

4.0 Reactor

4.1 Summary Description

The reactor assembly consists of the reactor pressure vessel (RPV), pressure-containing appurtenances (including CRD housings), incore instrumentation housings, and the head vent and spray assembly plus the reactor internal components described in Subsection 4.1.2. Figures 5.3-2a, 5.3-2b, and Table 5.3-2 show the arrangement of the reactor assembly components. A summary of the important design and performance characteristics is given in Subsection 1.3.1. Loading conditions for reactor assembly components are specified in Subsection 3.9.5.2.

4.1.1 Reactor Pressure Vessel

The reactor pressure vessel includes the Reactor Internal Pump (RIP) casing and flow restrictors in each of the steam outlet nozzles, and the shroud support and pump deck which form the partition between the RIP suction and discharge. The RPV design and description are covered in Section 5.3.

4.1.2 Reactor Internal Components

As described in Subsection 3.9.5.1, the major reactor internal components include:

- (1) The core (fuel, channels, control blades and instrumentation)
- (2) Core support structure (including the shroud, top guide and core plate)
- (3) Shroud head and steam separator assembly
- (4) Steam dryer assembly
- (5) Feedwater spargers
- (6) Core spray
- (7) Core flooding spargers

Except for the Zircaloy in the reactor core, these reactor internals are stainless steel or other corrosion-resistant alloys. The fuel assemblies (including fuel rods and channel), control blades, shroud head and steam separator assembly, and steam dryers and incore instrumentation dry tubes are removable when the reactor vessel is opened for refueling or maintenance.

4.1.2.1 Reactor Core

Important features of the reactor core are:

- (1) The bottom-entry cruciform control rods, which were first introduced in the Dresden-1 reactor in April 1961, have accumulated thousands of hours of service.

- (2) Fixed incore fission chambers (LPRMs) provide continuous local power range neutron flux monitoring. A guide tube in each incore assembly provides for a Traversing Incore Probe (TIP) for calibration and axial detail. Startup Range Neutron Monitors (SRNMs) are located at fixed locations between the LPRMs as shown on Figure 4.1-1. The incore location of the startup and source range instruments provides coverage of the large reactor core and provides an acceptable signal-to-noise ratio and neutron-to-gamma ratio. All incore instrument leads enter from the bottom and the instruments are in service during refueling. Incore instrumentation is presented in Subsection 7.6.1.
- (3) As shown by experience obtained at Dresden-1 and other BWR plants, utilizing the incore flux monitor system, the desired power distribution can be maintained within a large core by proper control rod scheduling.
- (4) The fuel channels (a) provide a fixed flow path for the boiling coolant, (b) serve as a guiding surface for the control rods, and (c) protect the fuel during handling operations.
- (5) The mechanical reactivity control permits criticality checks during refueling and provides maximum plant safety. The core is designed to be subcritical at any time in its operating history with any one control rod fully withdrawn and the other control rods fully inserted.
- (6) The selected control rod pitch represents a practical value of individual control rod reactivity worth, and allows adequate clearance below the pressure vessel between CRD mechanisms for ease of maintenance and removal.
- (7) The reactor core is arranged as an upright circular cylinder containing a large number of fuel cells and is located within the core shroud inside the reactor vessel.

4.1.2.1.1 Fuel Assembly Description

The fuel assembly description is provided in Section 4.2.

4.1.2.1.2 Assembly Support and Control Rod Location

A few peripheral fuel assemblies are supported by the core plate. Otherwise, individual fuel assemblies in the core rest on fuel support pieces mounted on top of the Control Rod Guide Tubes (CRGTs). Each guide tube, with its orificed fuel support, bears the weight of four assemblies and is supported by a CRD penetration nozzle in the bottom head of the reactor vessel. The core plate provides lateral support and guidance at the top of each CRGT and directs the reactor recirculation into the orificed fuel support and through the fuel assemblies. The top guide, mounted on top of the shroud, provides lateral support and guidance for the top of each fuel assembly. The reactivity of the core is controlled by cruciform control rods and their associated mechanical hydraulic drive system. The control rods occupy alternate spaces

between fuel assemblies. Each independent drive enters the core from the bottom, and accurately positions its associated control rod during normal operation with an electric motor-driven ball screw. Scram hydraulic pressure acts on the hollow cylinder to exert several times the force of gravity to insert the control rod during the scram mode of operation. Bottom entry allows optimum power shaping in the core, ease of refueling, and convenient drive maintenance.

4.1.2.2 Shroud

Detailed information on the shroud is provided in Subsection 3.9.5.1.1.1.

4.1.2.3 Shroud Head and Steam Separators

Detailed information on the shroud head and separators is presented in Subsection 3.9.5.1.2.1.

4.1.2.4 Steam Dryer Assembly

Detailed information on the steam dryer assembly is presented in Subsection 3.9.5.1.2.3.

4.1.3 Reactivity Control Systems

4.1.3.1 Operation

The control rods perform dual functions of power distribution shaping and reactivity control. Power distribution in the core is controlled during operation of the reactor by manipulation of selected patterns of rods. The rods, which enter from the bottom of the near cylindrical reactor core, are positioned to counterbalance steam voids in the top of the core and effect significant power flattening.

These groups of control rods, used for power flattening, experience a somewhat higher duty cycle and neutron exposure than the other rods in the control system.

The reactivity control function requires that all rods be available for either reactor “scram” (prompt shutdown) or reactivity regulation. Because of this, the control rods are mechanically designed to withstand the dynamic forces resulting from a scram. They are connected to bottom mounted, electro-hydraulically actuated drive mechanisms which allow either electric motor-controlled axial positioning for reactivity regulation or hydraulic rapid scram insertion. The design of the rod-to-drive connection permits each blade to be attached or detached from its drive without disturbing the remainder of the control system. The bottom-mounted drives permit the entire control system to be left intact and remain operable for tests with the reactor vessel open.

4.1.3.2 Description of Control Rods

A description of the control rods is provided in Section 4.2.

4.1.3.3 Supplementary Reactivity Control

The core control requirements are met by use of the combined effects of the movable control rods, supplementary burnable poison, and variation of reactor coolant flow. Descriptions of the supplementary burnable poison are presented in Sections 4.2 and 4.3.

4.1.4 Analysis Techniques

4.1.4.1 Reactor Internal Components

Computer codes used for the analysis of the internal components are as follows:

- (1) NASTRO4V
- (2) SAP4G07
- (3) HEATER
- (4) USAGE01
- (5) ANSYS
- (6) CLAPS
- (7) ASIST
- (8) SEISM03
- (9) SASSI
- (10) ACSTIC2

Detail descriptions of these programs are given in the following subsections.

4.1.4.1.1 NASTRO4V

NASTRO4V is a GE in-house version of the MSC/NASTRAN program (Digital VAX Version 64) which is developed and maintained by the MacNeal Schweldler Corporation in Los Angeles. As a general purpose computer program for finite element analysis, its capabilities include (1) static response to concentrated and distributed loads, to thermal expansion and to enforced deformation; (2) dynamic response to transient loads, to steady-state sinusoidal loads and to random excitation; (3) determination of real and complex eigen values for use in vibration analysis, dynamic stability analysis, and elastic stability analysis; (4) nonlinear static and dynamic analysis including material and geometric non-linearities; and (5) steady-state and transient heat conduction.

4.1.4.1.2 SAP4G07

SAP4G07 is a general-purpose finite element computer program used to perform stress, dynamic, and seismic analyses of structural, mechanical and piping components. Dynamic analyses can be done using direct integration or mode superposition. Response spectrum analysis (a mode superposition method) can include multiple support excitation. SAP4G07 is a GE in-house program based on similar programs developed by E. L. Wilson of UC Berkeley and Dr. K.J. Bathe.

4.1.4.1.3 HEATER

HEATER is a computer program used in the hydraulic design of feedwater spargers and their associated delivery header and piping. The program utilizes test data obtained by GE using full-scale mockups of feedwater spargers combined with a series of models which represent the complex mixing processes obtained in the upper plenum, downcomer, and lower plenum. Mass and energy balances throughout the Nuclear Steam Supply System (NSSS) are modeled in detail. The program is used (1) in the hydraulic design of the feedwater spargers for each BWR plant, (2) in the evaluation of design modifications, and (3) the evaluation of unusual operational conditions.

4.1.4.1.4 USAGE01

USAGE01 is a GE proprietary computer program used in performing ASME-III Section NB & NG structural fatigue usage calculations. The program follows Paragraphs NB or NG-3222.4e. For SRV cyclic loading, it automatically accounts for the follow-on cycles.

4.1.4.1.5 ANSYS

ANSYS is a general-purpose finite element computer program designed to solve a variety of problems in engineering analysis.

The ANSYS program features the following capabilities:

- (1) Structural analysis, including static elastic, plastic and creep, dynamic, seismic and dynamic plastic, and large deflection and stability analysis.
- (2) One-dimensional fluid flow analysis.
- (3) Transient heat transfer analysis, including conduction, convection, and radiation with direct input to thermal-stress analyses.
- (4) An extensive finite element library, including gaps, friction interfaces, springs, cables (tension only), direct interfaces (compression only), curved elbows, etc. Many of the elements contain complete plastic, creep, and swelling capabilities.

- (5) Plotting—Geometry plotting is available for all elements in the ANSYS library, including isometric and perspective views of three-dimensional structures.
- (6) Restart Capability—The ANSYS program has restart capability for several analyses types. An option is also available for saving the stiffness matrix once it is calculated for the structure, and using it for other loading conditions.

ANSYS is used extensively in GE for elastic and elastic-plastic analysis of the reactor pressure vessel, core support structures, reactor internals, fuel and fuel channel.

4.1.4.1.6 CLAPS

CLAPS is a general purpose, two-dimensional finite element program used to perform linear and nonlinear structural mechanics analysis. The program solves plane stress, plane strain, and axisymmetric problems. It may be used to analyze for (1) instantaneous pressure, temperature and flux changes; (2) rapid transients; and (3) steady-state as well as conventional elastic and inelastic buckling analysis of structural components subjected to mechanical loading.

4.1.4.1.7 ASIST

The ASIST program is a GE code which can be used to obtain load distribution, deflections, critical frequencies and mode shapes in the “in-plane” or “normal-to-plane” modes for planar structures of any orientation that (1) are statistically indeterminate, (2) can be represented by straight or curved beams, and (3) are under basically any loading, thermal gradient, or sinusoidal excitation. Deformations and resulting load distributions are compared considering all strain energies (i.e., bending, torsion, shear and direct). ASIST also considers the effects of the deflected shape on loads and provides deflections calculated for the structure. In addition to this beam column (large deflection) capability, the buckling instability of planar structures can also be calculated for the structure.

The ASIST program has been used to determine spring constants, stresses, deflections, critical frequencies and associated mode shapes for frames, shafts, rotors, and other jet engine components. It has been used extensively as a design and analysis tool for various components of nuclear fuel assemblies.

4.1.4.1.8 SEISM03

SEISM03 is a GE proprietary computer program for non-linear dynamic analysis. It is based on the component element method developed by S. Levy and J.P. Wilkinson of GE CR&D. The method uses basic mass, spring, damper, gap, and coupling elements in a direct integration approach to solve non-linear dynamic analysis. This is the main dynamic analysis engineering computer program (ECP). Other programs used in conjunction with SEISM03 are:

- (1) SEPARE

This ECP is a pre-processor for SEISM. It takes the output from CRTFI and phases the input time histories of all loads with the basic load time histories. SEPRE also converts all input loads to the format required for input to SEISM.

(2) **SEPST**

This ECP is the SEISM post-processor. SEPST condenses the SEISM output data into a form which is more practical to interpret. It determines and prints the initial values, the maximum and minimum values for all components, and the times of their occurrence. In addition, it generates the response time history plots of selected components.

(3) **CRTFI**

The CRTFI program uses, as input, the scaled or composite horizontal acceleration time histories at the mid fuel and end fuel positions to determine (1) the clamping forces to be applied to the analysis model friction elements, (2) the scram uplift forces on a bundle, (3) inertial forces of the fuel in order to obtain reaction forces on both ends of the fuel, and (4) fuel-center deflection and uplift forces due to scram.

4.1.4.1.9 SASSI

SASSI can be used to perform dynamic soil-structure interaction analysis in two or three dimensions. The seismic environment consists of an arbitrary three-dimensional (3-D) superposition of inclined body waves and surface waves. The site consists of semi-infinite elastic or viscoelastic halfspace. The structure and the soil can be modeled using a combination of 3-D solid element, 3-D beam element, four-node quadrilateral plate/shell element, 2-D four-node plane strain element, 3-D spring element, and stiffness/mass matrix element. Seismic load in the form of an acceleration time history can be applied to one of the three global directions at a control point on a soil layer interface. External forces or moments such as impact loads, wave forces, or loads from the rotating machinery can be introduced directly to nodes in the soil-structure system.

SASSI is formulated in the frequency domain using the complex response method and the finite element technique. Although it is strictly a linear program, approximate non-linear analysis can be performed by an iterative scheme called "Equivalent Linear Method."

4.1.4.1.10 ACSTIC2

ACSTIC2 is a Westinghouse computer code which is used for predicting the amplitudes of pump-induced acoustic pressures in fluid-handling systems using a node-flow path discretization methodology and a harmonic analysis algorithm. The pump is represented as what has been referred to in the literature as a "volumetric forcing function." With this program, the fluid system is broken into nodes (pressure) and flow paths (mass flow), the latter

connecting the former in multi-dimensional arrays or networks. The computer code is used to calculate pump-induced pressure pulsation loads on reactor internals.

4.1.4.2 Fuel Design Analysis

The fuel design analysis models are discussed in Section 4.2.

4.1.4.3 Reactor Systems Dynamics

The analysis techniques and computer codes used in reactor systems dynamics are discussed in References 4.1-1 and 4.1-2.

4.1.4.4 Nuclear Analysis

The analysis techniques are discussed in Section 4.3.

4.1.4.5 Neutron Fluence Calculations

Neutron vessel fluence calculations were carried out using a two-dimensional, discrete ordinates, Sn transport code with general anisotropic scattering.

This code is the most widely used two-dimensional, discrete ordinates code for solving various radiation transport problems. The program will solve both fixed source and multiplication problems. Rectangular (XY, or RZ) and polar (R, θ) geometry are allowed with various boundary conditions. The fluence calculations incorporate, as an initial starting point, neutron fission distributions prepared from core physics data as a distributed source. Anisotropic scattering was considered for all regions. The cross sections were prepared with 1/E flux weighting polynomial expansion matrices for anisotropic scattering but did not include the resonance self-shielding factors.

4.1.4.6 Thermal-Hydraulic Calculations

The thermal-hydraulic models are discussed in Section 4.4.

4.1.5 References

- 4.1-1 "Reference Safety Report for Boiling Water Reactor Reload Fuel", CENPD-300-P-A, July 1996.
- 4.1-2 "Reference Safety Report for Boiling Water Reactor Fuel and Core Analyses Supplement 1 to CENPD-300-P-A," WCAP 17322-P, September 2010.

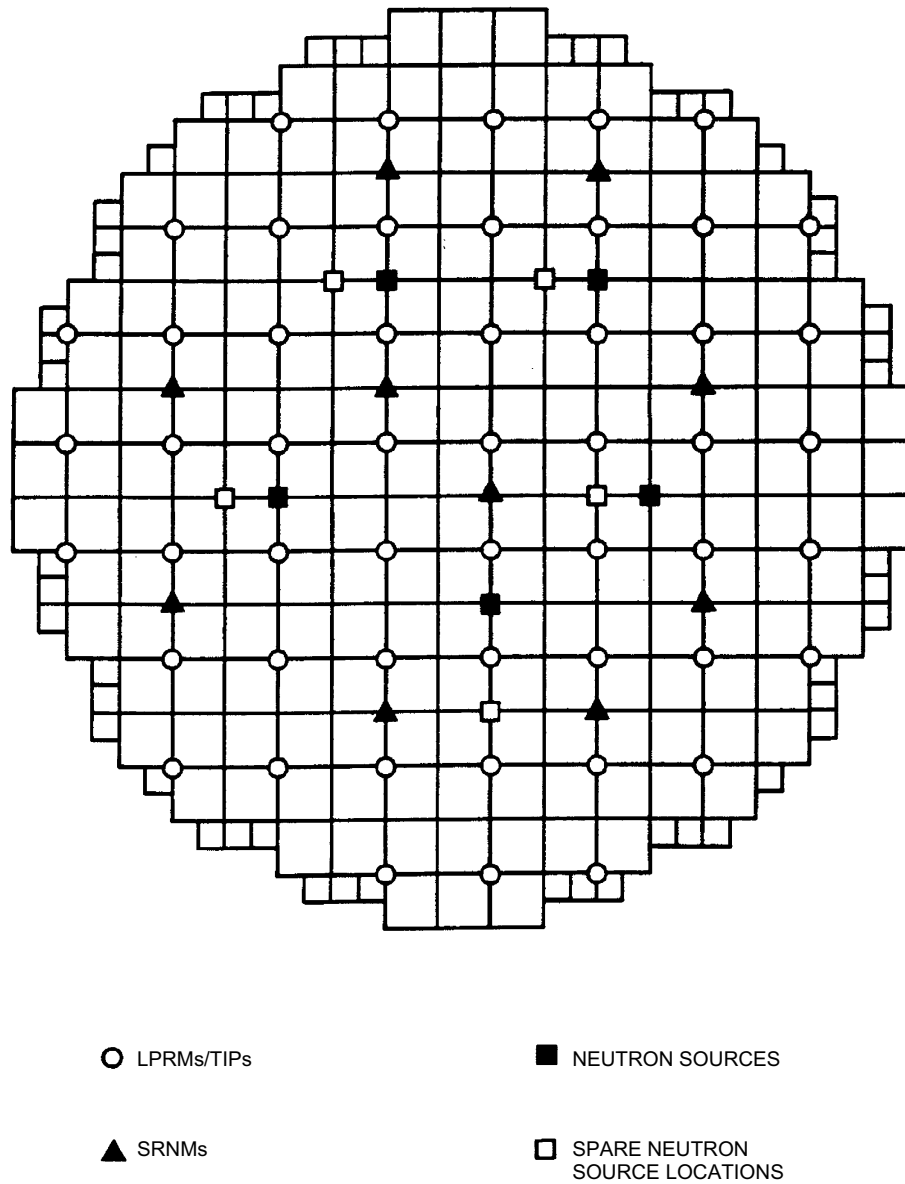


Figure 4.1-1 Core Configuration with Location of Instrumentation