considered to be separate channels. For Division 3, the Loss of Voltage Function logic inputs to a single time delay relay. Thus, only one time delay channel is associated with Division 3.) Refer to LCO 3.8.1, "AC Sources—Operating," and LCO 3.8.2, "AC Sources—Shutdown," for Applicability Bases for the DGs.

1.c, 1.d, 2.c, 2.d. 4.16 kV Emergency Bus Undervoltage
(Degraded Voltage)

A reduced voltage condition on a 4.16 kV emergency bus indicates that while offsite power may not be completely lost to the respective emergency bus, power may be insufficient for starting large motors without risking damage to the motors that could disable the ECCS function. Therefore, power supply to the bus is transferred from offsite power to onsite DG power when the voltage on the bus drops below the Degraded Voltage Function Allowable Values (degraded voltage with a time delay). This ensures that adequate power will be available to the required equipment.

The Bus Undervoltage Allowable Values are low enough to prevent inadvertent power supply transfer, but high enough to ensure that sufficient power is available to the required equipment. ~~The Allowable Values have a 120 volt Basis of ≥ 107.5 volts and ≤ 109.5 volts.~~ The Time Delay Allowable

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INSERT for TS Bases at page B 3.3-225

As stated above, the purpose of this instrumentation is to ensure that sufficient power will be available to support the ECCS function during a LOCA. During a LOCA, the ECCS and other safety systems will be initiated at the start of the event. This large loading of the safety buses results in a voltage transient of sufficient magnitude to start the degraded voltage timers. If the degraded voltage relays do not reset, which requires the voltage to be restored to a level above the relay reset setpoint, the bus undervoltage time delay relays will trip, resulting in bus transfer to the DGs. Thus, the relay reset (pick-up) setpoint must be high enough to ensure adequate voltage for the safety-related loads. The Degraded Voltage Allowable Value Specified is the relay reset setpoint. The Allowable Value has a 120-volt basis of ≥ 111.08 volts. (Ref. 5)

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SAFETY ANALYSES,
LCO, and
APPLICABILITY1.c, 1.d, 2.c, 2.d. 4.16 kV Emergency Bus Undervoltage
(Degraded Voltage) (continued)

Values are long enough to provide time for the offsite power supply to recover to normal voltages, but short enough to ensure that sufficient power is available to the required equipment.

Two channels of 4.16 kV Emergency Bus Undervoltage (Degraded Voltage) Function per associated emergency bus for Divisions 1, and 2 and ~~three channels for Division 3~~ are only required to be OPERABLE when the associated DG is required to be OPERABLE to ensure that no single instrument failure can preclude the DG function. (Two channels input to each of the Division 1, and Division 2, DGs and ~~three channels input to the Division 3 DGs~~. The Degraded Voltage Function logic for each Division inputs to a single time delay relay. Thus, only one time delay channel is associated with each Division.) Refer to LCO 3.8.1 and LCO 3.8.2 for Applicability Bases for the DGs.

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ACTIONS

A Note has been provided to modify the ACTIONS related to LOP instrumentation channels. Section 1.3, Completion Times, specifies that once a Condition has been entered, subsequent divisions, subsystems, components, or variables expressed in the Condition discovered to be inoperable or not within limits will not result in separate entry into the Condition. Section 1.3 also specifies that Required Actions of the Condition continue to apply for each additional failure, with Completion Times based on initial entry into the Condition. However, the Required Actions for inoperable LOP instrumentation channels provide appropriate compensatory measures for separate inoperable channels. As such, a Note has been provided that allows separate Condition entry for each inoperable LOP instrumentation channel.

A.1

With one or more channels of a Function inoperable, the Function may not be capable of performing the intended function. Therefore, only 1 hour is allowed to restore the

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INSERT for TS Bases at page B 3.3-226

Footnote (a) and (b) to Table 3.3.8.1-1 explain that the TS changes are effective upon Release for Operation of the corresponding plant modification. The planned modifications are: AP-027 for Division I, AP-028 for Division II, and AP-029 for Division III.

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SR 3.3.8.1.1

This SR has been deleted

~~Performance of the CHANNEL CHECK once every 12 hours ensures that a gross failure of instrumentation has not occurred. A CHANNEL CHECK is normally a comparison of the parameter indicated on one channel to a similar parameter on other channels. It is based on the assumption that instrument channels monitoring the same parameter should read approximately the same value. Significant deviations between the instrument channels could be an indication of excessive instrument drift in one of the channels or something even more serious. A CHANNEL CHECK will detect gross channel failures; thus, it is key to verifying the instrumentation continues to operate properly between each CHANNEL CALIBRATION.~~

~~Agreement criteria are determined by the plant staff based on a combination of the channel instrument uncertainties, including indication and readability. If a channel is outside the criteria, it may be an indication that the instrument has drifted outside its limit.~~

~~The frequency is based on operating experience that demonstrates channel failure is rare. The CHANNEL CHECK supplements less formal, but more frequent, checks of channels during normal operational use of the displays associated with the required channels of the LCO.~~

SR 3.3.8.1.2

A CHANNEL FUNCTIONAL TEST is performed on each required channel to ensure that the entire channel will perform the intended function. For Series Functions, a separate CHANNEL FUNCTIONAL TEST is not required for each Function, provided each Function is tested.

Any setpoint adjustment shall be consistent with the assumptions of the current plant specific setpoint methodology.

The Frequency of 31 days is based on plant operating experience with regard to channel OPERABILITY that demonstrates that failure in any 31 day interval is rare.

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SR 3.3.8.1.3

A CHANNEL CALIBRATION is a complete check of the instrument loop and the sensor. This test verifies the channel responds to the measured parameter within the necessary range and accuracy. CHANNEL CALIBRATION leaves the channel adjusted to account for instrument drifts between successive calibrations consistent with the plant specific setpoint methodology.

The Frequency is based on the assumption of the magnitude of equipment drift in the setpoint analysis.

SR 3.3.8.1.4

The LOGIC SYSTEM FUNCTIONAL TEST demonstrates the OPERABILITY of the required actuation logic for a specific channel. The system functional testing performed in LCO 3.8.1 and LCO 3.8.2 overlaps this Surveillance to provide complete testing of the assumed safety functions.

The 18 month Frequency is based on the need to perform this Surveillance under the conditions that apply during a plant outage and the potential for an unplanned transient if the Surveillance were performed with the reactor at power. Operating experience has shown these components usually pass the Surveillance when performed at the 18 month Frequency.

REFERENCES

1. USAR, Section 8.3.1.1.2.
2. USAR, Section 5.2.2.
3. USAR, Section 6.3.3.
4. USAR, Chapter 15.

5. LP Calculation 19-AN-19

BASES (continued)

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The AC sources are designed to permit inspection and testing of all important areas and features, especially those that have a standby function, in accordance with 10 CFR 50, GDC 18 (Ref. 8). Periodic component tests are supplemented by extensive functional tests during refueling outages under simulated accident conditions. The SRs for demonstrating the OPERABILITY of the DGs are in accordance with the recommendations of Regulatory Guide 1.9 (Ref. 3), Regulatory Guide 1.108 (Ref. 9), and Regulatory Guide 1.137 (Ref. 10).

Where the SRs discussed herein specify voltage and frequency tolerances, the minimum and maximum steady state output voltages of 3740 V and 4580 V respectively, are equal to $\pm 10\%$ of the nominal 4160 V output voltage. The specified minimum and maximum frequencies of the DG is 58.8 Hz and 61.2 Hz, respectively, are equal to $\pm 2\%$ of the 60 Hz nominal frequency. The specified steady state voltage and frequency ranges are derived from the recommendations given in Regulatory Guide 1.9 (Ref. 3). *However, the minimum voltage was increased to ensure adequate voltage to operate all safety-related loads during a DBA (Ref 14).*

SR 3.8.1.1

This SR ensures proper circuit continuity for the offsite AC electrical power supply to the onsite distribution network and availability of offsite AC electrical power. The breaker alignment verifies that each breaker is in its correct position to ensure that distribution buses and loads are connected to their preferred power source and that appropriate independence of offsite circuits is maintained. The 7 day Frequency is adequate since breaker position is not likely to change without the operator being aware of it and because its status is displayed in the control room.

SR 3.8.1.2 and SR 3.8.1.7

These SRs help to ensure the availability of the standby electrical power supply to mitigate DBAs and transients and maintain the unit in a safe shutdown condition.

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Diesel Generator Test Schedule (continued)

A test interval in excess of 7 days (or 31 days, as appropriate) constitutes a failure to meet SRs and results in the associated DG being declared inoperable. It does not, however, constitute a valid test or failure of the DG, and any consecutive test count is not reset.

REFERENCES

1. 10 CFR 50, Appendix A, GDC 17.
2. USAR, Chapter 8.
3. Regulatory Guide 1.9.
4. USAR, Chapter 6.
5. USAR, Chapter 15.
6. Regulatory Guide 1.93.
7. Generic Letter 84-15, July 2, 1984.
8. 10 CFR 50, Appendix A, GDC 18.
9. Regulatory Guide 1.108.
10. Regulatory Guide 1.137.
11. ANSI C84.1, 1982.
12. NUMARC 87-00, Revision 1, August 1991.
13. IEEE Standard 308.
14. IP Calculation 19-AN-19