

**APEX-AP1000 Confirmatory Testing
To Support
AP1000 Design Certification
(Non-Proprietary)**

**U.S. Nuclear Regulatory Commission
Office of Nuclear Regulatory Research
Washington, DC 20555-0001**



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ABSTRACT

This report summarizes the confirmatory testing performed using the Advanced Plant Experiment (APEX) facility at Oregon State University (OSU). The APEX is a unique thermal-hydraulic integral system test facility, which is used to assess the performance of passive safety systems and was modified to accurately represent the design of the Westinghouse AP1000 advanced passive nuclear reactor. The U.S. Nuclear Regulatory Commission (NRC) sponsored eight beyond-design-basis accident (DBA) tests in the APEX facility, which were successfully completed from June 2003 through July 2004 and are discussed in detail in this report. Those eight beyond-DBA tests investigated scenarios with two or more simultaneous failures of the AP1000 passive safety systems during large- and small-break loss-of-coolant accidents, including station blackout and cold shutdown conditions. The experiments run in APEX-AP1000 confirm significant liquid entrainment and carryover of water to the automatic depressurization system (ADS) during and after actuation of the fourth-stage (ADS4) valves. These processes are important as thermal-hydraulic codes used to analyze the AP1000 design must adequately predict or bound upper plenum and hot leg entrainment. In addition, the tests show that failure of ADS4 valves on the non-pressurizer side of the plant results in a greater delay in in-containment refueling water storage tank (IRWST) injection than failure of ADS4 valves on the pressurizer side of the plant; while failure of two out of four ADS4 valves on the non-pressurizer side of the plant produces low two-phase mixture levels in the core during certain simulated vessel injection line and cold leg breaks.

FOREWORD

The U.S. Nuclear Regulatory Commission (NRC) has reviewed Westinghouse Electric Company's request, dated March 28, 2002, for final design approval and standard design certification for the AP1000 advanced passive nuclear reactor. The AP1000 standard design is essentially an updated version of Westinghouse's AP600 design, which the NRC certified on December 16, 1999.

Following receipt of an application for certification of a new nuclear power plant design, the NRC's standard design certification process involves an acceptance review, a technical review, and a rulemaking to certify the design. The AP1000 design certification review involved technical reviewers from the NRC's Offices of Nuclear Reactor Regulation, Nuclear Security and Incident Response, and Nuclear Regulatory Research. These reviewers carefully considered the AP1000 Design Control Document (DCD) and Probabilistic Risk Assessment in accordance with the applicable and technically relevant standards for reviewing design certification applications, as set forth in Title 10, Section 52.48, of the *Code of Federal Regulations* (10 CFR 52.48). In addition, the reviewers considered those standards that were modified by the exemptions identified in the final safety evaluation report (FSER) for the AP1000 design, which the NRC published as NUREG-1793 in September 2004.

In support of the NRC's design certification activities, this report documents the confirmatory integral testing conducted at Oregon State University's Advanced Plant Experiment (APEX) facility. Specifically, the NRC sponsored 8 beyond-design-basis accident (DBA) tests run in APEX, which is a one-quarter height, one-half time scale, reduced-pressure, integral test facility modified to represent AP1000 conditions. Those 8 beyond-DBA tests investigated scenarios with two or more simultaneous failures of the AP1000 passive safety system during large- and small-break loss-of-coolant accidents, including station blackout and cold shutdown conditions. The objectives of these beyond-DBA tests were to confirm AP1000 safety margins and provide a database to assess NRC's thermal-hydraulic computer codes. This report presents the results of these tests, along with a detailed scaling analysis and facility description.

Review of the APEX-AP1000 test results conclusively shows that the core remains cooled and did not experience heatup for most of the beyond-DBA scenarios. These test results were factored into the final evaluation of the AP1000 design and, on the basis of their independent analysis described in the FSER, the NRC staff concluded that Westinghouse's application for AP1000 design certification meets the applicable content requirements of 10 CFR 52.47, as well as the review standards of 10 CFR 52.48.



Carl J. Paperiello, Director
Office of Nuclear Regulatory Research

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EXECUTIVE SUMMARY

This report documents the confirmatory testing performed using the Advanced Plant Experiment (APEX) facility at Oregon State University (OSU). The APEX is a unique thermal-hydraulic integral system test facility, which is used to assess the performance of passive safety systems and was modified to accurately represent the designs of the Westinghouse AP600 and AP1000 advanced passive nuclear reactors. The U.S. Nuclear Regulatory Commission (NRC) sponsored eight beyond-design-basis accident (DBA) tests of the AP1000 design, which were successfully completed in the APEX facility from June 2003 through July 2004. This program had the following objectives:

- Conduct tests to assess the performance of the Westinghouse AP1000 passive safety systems for a select range of beyond-DBA scenarios.
- Generate data to confirm analyses that Westinghouse submitted for AP1000 design certification.
- Obtain experimental data to benchmark the NRC's thermal-hydraulic computer codes.

The NRC extensively used data from the APEX facility in the AP600 design certification process, drawing upon approximately 75 tests for use in code assessment and qualification of the AP600 safety margin. To address performance specific to the AP1000 design (essentially an uprated version of the AP600 design), the APEX facility underwent significant modifications in 2002 in order to more accurately represent the AP1000. That facility modification included an increase in the maximum core power; new pressurizer (PZR) and surge lines; larger core makeup tanks (CMTs); larger-diameter fourth-stage automatic depressurization system (ADS4) piping; and decreased line resistances for the CMTs, ADS4, and passive residual heat removal (PRHR) heat exchanger. In addition, Reyes performed a comprehensive scaling analysis (Appendix A) to guide the facility modifications to ensure that the APEX experiments preserved AP1000 conditions.

This study investigated several beyond-DBA scenarios, including 1- and 2-inch cold leg breaks, double-ended direction vessel injection (DEDVI) line breaks, Mode 5 operation with loss of residual normal heat removal system (RNS) cooling, and station blackout. Based on experience from analyzing previous AP600 tests, one of the main purposes of the APEX-AP1000 test program was to investigate the sensitivity of the failure of the automatic depressurization system (ADS) on core coolability.

Based on the experiments run in the APEX facility, we can draw the following conclusions:

- (1) The APEX-AP1000 tests confirm significant liquid entrainment and carryover of water to the ADS4 system during and after ADS4 valve actuation. High liquid carryover to the ADS4 may occur in the AP1000 reactor. These data are appropriate for assessment of thermal-hydraulic codes used to analyze the AP1000.
- (2) Test results from tests NRC-AP1000-03, 05, and DBA-02 show that failure of ADS4 valves on the non-pressurizer side of the plant results in a greater delay in in-containment refueling water storage tank (IRWST) injection than failure of ADS4 valves on the pressurizer side of the plant.

- (3) Failure of two out of four ADS4 valves on the non-pressurizer side of the plant results in core uncover (based on the two-phase mixture level) during simulated DEDVI line and cold leg breaks.
- (4) Review of the APEX-AP1000 DBA test results and code calculations submitted by Westinghouse for design certification conclusively show that the core remains cooled, and heatup was not experienced for design-basis scenarios. In fact, core heatup was only experienced in select beyond-DBA tests (NRC-AP1000-05 and 06).

ABBREVIATIONS

ACC	Accumulator
ADS	Automatic Depressurization System
ADS4	Fourth-Stage Automatic Depressurization System
AP600	Advanced Passive 600-MWe Plant (Westinghouse)
AP1000	Advanced Passive 1,000-MWe Plant (Westinghouse)
APEX	Advanced Plant Experiment (OSU Facility)
ASME	American Society of Mechanical Engineers
BAMS	Break and ADS Measurement System
CCFL	Counter-Current Flow Limitation
CFR	<i>Code of Federal Regulations</i>
CL	Cold Leg
CMT	Core Makeup Tank
CMT-PBL	Core Makeup Tank Pressure Balance Line
CRP	Condensate Return Pump
CRT	Condensate Return Tank
CVS	Chemical and Volume System
DAS	Data Acquisition System
DBA	Design-Basis Accident
DCD	Design Control Document (AP1000)
DEDVI	Double-Ended Direction Vessel Injection
DI	Demineralization System
DP	Differential Pressure
DVI	Direct Vessel Injection
FMM	Magnetic Flowmeter
FSER	Final Safety Evaluation Report
FST	Feedwater Storage Tank
FVM	Vortex Flowmeter
H2TS	Hierarchical Two-Tiered Scaling
HL	Hot Leg

HPS	Heated Phase Switch
HX	Heat Exchanger
IRWST	In-Containment Refueling Water Storage Tank
KW	Heater Power
LCT	Load Cell Transducer
LDP	Differential Pressure Level
LOCA	Loss-of-Coolant Accident
LT	Level Transducer
MFP	Main Feedwater Pump
NI	National Instruments
NRC	U.S. Nuclear Regulatory Commission
NSSS	Nuclear Steam Supply System
OSU	Oregon State University
P&ID	Piping and Instrumentation Drawings
PBL	Pressure Balance Line
PC	Process Controller
PIRT	Phenomena Identification and Ranking Table
PLC	Programmable Logic Controller
PORV	Power Operated Relief Valve
PRHR	Passive Residual Heat Removal
PT	Pressure Transducer
PZR	Pressurizer
RCP	Reactor Coolant Pumps
RCS	Reactor Coolant System
RNS	Residual Normal Heat Removal System
ROSA	Rig of Safety Assessment
RPV	Reactor Pressure Vessel
RSO	Return to Saturation Oscillation
Rx	Reactor Vessel
SB	Small Break

SBLOCA	Small-Break Loss-of-Coolant Accident
SCR	Silicon Control Rectifier
SG	Steam Generator
T/C	Thermocouple
TF	Fluid Temperature
TH	Heater Rod Temperature
TR	Thermocouple Rod
TW	Wall Temperature

1. INTRODUCTION

This report documents the confirmatory testing performed using the Advanced Plant Experiment (APEX) facility at Oregon State University (OSU). The APEX is a unique thermal-hydraulic integral system test facility (Figure 1.1), which is used to assess the performance of passive safety systems and was modified to accurately represent the Westinghouse AP600 and AP1000 advanced passive nuclear reactor designs. The U.S. Nuclear Regulatory Commission (NRC) sponsored this research through Contract #NRC-04-03-049, which encompassed eight beyond-design-basis accident (DBA) tests of the AP1000 design. Testing began in June 2003, and the final test was completed in July 2004. This program had the following objectives:

- Conduct tests to assess the performance of the Westinghouse AP1000 passive safety systems for a select range of beyond-DBA scenarios.
- Generate data to confirm analyses that Westinghouse submitted for AP1000 design certification.
- Obtain experimental data to benchmark the NRC's thermal-hydraulic computer codes.

The NRC extensively used data from the APEX facility in the AP600 design certification process, drawing upon approximately 75 tests for use in code assessment and qualification of AP600 safety margin. To address performance specific to the AP1000 design (essentially an uprated version of the AP600 design), the APEX facility underwent significant modifications in 2002 in order to more accurately represent the AP1000. The facility modification included an increase in the maximum core power; new pressurizer (PZR) and surge lines; larger core makeup tanks (CMTs); larger-diameter fourth-stage automatic depressurization (ADS4) system piping; and decreased line resistances for the CMTs, ADS4, and passive residual heat removal (PRHR) heat exchanger (HX).

The study investigated several beyond-DBA scenarios, including 1- and 2-inch cold leg breaks, double-ended direction vessel injection (DEDVI) line breaks, Mode 5 operation with loss of residual normal heat removal system (RNS) cooling, and station blackout. Based on experience from analyzing previous AP600 tests, one of the main purposes of the APEX-AP1000 test program was to investigate the sensitivity of the failure of the automatic depressurization system (ADS) on core coolability. Therefore, for each accident scenario, one or more ADS valves were failed on demand or were unavailable for each test.

Chapter 1 includes this introduction, while Chapter 2 describes the results of the comprehensive scaling analysis (Appendix A) conducted by Reyes to guide the modifications to upgrade the APEX facility from AP600 to AP1000 geometries and test conditions. In Chapter 3, the reader can find a detailed facility description with component and instrument information (component dimensions can be found in Appendix B). Chapter 4 summarizes the APEX-AP1000 test results, while Appendix C contains more detailed instrument plots and sequence of events for each test. Readers should note that the non-proprietary version of this report the majority of the information in Appendices A, B, and C has been removed. In addition, a supplement to the proprietary version of this report includes three compact disks containing APEX facility drawings, test reports, and the APEX database.

The APEX Testing Facility

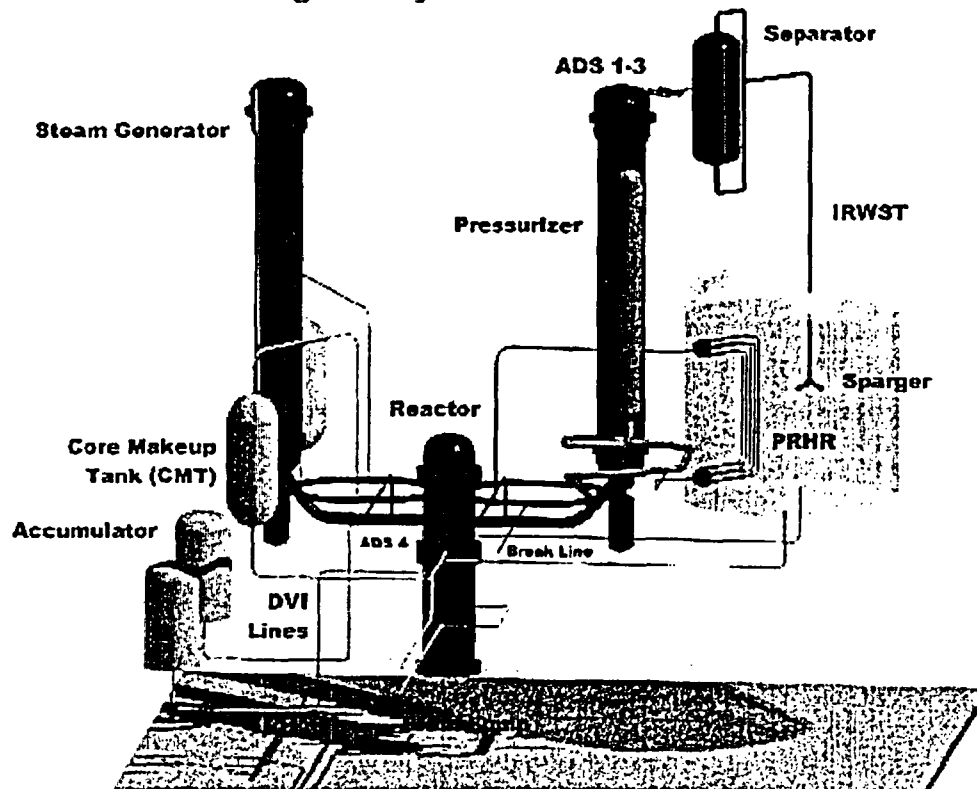


Figure 1.1. APEX Facility Layout

2. SCALING ANALYSIS RESULTS

The APEX-AP1000 scaling analysis by Reyes (Appendix A) provided the basis for modifying core decay power; CMT and PZR volumes; the in-containment refueling water storage tank (IRWST) and containment flood-up elevations; ADS4, IRWST, PRHR, and CMT line resistances; PZR surge line diameter; ADS4, upper core plate, and upper support plate flow areas; and upper plenum structures. The majority of the APEX-AP1000 scaling analysis was based on results from the original AP600 scaling analysis because the AP1000 is geometrically similar to the AP600, and the thermal-hydraulic phenomena studied fell within the scope of the original AP600 test program.

The purpose of the APEX-AP1000 confirmatory test program was to examine AP1000 passive safety system performance and provide high-quality benchmark data for the NRC's thermal-hydraulic computer codes used in reactor safety analysis. Previous testing in the APEX facility demonstrated that all of the thermal-hydraulic phenomena observed in large-scale AP600 facilities (such as ROSA-AP600 or SPES) were also observed in APEX and, consequently, provide a broad database for code assessment. However, the most faithful representation of the AP600 phenomena was for the very-long-term cooling phase, which occurs at low system pressure. The APEX-AP1000 test program was modified to include full-pressure ADS4 blowdown tests to investigate the transition period that leads to the onset of IRWST injection. The scaling analysis provided the basis for the plant modifications listed in Table 2.1.

Table 2.1. Modifications to APEX Components To Simulate AP1000 Conditions

Component	Modification to APEX
Reactor Power	Increase core power by 67%
PZR	Increase PZR volume Reduce PZR Surge Line Diameter
CMTs	Increase CMT volumes by 25% Reduce line resistance to 64% of original value
IRWST	Increase IRWST liquid level
ADS4	Increase ADS4 flow area by 76% Reduce line resistance to 28% of original value
PRHR HX	Increase PRHR flow capacity by 74% by reducing line resistance No change in surface area/tube number required for testing
Containment Sump Flood-Up Elevation	Change flood-up elevation in primary sump tank

The following paragraphs briefly summarize the results of the scaling study.

- (1) The original AP600 scaling analysis, WCAP-14270 [Ref. 1], which was conducted in support of the existing APEX facility design, was found to be applicable to the APEX-AP1000 design for two reasons. First, the thermal-hydraulic phenomena to be studied fell within the scope of the original AP600 test program, with the exception of upper plenum behavior. Second, the AP1000 design is geometrically similar to the AP600 design. As a result, all tank volumes, flow areas, and line resistance scaling ratios found in WCAP-14270 were used in the present study.
- (2) An NRC PZR surge line study by Bessette and Di Marzo [Ref. 2] guided the modification of the APEX-AP1000 PZR surge line. The reduced line diameter is expected to produce a better simulation of the PZR draining behavior.
- (3) The reactor coolant system (RCS) depressurization scaling analysis represents a more comprehensive approach than that implemented in the original AP600 study. Nonetheless, the derived similarity criteria resulted in scaling ratios that were identical to those in the original study. Thus, it was determined that the characteristic time ratios for the AP1000 reactor would be well-matched in APEX-AP1000. The greatest distortion (a factor of 2) was the result of pressure-scaled fluid properties.
- (4) A scaling analysis was performed to design the APEX-AP1000 facility to simulate the important phenomena that occur during the transition from ADS4 blowdown to the onset of IRWST injection, as shown in Figure 2.1. The key phenomena have been identified and described, and the scaling analysis indicated that full-pressure ADS4 blowdown tests could be performed using the modified APEX-AP1000 test facility. The maximum decay power, at the time of ADS4 valve opening, was calculated for the DEDVI break. The AP1000 core axial void fraction profile and core averaged void fraction were also shown to be preserved in the APEX-AP1000 facility.
- (5) A detailed pool entrainment scaling analysis was performed to design the upper plenum components in the APEX-AP1000 facility. The analysis indicated that well-scaled entrainment behavior is expected in the APEX facility to a depth of about 18.9 cm (0.55 in terms of dimensionless height) below the hot leg, as shown in Figure 2.2. Below this depth, the APEX facility is in the momentum-controlled region, whereas the AP1000 reactor would be in the deposition-controlled region at the equivalent scaled depth, as shown in Figure 2.2. It was also determined that the entrainment rates in the near-surface region are a factor of 150 times greater than those generated in the momentum-controlled region, which are a factor of 4 to 6 times greater than those generated in the deposition-controlled region. Thus the APEX facility will conservatively simulate the entrainment behavior when the level is below the midpoint of the upper plenum.

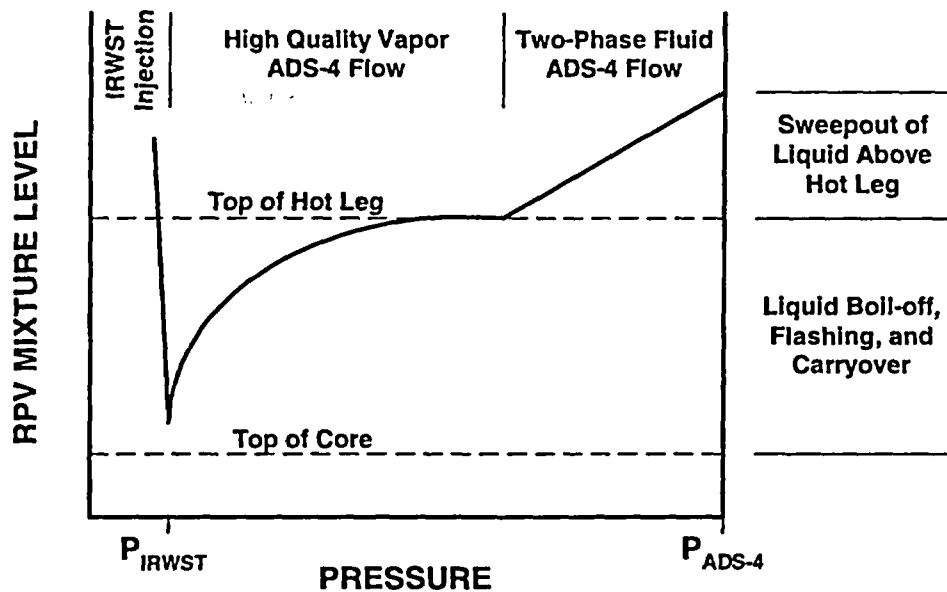


Figure 2.1. Important Phenomena During Transition from ADS4 Blowdown to IRWST Injection

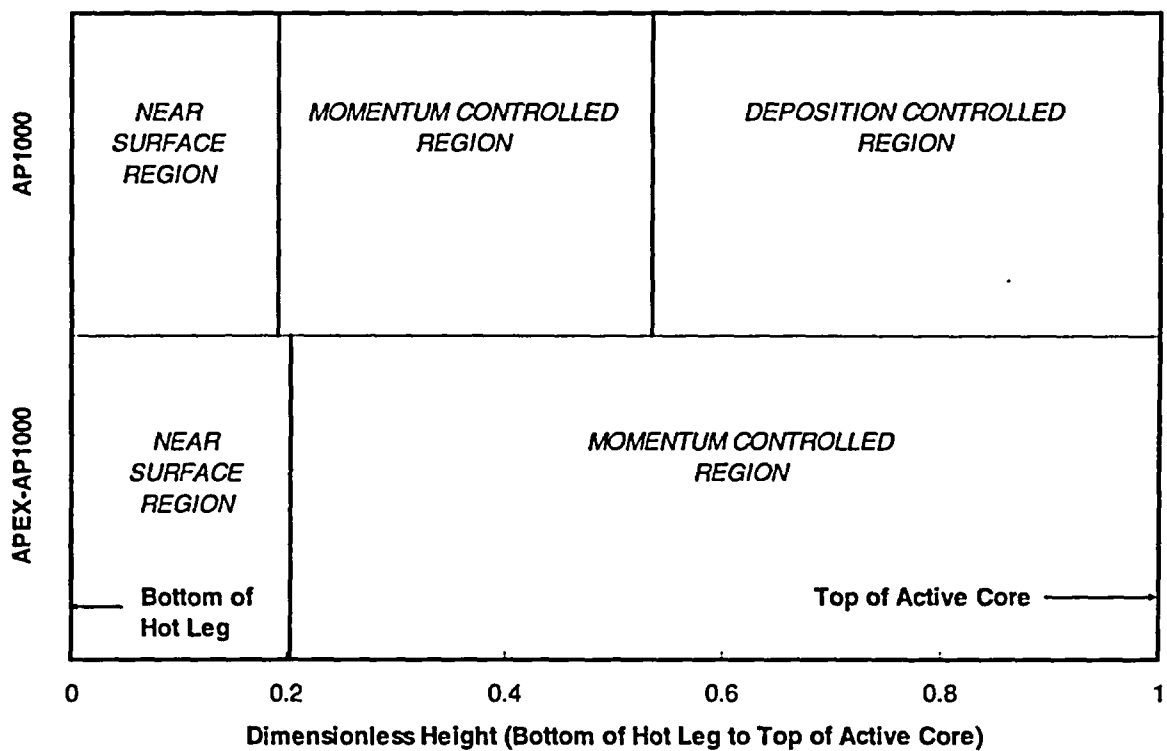


Figure 2.2. Upper Plenum Pool Entrainment Regions in AP1000 and APEX-AP1000

3. FACILITY DESCRIPTION

This chapter provides a comprehensive description of the APEX-AP1000 test facility, including the reactor coolant system (RCS); passive safety systems; instrumentation, controls, and power systems; and balance-of-plant components.

The OSU Department of Nuclear Engineering has modified its APEX facility to assess the performance of the AP1000 passive safety system. APEX is a unique, world-class, one-quarter height, one-half time scale, reduced-pressure, thermal-hydraulic, integral system test facility. In the past, the data obtained using the APEX facility formed an essential aspect of the AP600 design certification program. Modified to accurately represent the AP1000 reactor, the APEX facility is referred to as APEX-AP1000. Appendix B to this report presents information about the APEX-AP1000 facility, such as piping and component dimensions, setpoints, and control logic.

The APEX test facility, depicted in Figure 1.1, has been specifically designed and constructed to provide high-quality data for use in computer code benchmark calculations. Table 2.1 summarizes the significant modifications required to adapt the facility for AP1000 testing, which included new reactor heater rods to increase the maximum facility power from 600 kW to 1000 kW. In addition, the PZR and CMTs were increased in size, passive core cooling system injection line resistance was reduced, and the ADS4 valves and associated piping were increased in size to provide larger RCS depressurization capacity. In addition, a formal scaling analysis (Appendix A) was performed to ensure that the facility accurately represents the AP1000 reactor. The resulting APEX-AP1000 test facility includes the following systems:

- **Reactor Coolant System:** This includes an electrically heated 48-rod bundle core, a reactor vessel with internals, two hot legs (HLs), four cold legs (CLs), two 133 U-tube steam generators (SGs), one PZR, and four reactor coolant pumps (RCPs).
- **Passive Safety Systems:** This includes two CMTs, two accumulators (ACCs), a four-stage ADS, one PRHR HX, one IRWST, and portions of the lower containment compartments.
- **Balance of Plant:** This includes a feedwater system, non-safety grade chemical volume control system (CVS), and an active residual heat removal system. The geometry of the interconnecting pipe routings was also duplicated.

All of the RCS components are constructed of stainless steel and capable of consistent operation at 400 psia (2.76 MPa) while at saturation temperatures. All primary system components are insulated to minimize heat loss.

3.1 Reactor Coolant System (RCS)

The APEX facility RCS is a complete model of the AP1000 nuclear steam supply system (NSSS). As such, the RCS includes the reactor pressure vessel (RPV), one PZR, two SGs, four RCPs, and associated primary loop piping. See Figures 3.1 and 3.2 for elevation and plan views of the RCS, respectively.

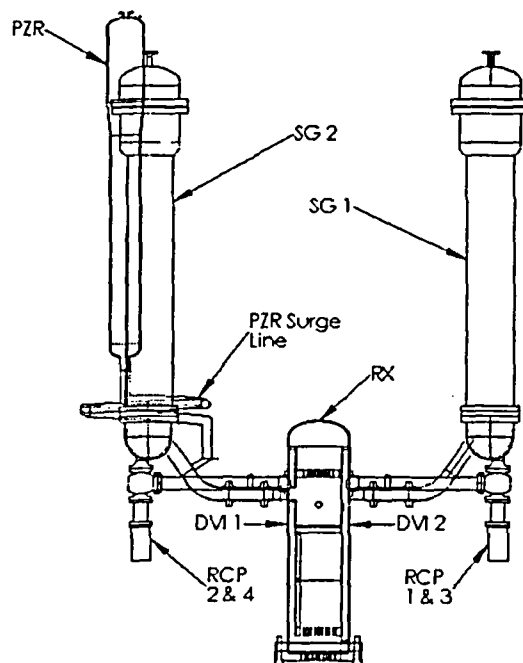


Figure 3.1. Elevation View of Reactor Coolant System

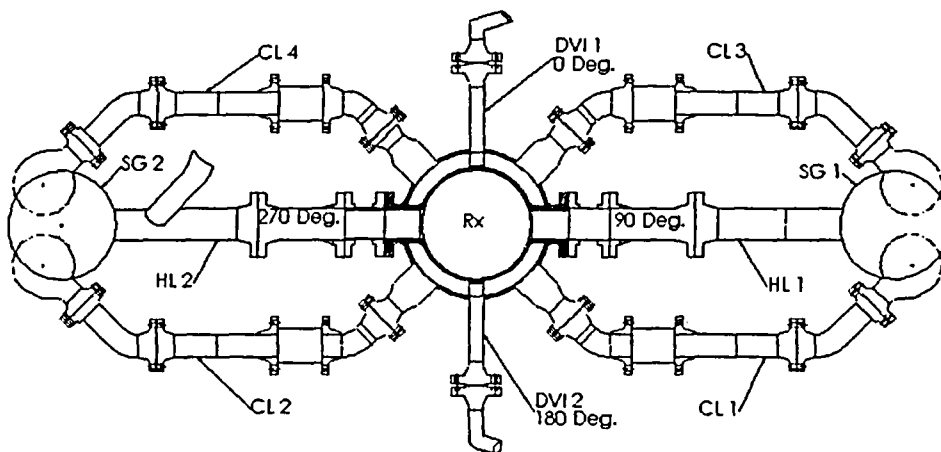


Figure 3.2. Plan View of Reactor Coolant System

3.2 Reactor Pressure Vessel (RPV)

The RPV models the upper and lower internals of the AP1000 reactor vessel, core barrel, downcomer, and core. The maximum core power is approximately 1000 kW, which can be distributed in two radial power zones and can be programmed to simulate time-dependent decay power. The RPV includes connections for the two HLs, four CLs, and two direct vessel injection (DVI) lines.

During normal operation, cold water enters through the four CLs into an annular downcomer region that is bounded by the inside surface of the reactor vessel shell and the outside surface of the core barrel. The cylindrical reactor vessel shell is fabricated from Stainless Steel (SS) 304 plate. The core barrel extends from the upper head flange down to the lower core plate and is made of SS 304.

The cold water in the downcomer flows into the lower plenum, a cylindrical fluid volume region bounded vertically by the lower core plate and the lower head plate. The lower head plate is bolted to the carbon-steel reactor vessel flange, which is welded to the cylindrical reactor vessel shell. The fluid changes direction in the lower plenum and travels upward through holes in the lower core plate into the core. The upper vessel head is a 2:1 elliptical head.

The heated zone of the core consists of 48 heater rods and 5 fluid thermocouple (T/C) rods. Six of the heater rods have a T/C located at the disc end (top) of the heater. In addition to the heater rod T/Cs and individual fluid T/Cs in the RPV, there are five T/C rods that measure the axial fluid temperature distribution in the core. All of the heater rods penetrate the lower head plate, lower plenum, and lower core plate to create a heated zone between the lower core plate and the upper core plate (see Figure 3.3). Two spacer grids are provided for support of the heaters, one at the mid-plane of the heaters and the other near the core exit. The heater bundle is surrounded by a reflector/baffle that directs the fluid through the core (see Figure 3.4). The reflector is filled with PUROCast™ (ceramic) to minimize the heat capacity of the core region.

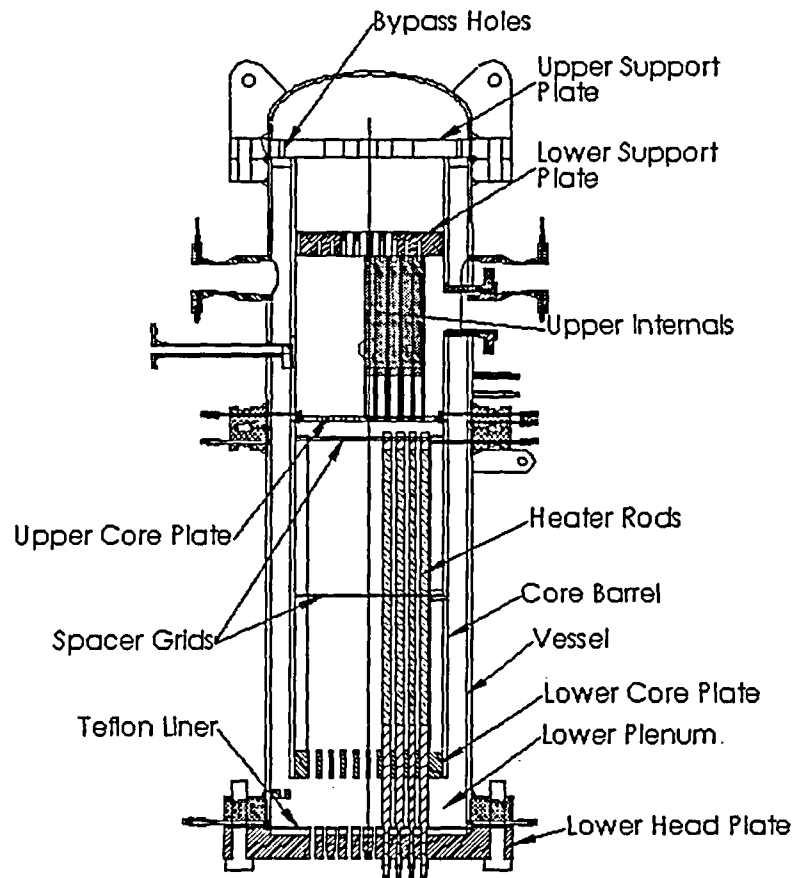


Figure 3.3. Reactor Cross-Section View

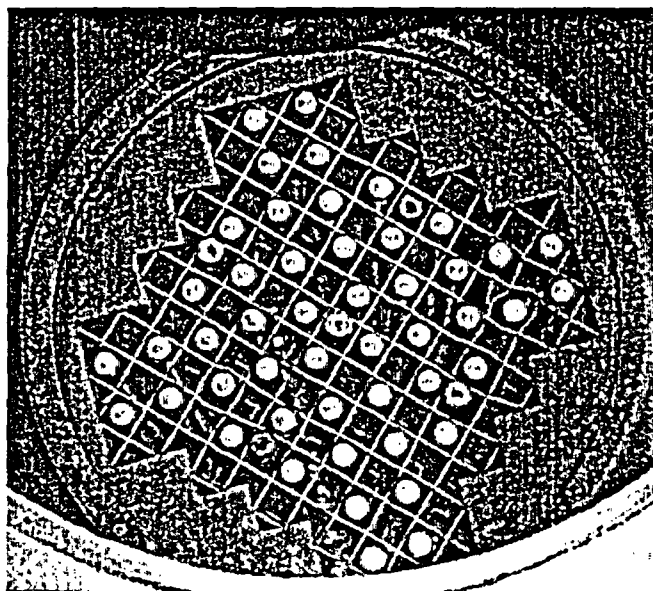


Figure 3.4. View of Reactor Core from Above

The heated water leaves the top of the core and flows upward through the upper core plate into the upper plenum. The upper plenum is bounded by the upper core plate and lower support plate (see Figure 3.3). The upper core plate supports the upper plenum internals that simulate the control rod guide tubes and other upper plenum structure. The heated water leaves the upper plenum via the two HL nozzles.

The volume above the upper support plate is the upper head region. It is connected to the upper plenum via 10 holes and a single hole in the upper support plate. The hole in the center of the upper support plate allows a capacitance level probe to penetrate to just above the upper core plate. The Drexelbrook Universal Lite™ capacitance probe provides a mixture level from the top of the upper core plate to the upper support plate. It is also connected to the downcomer via 10 bypass holes located at the top of the downcomer. The Universal Lite™ instrument is a capacitance-to-current transducer. A change in level produces a change in capacitance causing a corresponding change in current (4-20 mA). It is called a two-wire transmitter because the same two wires that are used to power the unit also indicate the change in level.

Table 3.1 lists the T/Cs located in the RPV, while Table 3.2 lists the pressure instrumentation in the RPV.

Table 3.1. Thermocouples in the Reactor Pressure Vessel

Tag Name	Description	Tag Name	Description
TF-101	CL-3/Reactor Flange @ Top	TF-163	Lower Rx Vessel Layer A-A @ 135 degrees
TF-102	CL-4/Reactor Flange @ Top	TF-164	Upper Rx Vessel Layer H-H @ 0 degrees
TF-103	CL-3/Reactor Flange @ Bottom	TF-165	Upper Rx Vessel Layer H-H @ 6.2 degrees
TF-104	CL-4/Reactor Flange @ Bottom	TF-166	Upper Rx Vessel Layer I-I @ 0 degrees
TF-105	CL-1/Reactor Flange @ Top	TF-167	Heater Rod B2-319 @ 40.13"
TF-106	CL-2/Reactor Flange @ Top	TF-168	Upper Rx Vessel Layer K-K @ 270 degrees
TF-107	CL-1/Reactor Flange @ Bottom	TF-169	Upper Rx Vessel Layer M-M @ 90 degrees
TF-108	CL-2/Reactor Flange @ Bottom	TF-170	Upper Rx Vessel Layer M-M @ 270 degrees
TF-113	DVI-1/Reactor Flange @ Top	TF-171	Top of Reactor Down to within 0.50" of Upper Support Plate
TF-114	DVI-2/Reactor Flange @ Bottom	TF-172	Lower Rx Vessel Layer AA-AA @ 0 degrees
TF-115	DVI-1/Reactor Flange @ Bottom	TF-173	Lower Rx Vessel Layer AA-AA @ 270 degrees
TF-116	DVI-2/Reactor Flange @ Top	TR-001-1	Core Thermocouple Rod D-001 @ 10.50"
TF-118	Lower Rx Vessel Layer Y-Y @ 30 degrees	TR-001-2	Core Thermocouple Rod D-001 @ 19.13"
TF-120	Top of Reactor @ 8.5" & 350 degrees	TR-001-3	Core Thermocouple Rod D-001 @ 25.13"

Table 3.1. Thermocouples in the Reactor Pressure Vessel

Tag Name	Description	Tag Name	Description
TF-126	Lower Rx Vessel Layer A-A @ 225 degrees	TR-001-4	Core Thermocouple Rod D-001 @ 31.13"
TF-127	Lower Rx Vessel Layer A-A @ 315 degrees	TR-001-5	Core Thermocouple Rod D-001 @ 37.13"
TF-128	Lower Rx Vessel Layer C-C @ 0 degrees	TR-001-6	Core Thermocouple Rod D-001 @ 43.13"
TF-129	Lower Rx Vessel Layer C-C @ 32 degrees	TR-303-1	Core Thermocouple Rod D-303 @ 10.51"
TF-130	Lower Rx Vessel Layer G-G @ 0 degrees	TR-303-2	Core Thermocouple Rod D-303 @ 19.13"
TF-131	Lower Rx Vessel Layer G-G @ 11.3 degrees	TR-303-3	Core Thermocouple Rod D-303 @ 25.13"
TF-132	Upper Rx Vessel Layer F-F @ 0 degrees	TR-303-4	Core Thermocouple Rod D-303 @ 31.13"
TF-133	Upper Rx Vessel Layer F-F @ 8 degrees	TR-303-5	Core Thermocouple Rod D-303 @ 37.13"
TF-134	Upper Rx Vessel Layer E-E @ 0 degrees	TR-303-6	Core Thermocouple Rod D-303 @ 43.13"
TF-135	Upper Rx Vessel Layer E-E @ 6.2 degrees	TR-308-1	Core Thermocouple Rod E-308 @ 22.13"
TF-140	HL-2/Reactor Flange @ Top	TR-308-2	Core Thermocouple Rod E-308 @ 34.13"
TF-141	HL-1/Reactor Flange @ Top	TR-308-3	Core Thermocouple Rod E-308 @ 46.13"
TF-142	HL-2/Reactor Flange @ Bottom	TR-308-4	Core Thermocouple Rod D-001 @ 49.13"
TF-143	HL-1/Reactor Flange @ Bottom	TR-308-5	Core Thermocouple Rod D-001 @ 51.13"
TF-147	Upper Rx Vessel Layer I-I @ 180 degrees	TR-308-6	Core Thermocouple Rod D-303 @ 49.13"
TF-148	Upper Rx Vessel Layer I-I @ 188 degrees	TR-313-1	Core Thermocouple Rod D-313 @ 10.50"
TF-149	Upper Rx Vessel Layer H-H @ 180 degrees	TR-313-2	Core Thermocouple Rod D-313 @ 19.13"
TF-150	Upper Rx Vessel Layer H-H @ 186.2 degrees	TR-313-3	Core Thermocouple Rod D-313 @ 25.13"

Table 3.1. Thermocouples in the Reactor Pressure Vessel

Tag Name	Description	Tag Name	Description
TF-151	Upper Rx Vessel Layer E-E @ 186.2 degrees	TR-313-4	Core Thermocouple Rod D-313 @ 31.13"
TF-152	Upper Rx Vessel Layer E-E @ 180 degrees	TR-313-5	Core Thermocouple Rod D-313 @ 37.13"
TF-153	Upper Rx Vessel Layer F-F @ 180 degrees	TR-313-6	Core Thermocouple Rod D-313 @ 43.13"
TF-154	Upper Rx Vessel Layer F-F @ 188 degrees	TR-318-1	Core Thermocouple Rod F-318 @ 28.13"
TF-155	Lower Rx Vessel Layer G-G @ 180 degrees	TR-318-2	Core Thermocouple Rod F-318 @ 40.13"
TF-156	Lower Rx Vessel Layer G-G @ 191.3 degrees	TR-318-3	Core Thermocouple Rod F-318 @ 51.86"
TF-157	Lower Rx Vessel Layer C-C @ 212 degrees	TR-318-4	Core Thermocouple Rod D-303 @ 51.13"
TF-158	Lower Rx Vessel Layer C-C @ 180 degrees	TR-318-5	Core Thermocouple Rod D-313 @ 49.13"
TF-162	Lower Rx Vessel Layer A-A @ 45 degrees	TR-318-6	Core Thermocouple Rod D-313 @ 51.13"

Table 3.2. Pressure Instrumentation in the Reactor Pressure Vessel

Tag Name	Description
DP-111	DP Across Upper Core Plate
DP-114	DP Across Upper Support Plate
DP-121	DVI-1/Cold Leg 1 Differential Pressure
DP-122	DP Between DVI-2 and CL-2
DP-123	DP Between DVI-1 and CL-3
DP-124	DP Between DVI-2 and CL-4
DP-125	HL-1 Entrance Losses
DP-126	HL-2 Entrance Losses
DP-128	HL-2 Entrance Losses
LDP-101	CL to Bypass Holes Uncompensated Water Level (270)
LDP-102	CL to Bypass Holes Water Uncompensated Level (180)
LDP-103	DVI to CL Uncompensated Water Level (270)
LDP-104	DVI to CL Uncompensated Water Level (180)
LDP-105	Upper Core Plate to DVI Uncompensated Water Level (270)
LDP-106	Bottom of Core to Lower Core Plate Uncompensated Water Level (180)
LDP-107	Bottom of Core to Lower Core Plate Uncompensated Water Level (270)
LDP-108	Bottom of Core to Lower Core Plate Uncompensated Water Level (0)
LDP-109	Lower Core Plate to Mid-Core Spacer Grid (0) Uncompensated Water Level
LDP-110	Mid-Core Spacer Grid to Upper-Core Spacer Grid (0) Uncompensated Water Level
LDP-112	Upper Core Plate to DVI Water Level (0) Uncompensated Water Level
LDP-113	DVI to Bottom of Upper Support Plate (0) Uncompensated Water Level
LDP-115	Upper Support Plate to Top of Reactor Uncompensated Water Level
LDP-116	Bottom of Reactor to Bottom of Bypass Holes (270) Uncompensated Water Level
LDP-117	Upper Core Spacer Grid to DVI Water Uncompensated Level (180)
LDP-118	Lower Core Plate to Upper Core Plate (270) Uncompensated Water Level
LDP-119	Lower Core Plate to Upper Core Support Grid (180) Uncompensated Water Level
LDP-127	Reactor Wide Range Uncompensated Level

Table 3.2. Pressure Instrumentation in the Reactor Pressure Vessel

Tag Name	Description
LDP-138	Upper Core Spacer Grid to Bottom of Upper Support Plate (180) Uncompensated Water Level
LDP-139	Top of Lower Core Plate to Upper Core Spacer Grid Uncompensated Level
LDP-140	Bottom of Reactor to Bottom of Flow Holes (180) Uncompensated Water Level
LDP-141	Rx Vessel Upper Core Plate Uncompensated Level
PT-101	CL-1 Pressure @ Reactor Flange
PT-102	CL-2 Pressure @ Reactor Flange
PT-103	CL-3 Pressure @ Reactor Flange
PT-104	CL-4 Pressure @ Reactor Flange
PT-107	Reactor Upper Head Pressure
PT-108	Bottom of Reactor Pressure
PT-109	DVI-1 Pressure @ Reactor Flange
PT-110	DVI-2 Pressure @ Reactor Flange
PT-111	Reactor Annular Pressure @ Flow Bypass Holes
PT-112	Reactor Annular Pressure @ Bottom of Reactor
PT-113	Reactor Pressure Below Mid-Core Spacer Grid

3.3 Pressurizer (PZR)

A fully functional PZR, with internal heaters and a relief valve system capable of controlling the RCS pressure, has been included. The PZR is connected to HL-2 through the PZR surge line. The diameter of the PZR is not constant along its entire length. The larger diameter top was required for the APEX facility because there was not enough vertical space in the laboratory to accommodate the height of the PZR if the diameter remained constant (see Figure 3.5; note the notch in the beam to accommodate the taller PZR). The larger upper portion of the PZR is above the normal PZR water level, so only steam is present in the upper portion. The PZR in the APEX facility does not use a condensing spray for reduction of pressure; instead a vent is used to exhaust steam. A line from the first three stages of the ADS is connected to the top of the PZR for modeling the ADS depressurization of the primary system. The PZR has four heaters, and a T/C is installed in the disk end (top) of each heater. The PZR also has an air-operated valve to allow remote draining of the PZR. See Table 3.3 for a list of PZR-related instruments.

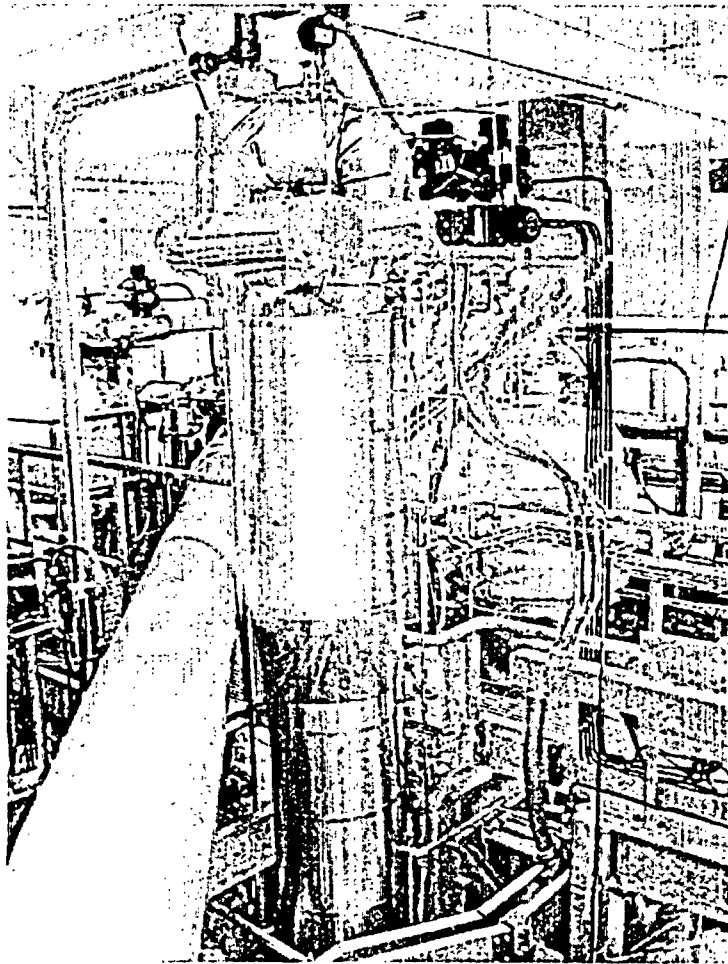


Figure 3.5. Photograph of Pressurizer in the APEX Facility

Table 3.3. Pressurizer Instrument Names and Locations

LDP, HPS, DP, KW, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
DP-611	PZR Surge Line DP	TF-601	PZR Surge Line @ PZR Inlet
HPS-604-1	Lower PZR Surge Line Heat Transfer Coefficient	TF-602	ADS1-3 Common Line @ PZR
HPS-604-2	Lower PZR Surge Line Heater dT above Fluid Temperature	TF-603	PZR Surge Line @ HL-2
HPS-604-3	Lower PZR Surge Line Fluid Temperature	TF-605	PZR Water Space Temperature
HPS-606-1	ADS1-3 Common Inlet Heat Transfer Coefficient	TF-608	PZR Fluid Temperature
HPS-606-2	ADS1-3 Common Inlet Heater dT above Fluid Temperature	TF-614	PZR Steam Vent Line Temperature
HPS-606-3	ADS1-3 Common Inlet Fluid Temperature	TH-601	PZR Heater Rod #1
KW-601	PZR Heater Power	TH-602	PZR Heater Rod #2
LDP-601	PZR WR Uncompensated Water Level	TH-603	PZR Heater Rod #3
LDP-602	PZR Surge Line Uncompensated Water Level	TH-604	PZR Heater Rod #4
LDP-605	PZR Upper Surge Line Pipe Uncompensated Water Level		
LDP-606	PZR Surge Line Pipe Level @ PZR Inlet Uncompensated Water Level		
LDP-607	PZR Middle Surge Line Pipe Uncompensated Water Level		
LDP-608	PZR Lower Surge Line Pipe Uncompensated Water Level		
LDP-609	PZR Surge Line Pipe Uncompensated Water Level @ HL-2		
PT-602	PZR NR Pressure		
PT-603	PZR NR Pressure		
PT-604	PZR Pressure		

3.4 Steam Generators (SGs)

Two SGs, one on each loop, have been included in the APEX facility. Each SG is instrumented and has a tube and shell made to simulate a Westinghouse Delta-75 Steam Generator (see Figure 2-8). The SG lower channel head includes connections for two RCPs and a single HL. SG2 contains a line from the PRHR HX located inside the IRWST. The T/Cs are attached to the outer surface and are embedded into the walls of selected SG tubes. Each SG contains 133 U-tubes. See Figures 3.6, 3.7, and 3.8 for images of the SG.

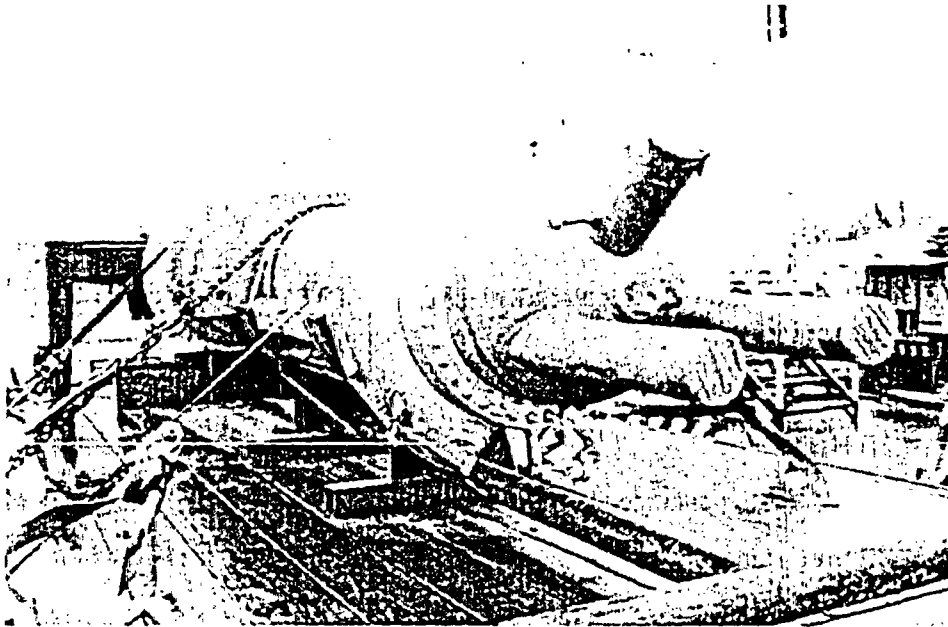


Figure 3.6. Steam Generator Being Delivered to the APEX Facility

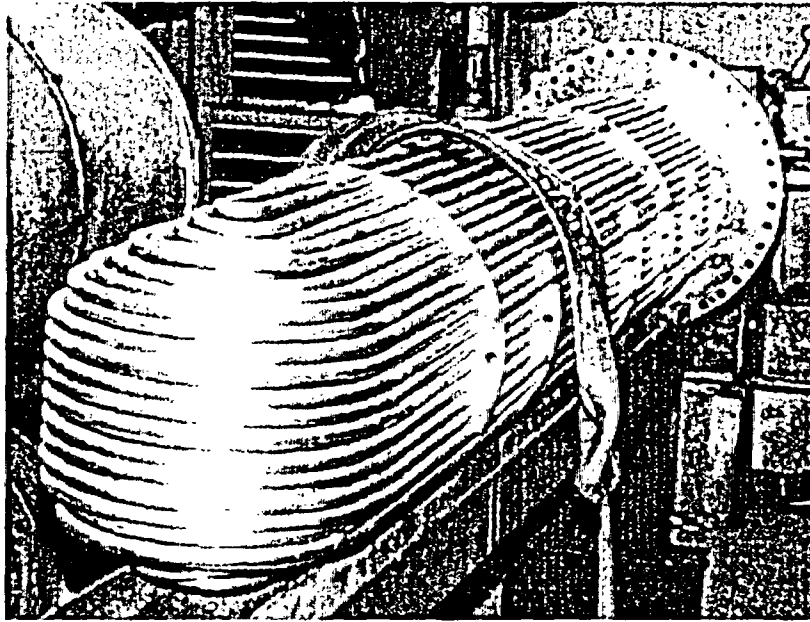


Figure 3.7. Steam Generator U-Tube Bundle

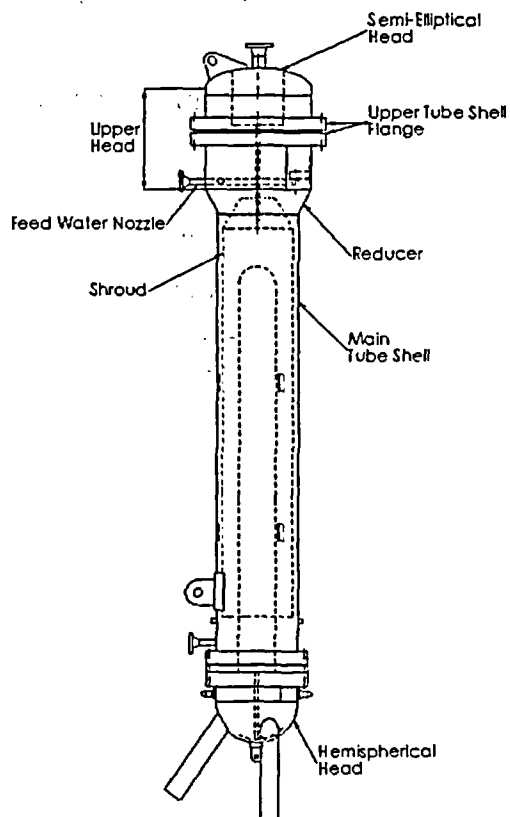


Figure 3.8. Steam Generator Components

A power-operated relief valve (PORV), and associated piping, is installed on both SGs and is connected to the exhaust header. An air-operated ball valve provides remote actuation. A flow orifice is installed in each line to limit steam flow. Each line includes a T/C, a pressure transmitter, and a Vortex flow meter. To provide flow measurement within the desired range, the PORV line was enlarged and a Vortex flow meter was installed. The PORV line discharges into a common steam line, which is then routed into the steam exhaust stack. Table 3.4 lists the instruments associated with the secondary side of the SGs, while Table 3.5 lists the instruments associated with the primary side of the SGs.

Table 3.4. Steam Generator Instrument Names and Locations (Secondary Side)

LDP and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
LDP-301	SG1 WR Uncompensated Water Level	TF-301	SG1 Steam Temperature
LDP-302	SG2 WR Uncompensated Water Level	TF-305	SG1 Downcomer HL Side Temperature
LDP-303	SG1 NR Uncompensated Water Level	TF-306	SG2 Downcomer HL Side Temperature
LDP-304	SG2 NR Uncompensated Water Level	TF-307	SG1 Downcomer CL Side Temperature
PT-301	SG1 Pressure	TF-308	SG2 Downcomer CL Side Temperature
PT-302	SG2 Pressure	TF-310	SG2 Steam Temperature
		TF-311	SG1 Feed Header Temperature
		TF-312	SG2 Feed Header Temperature

Table 3.5. Steam Generator Instrument Names and Locations (Primary Side)

LDP, DP, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
DP-211	SG-1 Short Tube Entrance Losses	TF-207	SG1 Short Tube @ Middle Outlet Side Temperature
DP-212	SG2 Long Tube Exit Losses	TF-208	SG2 Short Tube @ Middle Outlet Side Temperature
DP-213	SG1 Long Tube Exit Losses	TF-209	SG1 Short Tube @ Middle Inlet Side Temperature
DP-214	SG2 Long Tube Entrance Losses	TF-210	SG2 Short Tube @ Middle Inlet Side Temperature
LDP-207	SG1 to HL1 Elbow Plenum Uncompensated Water Level	TF-211	SG1 Long Tube @ Middle Outlet Temperature
LDP-208	SG2 to HL2 Elbow Plenum Uncompensated Water Level	TF-212	SG2 Long Tube @ Middle Outlet Temperature
LDP-209	SG1 HL Plenum Uncompensated Water Level	TF-213	SG1 Long Tube @ Middle Inlet Temperature
LDP-210	SG2 CL4 Plenum Uncompensated Water Level	TF-214	SG2 Long Tube @ Middle Inlet Temperature
LDP-211	SG1 CL3 Plenum Uncompensated Water Level	TF-215	SG1 Short Tube @ Top Temperature
LDP-212	SG2 CL2 Plenum Uncompensated Water Level	TF-216	SG2 Short Tube @ Top Temperature
LDP-213	SG1 CL1 Plenum Uncompensated Water Level	TF-217	SG1 Long Tube @ Top Temperature
LDP-214	SG2 HL Plenum Uncompensated Water Level	TF-218	SG2 Long Tube @ Top Temperature
LDP-215	SG1 Long Tube HL Uncompensated Water Level	TW-201	SG1 Short Tube Bottom Outlet
LDP-216	SG2 Short Tube HL Uncompensated Water Level	TW-202	SG2 Short Tube Bottom Outlet
LDP-217	SG1 Short Tube HL Uncompensated Water Level	TW-203	SG1 Short Tube Bottom Inlet

Table 3.5. Steam Generator Instrument Names and Locations (Primary Side)

LDP, DP, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
LDP-218	SG2 Long Tube HL Uncompensated Water Level	TW-204	SG2 Short Tube Bottom Inlet
LDP-219	SG1 Long Tube CL Uncompensated Water Level	TW-205	SG1 Long Tube Bottom Outlet
LDP-220	SG2 Short Tube CL Uncompensated Water Level	TW-206	SG2 Long Tube Bottom Outlet
LDP-221	SG1 Short Tube CL Uncompensated Water Level	TW-208	SG2 Long Tube Bottom Inlet
LDP-222	SG2 Long Tube CL Uncompensated Water Level	TW-209	SG1 Short Tube Top Outlet
PT-201	SG1 Long Tube Pressure (Top)	TW-210	SG2 Short Tube Top Outlet
PT-204	SG2 Long Tube Pressure (Top)		

3.5 Reactor Coolant Pump (RCP)

Four variable-speed RCPs have been included as part of the RCS. The RCPs simulate the AP1000 canned motor pumps and are attached to the lower channel head of each SG. Each pump outlet is connected to a single CL. The pumps are fabricated from SS 304 and can be programmed to simulate RCP coastdown. Figure 3.9 shows two RCPs mounted on SG2, while Figure 3.10 shows the pump head curve of the RCPs. See Table 3.6 for a list of the instrumentation related to the RCPs.

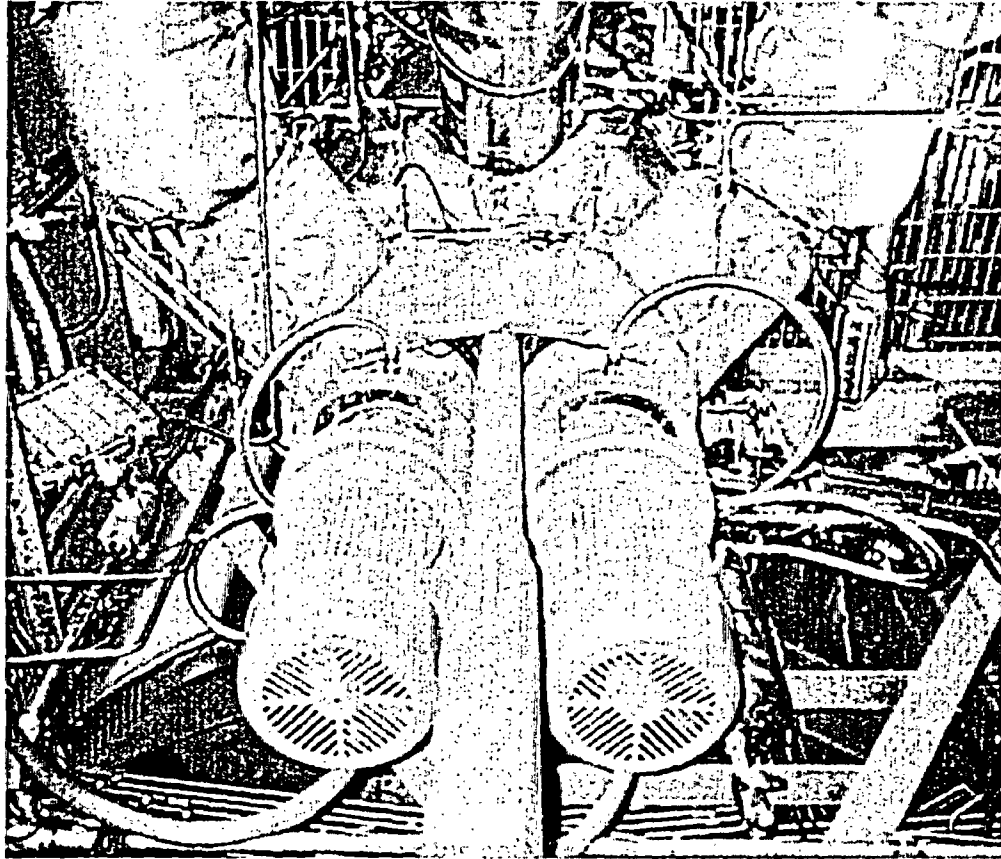
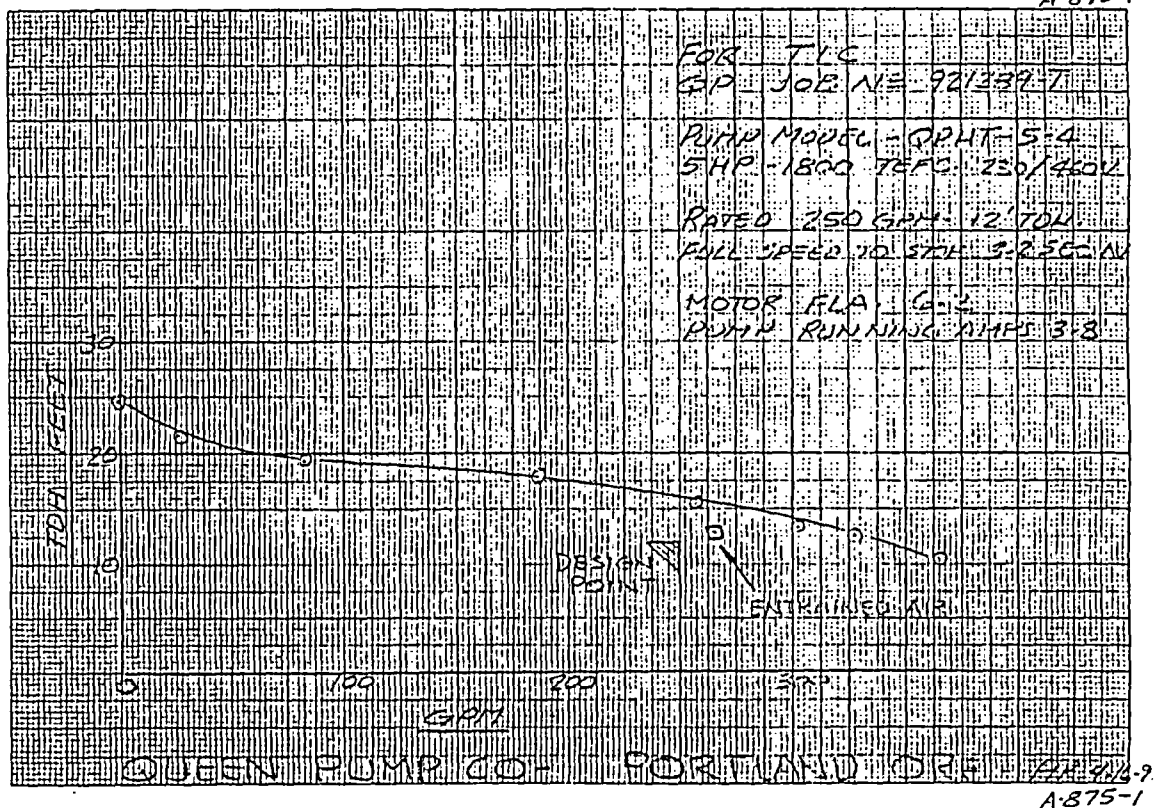


Figure 3.9. Image of Two Reactor Coolant Pumps from Bottom

A-875-1



A-875-1

Figure 3.10. Reactor Coolant Pump Head Curve

Table 3.6. Reactor Coolant Pump Instrument Names and Locations

Differential Pressure Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
DP-202	RCP-2 DP	TF-201	CL-1 @ RCP-1 Inlet Temperature
DP-203	RCP-1 DP	TF-202	CL-2 @ RCP-2 Inlet Temperature
DP-205	RCP-3 DP	TF-203	CL-3 @ RCP-3 Inlet Temperature
DP-206	RCP-4 DP	TF-204	CL-4 @ RCP-4 Inlet Temperature

3.6 Primary Loop Piping

The primary loop piping models two primary loops, each consisting of a single HL and two CLs. Figure 3.11 shows the PZR side of the RCS:

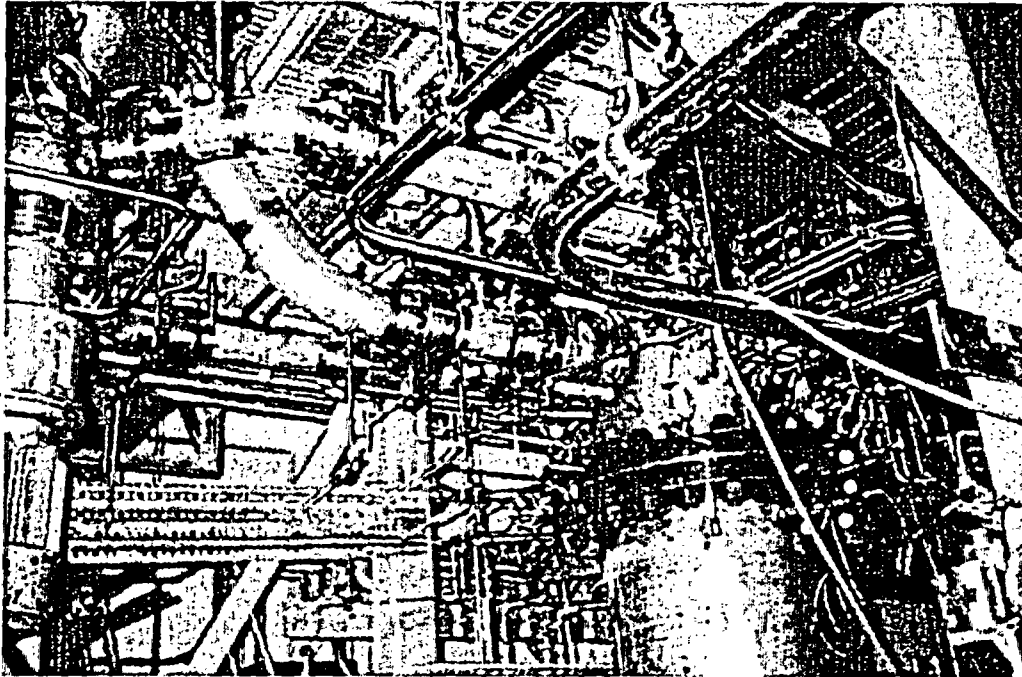


Figure 3.11. Primary Loop Piping in the Reactor Coolant System

Break spool pieces are installed on the HLs, CLs, DVI lines, and CMT pressure balance line (PBL) to simulate several pipe break scenarios. The APEX facility is able to simulate the following primary loop breaks:

- Top break on CL-3
- Bottom break on CL-3
- Bottom break on CL-4
- Bottom break on HL-2
- Single-ended DVI break
- Single-ended CMT balance line break
- Double-ended DVI break
- Double-ended CMT balance line break

Each of the primary loop breaks is initiated by pneumatic valves connected to the aforementioned locations. The break flow passes through an orifice plate, which is intended to set the size of the break, and may be changed out at anytime to simulate different break flow areas. The discharge from the break vents proceeds to the break and ADS measurement system (BAMS) to separate and measure the liquid and vapor components of the break flow rate.

3.6.1 Hot Legs (HLs)

In the primary side, each loop consists of a single pipe, which in turn, feeds the inverted U-tube SG mounted vertically on the bottom of each SG channel head. The HLs have connections for the fourth-stage ADS (ADS4). Refer to Table 3.7 for a list of instruments pertaining to the HL.

Table 3.7. Hot Leg Instrument Names and Locations

Tag Name	Description
DP-209	HL2 DP
DP-210	HL2 DP
DP-216	HL Break DP
DP-217	HL1 to CL1 DP @ SG1
DP-218	HL2 to CL2 DP @ SG2
DP-219	HL1 to CL3 DP @ SG1
DP-220	HL2 to CL4 DP @ SG2
DP-221	HL1 to CL1 DP @ RX
DP-222	HL2 to CL2 DP @ RX
DP-223	HL1 to CL3 DP @ RX
DP-224	HL2 to CL4 DP @ RX
HPS-205-1	HL1 Heat Transfer Coefficient
HPS-205-2	HL1 Heater dT above fluid temperature
HPS-205-3	HL1 Fluid temperature
HPS-206-1	HL2 Heat Transfer Coefficient
HPS-206-2	HL2 Heater dT above fluid temperature
HPS-206-3	HL2 Fluid Temperature
LDP-205	HL1 Uncompensated Water Level
LDP-206	HL2 Uncompensated Water Level
LDP-207	SG1 to HL1 Elbow Plenum Uncompensated Water Level
LDP-208	SG2 to HL2 Elbow Plenum Uncompensated Water Level
LDP-209	SG1 HL Plenum Uncompensated Water Level
LDP-214	SG2 HL Plenum Uncompensated Water Level
PT-202	HL2 Pressure @ SG2 Flange
PT-205	HL1 Pressure @ SG1 Flange
PT-206	HL Break Pressure @ Break Valve

3.6.2 Cold Legs (CLs)

In the primary side, each loop consists of two pipes, which in turn, feed the reactor vessel. The CL interconnects the reactor vessel and one of the two RCPs attached at the bottom of the SG. CL1 and CL3 have connections for the CMT-PBLs connected to the tops of CMT2 and CMT1, respectively. See Table 3.8 for a list of CL-related instrumentation.

Table 3.8. Cold Leg Instrument Names and Locations

DP, LDP, HPS, FMM, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
DP-201	CL1 DP	TF-201	CL1 @ RCP1 Inlet Temperature
DP-204	CL2 DP	TF-202	CL2 @ RCP2 Inlet Temperature
DP-207	CL3 DP	TF-203	CL3 @ RCP3 Inlet Temperature
DP-208	CL4 DP	TF-204	CL4 @ RCP4 Inlet Temperature
DP-217	HL1 to CL1 DP @ SG1	TF-221	CL3 T/C Rod @ 3.25 in. (8.26 cm)
DP-218	HL2 to CL2 DP @ SG2	TF-222	CL4 T/C Rod @ 3.25 in. (8.26 cm)
DP-219	HL1 to CL3 DP @ SG1	TF-223	CL3 T/C Rod @ 2.50 in. (6.35 cm)
DP-220	HL2 to CL4 DP @ SG2	TF-224	CL4 T/C Rod @ 2.50 in. (6.35 cm)
DP-221	HL1 to CL1 DP @ RX	TF-225	CL3 T/C Rod @ 1.75 in. (4.45 cm)
DP-222	HL2 to CL2 DP @ RX	TF-226	CL4 T/C Rod @ 1.75 in. (4.45 cm)
DP-223	HL1 to CL3 DP @ RX	TF-227	CL3 T/C Rod @ 1.25 in. (3.18 cm)
DP-224	HL2 to CL4 DP @ RX	TF-228	CL4 T/C Rod @ 1.25 in. (3.18 cm)
FMM-201	CL1 Loop Flow	TF-229	CL3 T/C Rod @ 0.75 in. (1.91 cm)
FMM-202	CL2 Loop Flow	TF-230	CL4 T/C Rod @ 0.75 in. (1.91 cm)
FMM-203	CL3 Loop Flow	TF-231	CL3 T/C Rod @ 0.25 in. (0.64 cm)
FMM-204	CL4 Loop Flow	TF-232	CL4 T/C Rod @ 0.25 in. (0.64 cm)
HPS-201-1	CL1 Heat Transfer Coefficient	TF-251-1	CL1 Loop Seal Upper Temperature
HPS-201-2	CL1 Heater dT Above Fluid Temperature	TF-251-2	CL1 Loop Seal Middle Temperature
HPS-201-3	CL1 Fluid Temperature	TF-251-3	CL1 Loop Seal Lower Temperature
HPS-202-1	CL2 Heat Transfer Coefficient	TF-252-1	CL2 Loop Seal Upper Temperature
HPS-202-2	CL2 Heater dT Above Fluid Temperature	TF-252-2	CL2 Loop Seal Middle Temperature
HPS-202-3	CL2 Fluid Temperature	TF-252-3	CL2 Loop Seal Lower Temperature
HPS-203-1	CL3 Heat Transfer Coefficient	TF-253-1	CL3 Loop Seal Upper Temperature
HPS-203-2	CL3 Heater dT Above Fluid Temperature	TF-253-2	CL3 Loop Seal Middle Temperature

Table 3.8. Cold Leg Instrument Names and Locations

DP, LDP, HPS, FMM, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
HPS-203-3	CL3 Fluid Temperature	TF-253-3	CL3 Loop Seal Lower Temperature
HPS-204-1	CL4 Heat Transfer Coefficient	TF-254-1	CL4 Loop Seal Upper Temperature
HPS-204-2	CL4 Heater dT Above Fluid Temperature	TF-254-2	CL4 Loop Seal Middle Temperature
HPS-204-3	CL4 Fluid Temperature	TF-254-3	CL4 Loop Seal Lower Temperature
LDP-201	CL1 Water Uncompensated Level	TF-255	CL1 Safety Injection Nozzle Temperature
LDP-202	CL2 Water Uncompensated Level	TF-256	CL2 Safety Injection Nozzle Temperature
LDP-203	CL3 Uncompensated Water Level	TF-257	CL3 Safety Injection Nozzle Temperature
LDP-204	CL4 Uncompensated Water Level	TF-258	CL4 Safety Injection Nozzle Temperature
LDP-210	SG2 CL4 Plenum Uncompensated Water Level		
LDP-211	SG1 CL3 Plenum Uncompensated Water Level		
LDP-212	SG2 CL2 Plenum Uncompensated Water Level		
LDP-213	SG1 CL1 Plenum Uncompensated Water Level		
LDP-219	SG1 Long Tube CL Uncompensated Water Level		
LDP-220	SG2 Short Tube CL Uncompensated Water Level		
LDP-221	SG1 Short Tube CL Uncompensated Water Level		
LDP-222	SG2 Long Tube CL Uncompensated Water Level		
PT-203	CL Break Pressure @ Break Valve		

3.6.3 Pressurizer Surge Line

The PZR surge line connects the bottom of the PZR to the top of HL2, near the SG end of the HL. The surge line enables continuous pressure adjustments between the RCS and the PZR. The PZR surge line spirals up from the HL to the PZR so that its geometry properly matches that of the AP1000 reactor (see Figure 3.12).

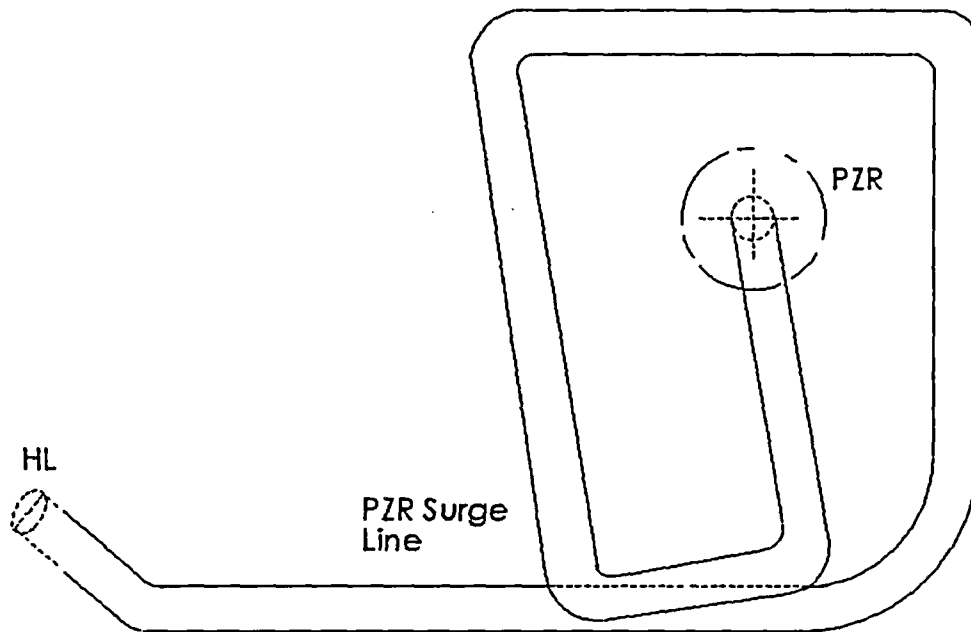


Figure 3.12. Pressurizer Surge Line Geometry (Top View)

3.7 Passive Safety Systems

3.7.1 Automatic Depressurization System (ADS) 1–4

The ADS1–3 valves in the APEX facility model two trains in the AP1000 reactor. Each valve is located after a flow orifice that models the scaled choked flow area of the AP1000. The ADS1–3 valve train discharges to the ADS1–3 separator, where the two-phase flow is separated and measured. All portions of the flow are recombined before dumping into the ADS1–3 sparger.

The ADS1–3 valves exit at the top of the PZR through a single section of pipe. The pipe then splits in three, and is reduced prior to the ADS1, 2, and 3 flow nozzles. After the valves, the piping is recombined into a common pipe, which is connected to the ADS1–3 separator. The fluid is separated into its steam and liquid components inside the ADS1–3 moisture separator. The steam flow and liquid flow are measured and then recombined and dumped through a sparger into the IRWST. The sparger consists of four separate legs (see Figure 3.13). The ADS1 valve is opened on “S” signal, “S” signal plus a time delay, or CMT low level, depending on the selected logic. The ADS2 and ADS3 valves open based on a time delay after actuation of ADS1.

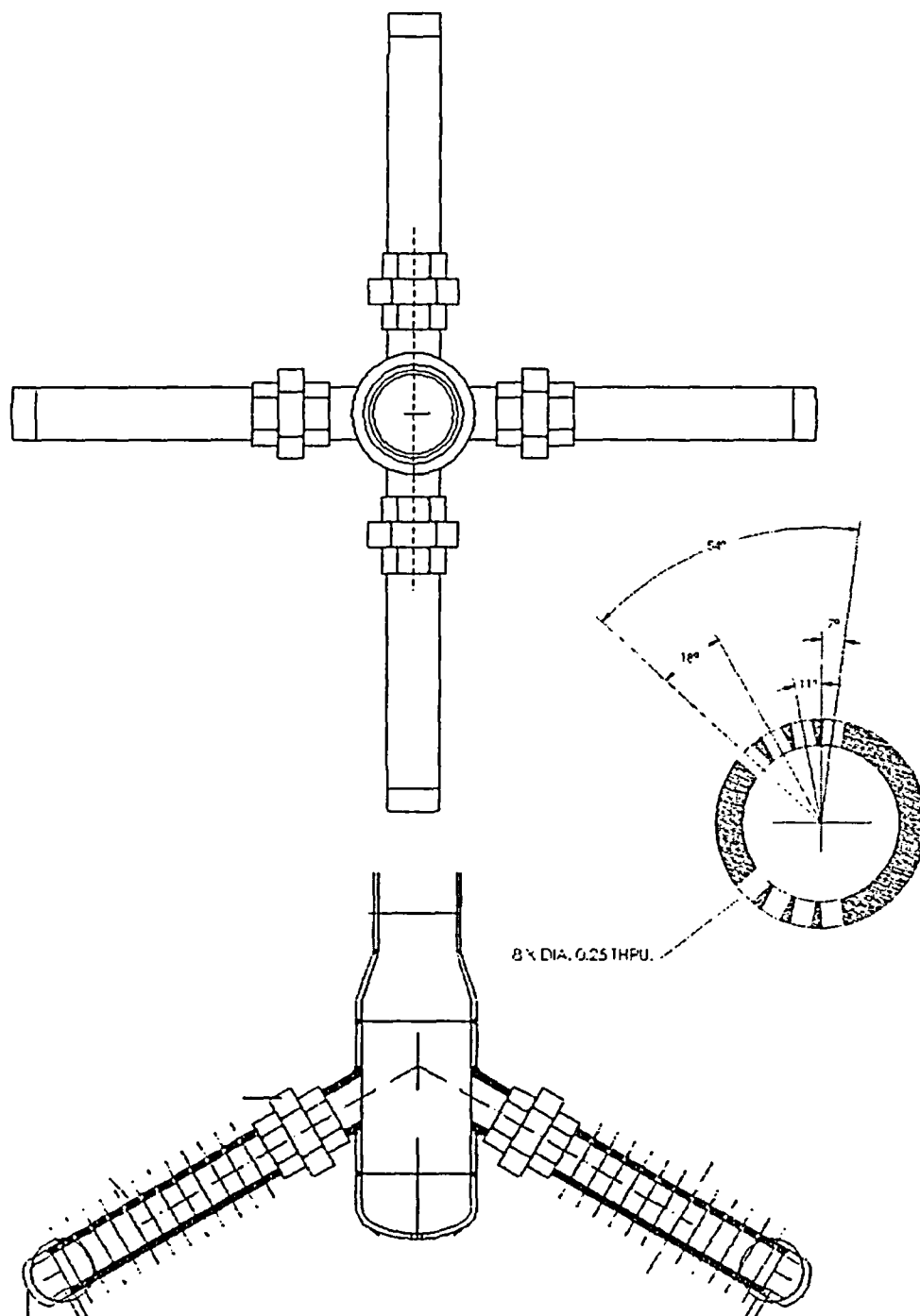


Figure 3.13. Illustration of Automatic Depressurization System 1-3 Sparger

Figure 3.14 shows the ADS1-3 sparger installed within the IRWST. Refer to Table 3.9 for a list of instrumentation pertaining to the ADS1-4 system.

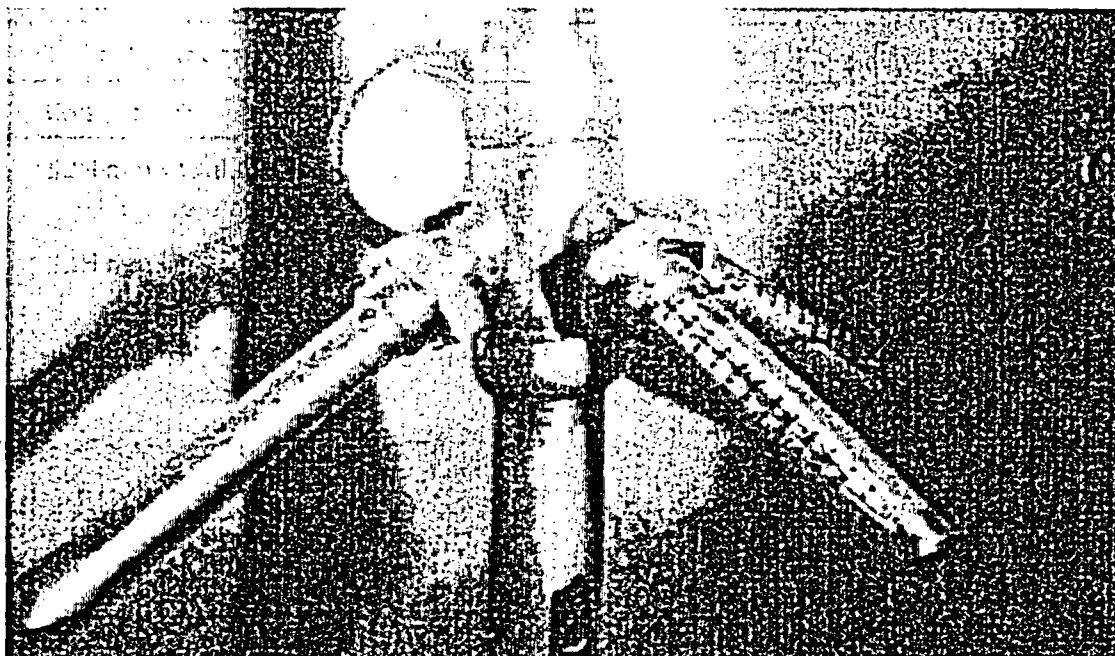


Figure 3.14. Photograph of Installed Sparger

Table 3.9. Automatic Depressurization System 1–4 Instrument Names and Locations

LDP, FDP, HPS, FMM, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
FDP-604	ADS2 Flow Differential Pressure	TF-602	ADS1–3 Common Line @ PZR Temperature
FDP-605	ADS1 Flow Differential Pressure	TF-609	ADS4–1 Discharge Temperature
FDP-606	ADS3 Flow Differential Pressure	TF-610	ADS4–2 Discharge Temperature
FMM-601	ADS1–3 Loop Seal Flow	TF-615	ADS1–3 Common Line from PZR Temperature
FMM-602	ADS4–2 Loop Seal Flow	TF-616	ADS1–3 Separator Loop Seal Temperature
FMM-603	ADS4–1 Loop Seal Flow	TF-617	ADS1–3 Separator Steam Outlet Temperature
LDP-603	ADS4A Vertical Exit Line Uncompensated Water Level	TF-618	ADS4–2 Loop Seal Temperature
LDP-604	ADS4B Vertical Exit Line Uncompensated Water Level	TF-619	ADS4–1 Loop Seal Temperature

Table 3.9. Automatic Depressurization System 1–4 Instrument Names and Locations

LDP, FDP, HPS, FMM, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
LDP-610	ADS1–3 Separator Uncompensated Water Level	TF-620	ADS4–2 Inlet From HL2 Temperature
LDP-611	ADS4–1 Separator Uncompensated Water Level	TF-621	ADS4–1 Inlet From HL1 Temperature
LDP-612	ADS4–2 Separator Uncompensated Water Level	TF-622	ADS4–2 Separator Steam Outlet Temperature
PT-605	ADS1–3 Separator Pressure	TF-623	ADS4–1 Separator Steam Outlet Temperature
PT-606	IRWST Sparger Line Pressure	TW-601	ADS1–3 Separator Wall Temperature
PT-610	ADS4–2 Separator Pressure	TW-602	ADS4–2 Separator Wall Temperature
PT-611	ADS4–1 Separator Pressure	TW-603	ADS4–1 Separator Wall Temperature
HPS-606-1	ADS1–3 Common Inlet Heat Transfer Coefficient		
HPS-606-2	ADS1–3 Common Inlet Heater dT Above Fluid Temperature		
HPS-606-3	ADS1–3 Common Inlet Fluid Temperature		

Two ADS4 valves are connected to the top of HL1 and HL2, respectively. Both ADS4 lines are similar, with the exception that ADS4–2 (PZR side) provides a tee connection for the PRHR HX system. Both ADS4 lines include valve flow area and line resistance. The flow from ADS4 is directed to a an orifice to match the separator, where the steam and liquid flows are separated and measured individually. The steam flow is routed through one of two lines depending on the expected flow rate and is then vented from the facility. The liquid flow is directed through a loop seal and into the primary sump.

3.7.2 In-Containment Refueling Water Storage Tank (IRWST)

The APEX IRWST is constructed of SS 304 and has four major connections, including the ADS1–3 sparger, DVI1 and 2, the primary sump, and the PRHR connections. Table 3.10 lists the pressure, weight, and flow rate instruments for the IRWST, while Table 3.11 lists the temperature measurement instrumentation. The temperature of the fluid in the IRWST is measured at several heights to determine stratification.

Table 3.10. IRWST LDP, LCT, FMM, DP, and PT Cells and Locations

Tag Name	Description
DP-701	IRWST-1 Injection Differential Pressure
DP-702	IRWST-2 Injection Differential Pressure
FMM-701	IRWST-1 Injection Flow
FMM-702	IRWST-2 Injection Flow
FMM-703	IRWST Overflow
LDP-701	IRWST Uncompensated Water Level
PT-701	IRWST Pressure
LCT-701	IRWST Weight

Table 3.11. IRWST Thermocouples and Location

Tag Name	Description	Tag Name	Description
TF-701	IRWST/PRHR T/C Rod @ Bottom Temperature	TF-713	IRWST Discharge to DVI-01 @ IRWST Temperature
TF-702	IRWST/PRHR T/C Rod @ 7.98 in. (20.27 cm)	TF-714	IRWST Discharge to DVI-02 @ IRWST Temperature
TF-703	IRWST/PRHR T/C Rod @ 15.97 in. (40.56 cm)	TF-715	IRWST Sparger T/C Rod @ 8.97 in. (22.78 cm)
TF-704	IRWST/PRHR T/C Rod @ 25.85 in. (65.67 cm)	TF-716	IRWST Sparger Nozzle Temperature
TF-705	IRWST/PRHR T/C Rod @ 35.73 in. (90.75 cm)	TF-717	IRWST Sparger T/C Rod @ 66.34 in. (168.50 cm)
TF-706	IRWST/PRHR T/C Rod @ 45.61 in. (115.85 cm)	TF-718	IRWST Sparger T/C Rod @ 98.45 in. (250.06 cm)
TF-707	IRWST/PRHR T/C Rod @ 55.49 in. (140.94 cm)	TF-719	IRWST Sparger Outlet Temperature
TF-708	IRWST/PRHR T/C Rod @ 65.36 in. (166.01 cm)	TF-720	IRWST/DVI2 Injection Line Temperature
TF-709	IRWST/PRHR T/C Rod @ 75.24 in. (191.11 cm)	TF-721	IRWST/DVI1 Injection Line Temperature
TF-710	IRWST/PRHR T/C Rod @ 86.36 in. (219.35 cm)	TF-722	IRWST Steam Exhaust Line Temperature
TF-711	IRWST/PRHR T/C Rod @ 97.47 in. (247.57 cm)	TF-723	IRWST/Primary Sump Overflow Temperature
TF-712	IRWST/PRHR T/C Rod @ 108.59 in. (275.82 cm)		

The two IRWST injection lines that connect into each DVI line start at the bottom of the IRWST, which in turn, connects to the SS 304 pipe connected to the DVI line. The IRWST injection lines are similar, with the exception that IRWST-1 provides a connection to the RNS pump suction. The IRWST injection line resistance is fine-tuned by an orifice plate installed in each line. The IRWST isolation valves (RCS-711/712) are opened on decreasing RCS pressure. See Figure 3.15 for an image of the IRWST.

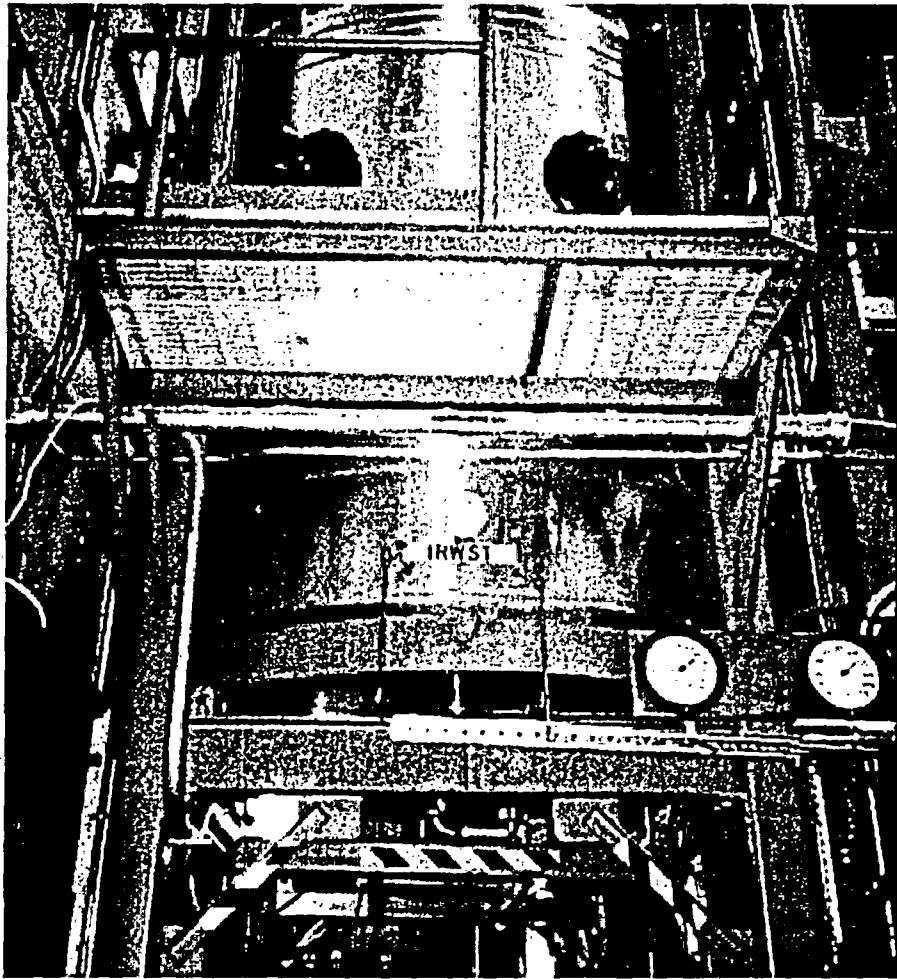


Figure 3.15. Photograph of the IRWST .

3.7.3 Core Makeup Tanks (CMT)

The CMTs are constructed of SS 304, and each CMT is connected to a CL and a DVI line by SS 304 pipe. The CMT injection line isolation valves (RCS-529/530) open on "S" signal for the station blackout subroutine or "S" signal plus a time delay for all other routines. The line resistance of the CMT injection lines is fine-tuned through the use of an orifice. The isolation valves in the CMT balance line (RCS-535/536) have no automatic control and remain open during facility testing. See Figure 3.16 for an image of a CMT. Table 3.12 lists all CMT-related instruments and piping.

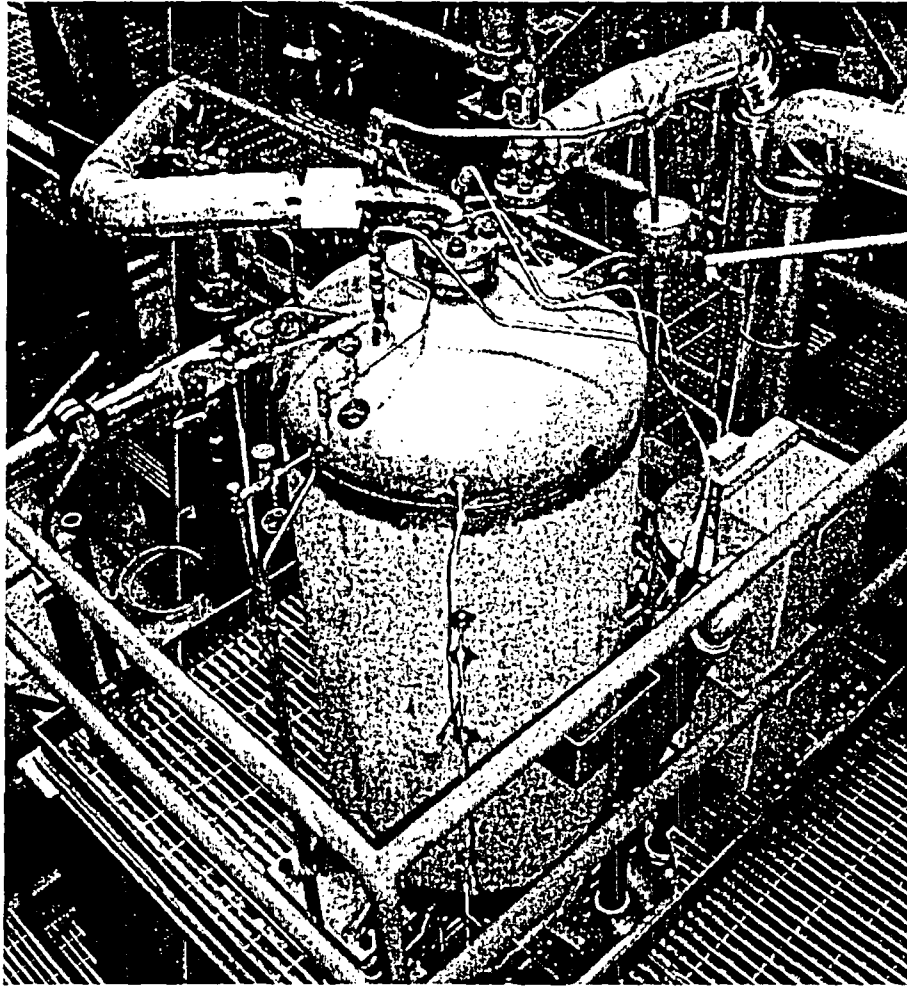


Figure 3.16. Photograph of a Core Makeup Tank

Table 3.12. Core Makeup Tank Instrument Names and Locations

LDP, FMM, HPS, DP, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
DP-501	CMT1 Injection Differential Pressure	TF-501	CMT1 Long T/C Rod @ 0.30 in. (0.76 cm) Temperature
DP-502	CMT2 Injection DP	TF-502	CMT2 Injection Line Temperature
DP-503	CMT1 Balance Line DP	TF-503	CMT1 @ ½ Lower Head Height
DP-504	CMT2 Balance Line DP	TF-504	CMT2 Long T/C Rod @ 0.30 in. (0.76 cm) Temperature
FMM-501	CMT1 Injection Flow	TF-505	CMT1 @ 20% Volume-Height
FMM-502	CMT2 CL Balance Line Flow	TF-506	CMT2 @ ½ Lower Head Height
FMM-503	CMT1 CL Balance Line Flow	TF-507	CMT1 Long T/C Rod @ 20.87 in. (53.01 cm) Temperature

Table 3.12. Core Makeup Tank Instrument Names and Locations

LDP, FMM, HPS, DP, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
FMM-504	CMT2 Injection Flow	TF-508	CMT2 @ 20% Volume-Height
LDP-501	CMT1 NR Uncompensated Water Level (Bottom)	TF-509	CMT1 Long T/C Rod @ 36.89 in. (93.70 cm) Temperature
LDP-502	CMT2 WR Uncompensated Water Level	TF-510	CMT2 Long T/C Rod @ 20.87 in. (53.01 cm) Temperature
LDP-503	CMT1 NR Uncompensated Water Level (Middle)	TF-511	CMT1 @ 50% Volume-Height
LDP-504	CMT2 NR Uncompensated Water Level (Bottom)	TF-512	CMT2 Long T/C Rod @ 36.89 in. (93.70 cm) Temperature
LDP-505	CMT1 NR Uncompensated Water Level (Top)	TF-513	CMT1 Long T/C Rod @ 40.59 in. (103.10 cm) Temperature
LDP-506	CMT2 NR Uncompensated Water Level (Middle)	TF-514	CMT2 @ 50% Volume-Height
LDP-507	CMT1 WR Uncompensated Water Level	TF-515	CMT1 Long T/C Rod @ 43.41 in. (110.26 cm) Temperature
LDP-508	CMT2 NR Uncompensated Water Level (Top)	TF-516	CMT2 Long T/C Rod @ 40.59 in. (103.10 cm) Temperature
LDP-509	CL3 to CMT1 Balance Line Uncompensated Water Level	TF-517	CMT1 @ 75% Volume-Height minus 3.7 in. (9.40 cm)
LDP-510	CL1 to CMT2 Balance Line Uncompensated Water Level	TF-518	CMT2 Long T/C Rod @ 43.41 in. (110.26 cm) Temperature
PT-501	CMT1 Pressure	TF-519	CMT1 Long T/C Rod @ 46.23 in. (117.42 cm) Temperature
PT-502	CMT-02 Pressure	TF-520	CMT2 @ 75% Volume-Height minus 3.7 in. (9.40 cm)
HPS-509-1	CMT-01 CL Balance Line Heat Transfer Coefficient	TF-521	CMT1 @ 75% Volume-Height
HPS-509-2	CMT-01 CL Balance Line Heater dT above fluid temperature	TF-522	CMT2 Long T/C Rod @ 46.23 in. (117.42 cm) Temperature
HPS-509-3	CMT-01 CL Balance Line Fluid temperature	TF-523	CMT1 Long T/C Rod @ 49.05 in. (124.59 cm) Temperature
HPS-512-1	CMT-02 CL Balance Line Heat Transfer Coefficient	TF-524	CMT
HPS-512-2	CMT-02 CL Balance Line Heater dT above fluid temperature	TF-525	CMT1 @ 1/2 Upper-Head Height
HPS-512-3	CMT-02 CL Balance Line Fluid temperature	TF-526	CMT2 SPARGER 2/3 TEMP

Table 3.12. Core Makeup Tank Instrument Names and Locations

LDP, FMM, HPS, DP, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
TF-530	CMT2 Long T/C Rod @ 51.87 in. (131.75 cm) Temperature	TF-527	CMT1 Long T/C Rod @ 51.87 in. (131.75 cm) Temperature
TF-531	CMT1 Balance Line @ CMT Inlet Temperature	TF-528	CMT 23% Head Temp
TF-532	CMT2 Long T/C Rod @ 56.61 in. (143.79 cm) Temperature		
TF-533	CMT1/CL Balance Line @ CL-3 Temperature	TF-542	CMT2 @ 60% Volume-Height
TF-535	CMT1 Injection Line Temperature	TF-543	CMT1 @ 75% Volume-Height
TF-536	CMT2/CL Balance Line @ CL-1 Temperature	TF-544	CMT2 @ 75% Volume-Height
TF-537	CMT1 @ 20% Volume-Height	TF-546	CMT2 Balance Line @ CMT Inlet Temperature
TF-538	CMT2 @ 20% Volume-Height	TF-547	CMT1 Long T/C Rod @ 54.24 in. (137.77 cm) Temperature
TF-539	CMT1 @ 50% Volume-Height	TF-548	CMT2 Long T/C Rod @ 54.24 in. (137.77 cm) Temperature
TF-540	CMT2 @ 50% Volume-Height	TF-549	CMT1 Discharge Line Temperature
TF-541	CMT1 @ 60% Volume-Height	TF-550	CMT2 Discharge Line Temperature
		TF-551	CMT1 Short T/C Rod (225 degrees) 5.5 in. (13.97 cm) from top

3.7.4 Passive Residual Heat Remover (PRHR) Heat Exchanger (HX)

The PRHR HX consists of a C-shaped heat exchanger, located inside the IRWST, and two connections to the primary loop. One inlet connection is between the HL2 ADS4 tee and the upper PRHR HX manifold on the IRWST. The outlet connection is between the lower PRHR HX manifold on the IRWST and the outlet plenum of SG2. The PRHR flow is actuated by an isolation valve (RCS-804) that opens on "S" signal, actuation of the ADS1 valve, or CMT injection valve opening, depending on the selected logic subroutine. The PRHR HX is connected to the upper and lower heat exchanger manifolds on the IRWST. It is made up of 88 individual tubes. See Figure 3.17 for an image of the PRHR HX. Table 3.13 contains a list of all instruments related to the PRHR.

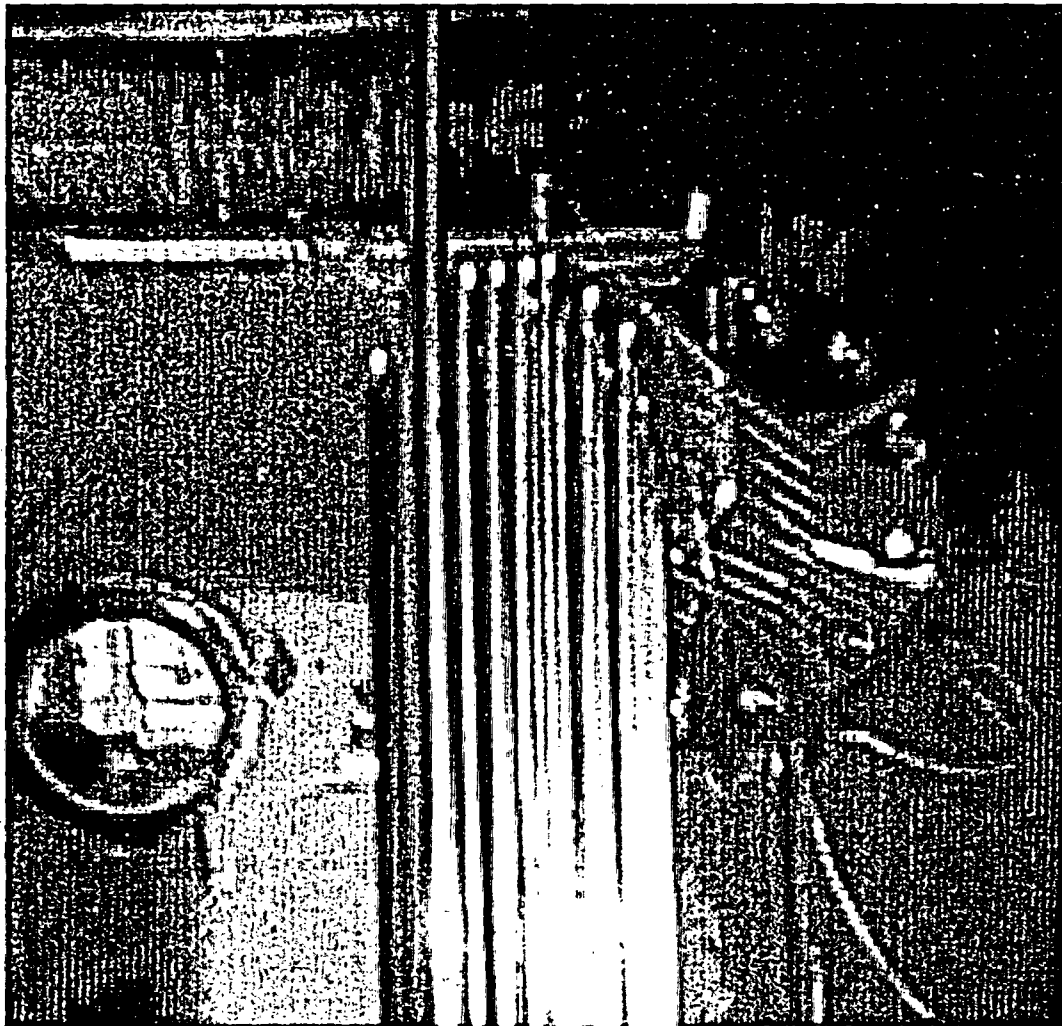


Figure 3.17. View of the PRHR HX Located Inside the IRWST

Table 3.13. PRHR Instrument Names and Locations

LDP, FMM, and HPS		Thermocouples	
Tag Name	Description	Tag Name	Description
FMM-802	PRHR Inlet Flow	TF-803	PRHR HX Inlet Temperature
FMM-804	PRHR Outlet Flow	TF-804	PRHR HX Outlet Temperature
LDP-801	PRHR HX Inlet Head Uncompensated Water Level	TF-805	PRHR HX Long Tube Outlet at Bend Temperature
LDP-802	PRHR HX WR Uncompensated Water Level	TF-806	PRHR HX Short Tube Outlet at Bend Temperature
HPS-801-1	PRHR HX Inlet Heat Transfer Coefficient	TF-808	PRHR HX Short Tube Outlet at Center Temperature
HPS-801-2	PRHR HX Inlet Heater dT Above Fluid Temperature	TF-809	PRHR HX Long Tube at Center Temperature
HPS-801-3	PRHR HX Inlet Fluid Temperature	TF-810	PRHR HX Short Tube Inlet at Bend Temperature
		TF-811	PRHR HX Long Tube Inlet at Bend Temperature
		TF-812	PRHR HX Outlet Head Temperature
		TW-801	PRHR HX Long Tube Outlet
		TW-802	PRHR HX Short Tube Outlet
		TW-803	PRHR HX Long Tube Lower Mid-piece
		TW-804	PRHR HX Short Tube Lower Mid-piece
		TW-805	PRHR HX Short Tube Upper Mid-piece
		TW-806	PRHR HX Long Tube Upper Mid-piece
		TW-807	PRHR HX Short Tube Inlet
		TW-808	PRHR HX Long Tube Inlet

3.7.5 Accumulators (ACC)

The two ACC tanks are constructed of a long piece of pipe with a pipe cap and a thick plate. The plate is cut to fit in one end of the pipe, and a pipe cap type end is used to seal the other end. Table 3.14 lists the instruments associated with the accumulators.

Table 3.14. Accumulator Instrument Names and Locations

LDP, FMM, DP, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
DP-401	ACC1 Injection DP	TF-401	ACC1 Outlet Temperature
DP-402	ACC2 Injection DP	TF-402	ACC2 Outlet Temperature
FMM-401	ACC1 Injection Flow	TF-403	ACC1 N ₂ Top Temperature
FMM-402	ACC2 Injection Flow	TF-404	ACC2 N ₂ Top Temperature
LDP-401	ACC1 Uncompensated Water Level	TF-405	ACC1 Injection Line Temperature
LDP-402	ACC2 Uncompensated Water Level	TF-406	ACC2 Injection Line Temperature
PT-401	ACC1 Pressure		
PT-402	ACC2 Pressure		

Each ACC is connected to a DVI line, and the fluid flow initiates from an ACC to its respective DVI line by means of a check valve (RCS-423/424), which opens when plant pressure becomes less than the pressure in the ACC. See Figure 3.18 for an image of an ACC.

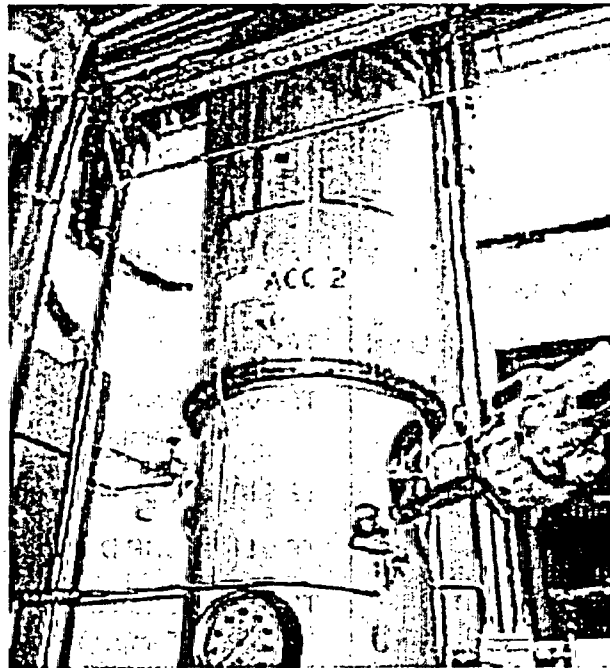


Figure 3.18. Photograph of One of the APEX Accumulators

3.7.6 Containment Sump

The primary containment sump tank is constructed of SS 304 plate, and the cylindrical section is capped with elliptical ends. The primary sump tank is connected to the ADS4 separators, the secondary sump, the break separator, DVI1 and 2, and the steam exhaust header. The sump collects all liquid flow from the break and ADS4 lines. Two containment sump recirculation lines are connected to the bottom of the primary sump and provide a recirculation path to the RPV via the DVI lines. Each line consists of an isolation valve with a parallel line with check valves. The isolation valves (CSS-909/910) open on decreasing IRWST level. A secondary sump is also provided to model containment sump volumes that are not available for long-term circulation. A curb overflow is simulated between the primary and secondary sumps by a weir plate. Table 3.15 lists the instruments associated with the primary and secondary sumps.

Table 3.15. Sump Instrument Names and Locations

LDP, FMM, FVM, LCT, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
FMM-901	Primary Sump-1 Recirculation Injection Flow	TF-901	Primary Sump Inlet from Fill Line Temperature
FMM-902	Primary Sump-2 Recirculation Injection Flow	TF-902	Secondary Sump Bottom Temperature
FMM-905	Break Separator Loop Seal Flow	TF-903	Primary Sump Bottom Temperature
FVM-903	Primary Sump Steam Exhaust Flow	TF-904	Primary Sump/DVI2 Injection Line Temperature
LDP-901	Primary Sump Uncompensated Water Level	TF-905	Primary Sump @ Secondary Sump Crossover Level Temperature
LDP-902	Secondary Sump Uncompensated Water Level	TF-906	Primary Sump Exhaust Temperature
LDP-903	CRT Uncompensated Water Level	TF-907	Primary Sump @ Top Temperature
LDP-905	Break Separator Uncompensated Water Level	TF-909	Primary Sump/DVI1 Injection Line Temperature
PT-901	Primary Sump Pressure	TF-910	CRP Discharge to Primary Sump Temp
LCT-901	Primary Sump Weight	TF-911	CRP Discharge to IRWST Temperature
LCT-902	Secondary Sump Weight	TF-912	Break Separator Loop Seal Temperature
		TF-913	Break Separator Steam Outlet Temperature
		TF-914	CRT Outlet Temperature

3.8 Instrumentation, Control, and Power Systems

This section describes the instrumentation, control, and power systems of the APEX test facility, as well as the data acquisition system, instrument devices, and associated control logic.

3.8.1 Instrumentation Description

The APEX test facility is equipped with approximately 600 instrument channels to capture the transient behavior of the safety systems. The APEX facility includes the following types of instrumentation channels:

- Thermocouples (TF/TR/TH/TW) are used to measure fluid, heater, and wall temperatures. Premium thermocouples with controlled purity thermocouple wire were incorporated.
- Magnetic flow meters (FMMs) are incorporated to measure single-phase liquid flows around the plant.
- Vortex shedding flow meters (FVMs) are used to measure single-phase vapor flow rates.
- Pressure transducers (PT) are used to measure the static pressures in various tanks and pipes within the facility.
- Differential pressure (LDP, DP) transducers are used to measure liquid levels in various tanks and pipes. The differential pressure cells are also used to measure pressure drops.
- Heated phase switches (HPSs) are used to determine the fluid phase at various points inside system piping. Each HPS measures fluid temperature, change in temperature (ΔT) between the fluid and the heater, and a relative heat transfer coefficient.
- Load cell transducers (LCTs) are incorporated to measure the liquid mass inside the IRWST, primary sump, and secondary sump.
- Heater power (KW) to the core is measured with four power meters. The power applied to the PZR heaters is measured by an additional power meter.
- A level transducer (LT) capacitance probe is used to measure collapsed liquid level in the reactor vessel.

Instrumentation channels are subdivided into 10 different groups based on a particular location, using the numbering system described in Table 3.16.

Table 3.16. Instrument Tag Locations

Channel Name	Location
xx-000s	Feed, Main Steam
xx-100s	Reactor Pressure Vessel
xx-200s	Primary Loop
xx-300s	SG
xx-400s	ACC
xx-500s	CMTs
xx-600s	PZR, ADS1-3
xx-700s	IRWST
xx-800s	PRHR, CVS, RNS
xx-900s	Sump, ADS4-1, ADS4-2, and Break System

3.8.2 Data Acquisition

The data acquisition system (DAS) writes the data into a single large database, as shown in Figure 3.19. Using a single database (rather than individual test files) offers the following advantages:

- improved management and maintenance
- enables retrieval to be independent of storage (i.e., the data are stored every second, but the database can be queried at another resolution, say every 5 seconds), which provides a very powerful and flexible retrieval capability
- easier comparisons between multiple tests

The DAS is manufactured by National Instruments (NI) and uses commercial off-the-shelf software. The signal type may be a 4–20 mA current signal, 1–5 VDC or 0–10 VDC voltage signal, or the millivolt signal originating from thermocouples. The instruments are connected to several terminal boards. Each terminal board can accept any combination of J-, K-, and T-type thermocouples and up to 32 channels of inputs with their own cold junction compensation. These terminal boards are also used for other types of signal inputs. Each terminal board is connected to one analog input module, which rests within a chassis that contains 12 modules. The DAS use three chassis to acquire the data. The signals from the chassis are then transferred to a computer that is equipped with a multifunction I/O board. Basically, the multifunction I/O boards switch their inputs between 622 channels at high speed to sample all input channels. The data for APEX are typically sampled at a rate of 1 Hertz per channel.

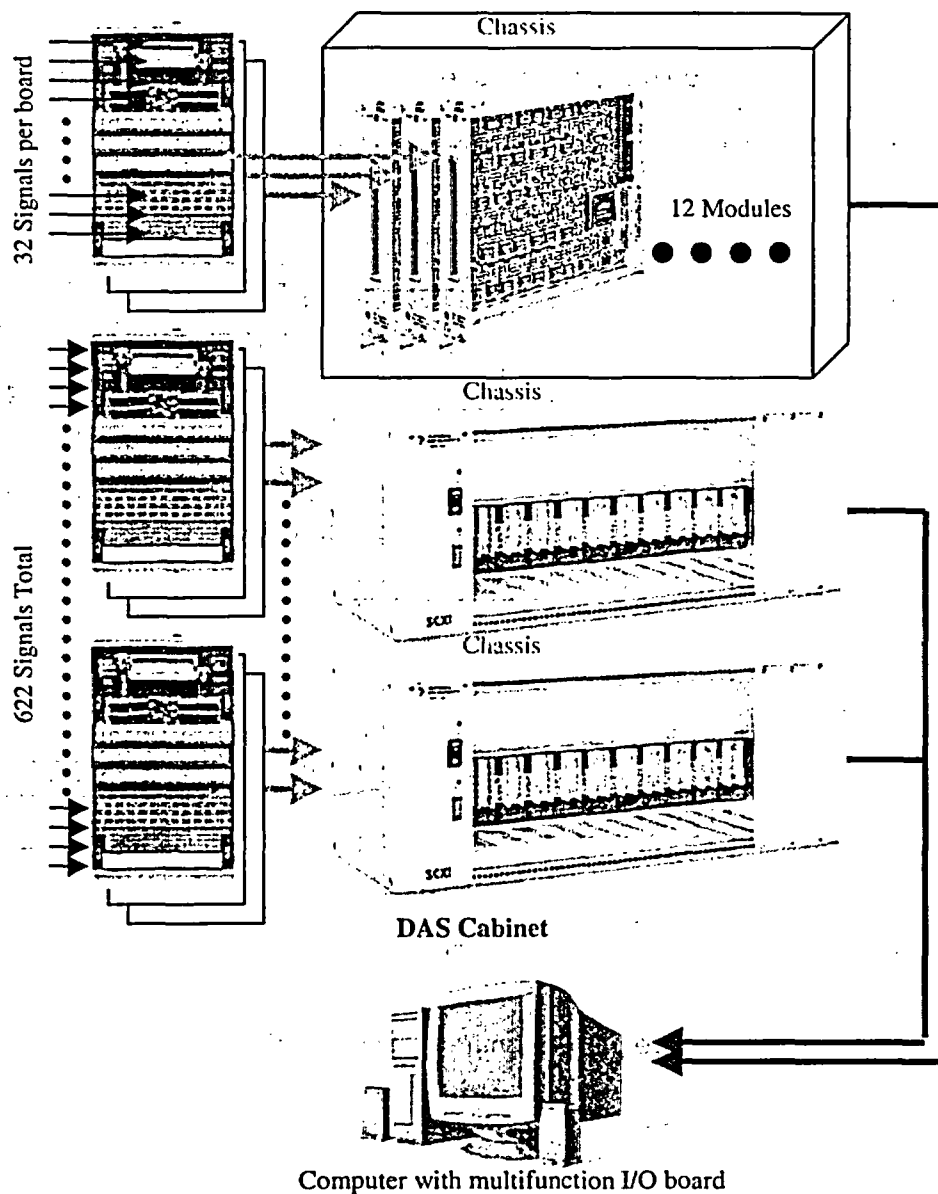


Figure 3.19. Data Acquisition System Hardware Overview

All of the data from input channels are acquired by NI-DAQ hardware/software and then converted into engineering units. The real-time data are sampled and stored in an NI Citadel database at one time per second per channel. Citadel is a proprietary database used for process data. OSU developed an export program to query the Citadel database and format the data file in ASCII text and NRC Data Bank binary file formats.

The NI DIAdem 8.1 trending software package is used to plot data for generating reports. DIAdem is capable of manipulating large data sets of more than a billion data points in up to 65,000 columns.

3.8.3 Control System and Control Logic

The APEX test facility control logic system includes various field process transmitters, operator switches, an OMRON programmable logic controller (PLC), a set of Fischer & Porter process controllers (PCs), and a supervisory host computer, as shown in Figure 3.20.

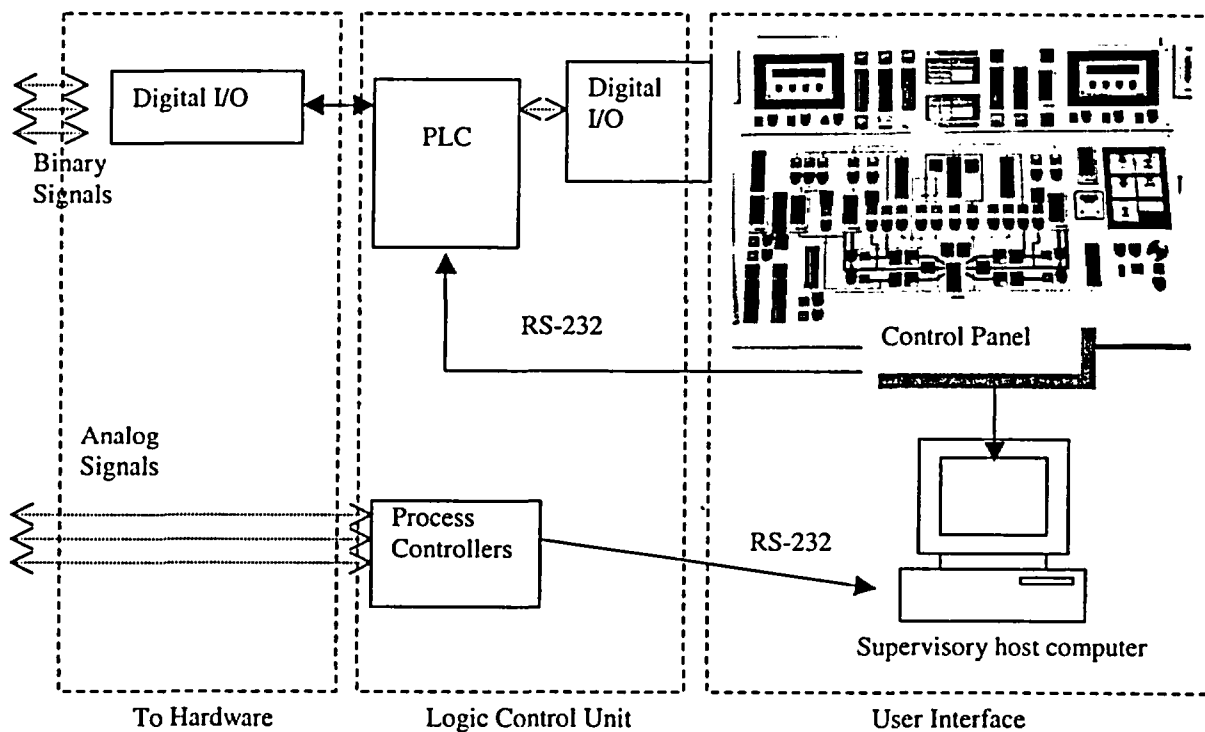


Figure 3.20. Control System Interface

The control system functions in three basic parts:

- (1) The PLC performs all binary logic functions for safety, sequencing, and operational control.
- (2) The PCs perform all dynamic (analog) process controls for smooth operation of variable control devices.
- (3) The supervisory system provides a graphical computer interface between the operator and the facility.

The PLC consists of a central processor for program execution, a power supply, two local racks of digital I/O, and several remote I/O racks located throughout the facility. All inputs are sensed as 24-VDC signals. All outputs are driven by a 24-VDC supply to energize pneumatic valves, pump motor starters, control panel lights and alarms, and other components. Figure 3.21 is photograph of the APEX control panel.

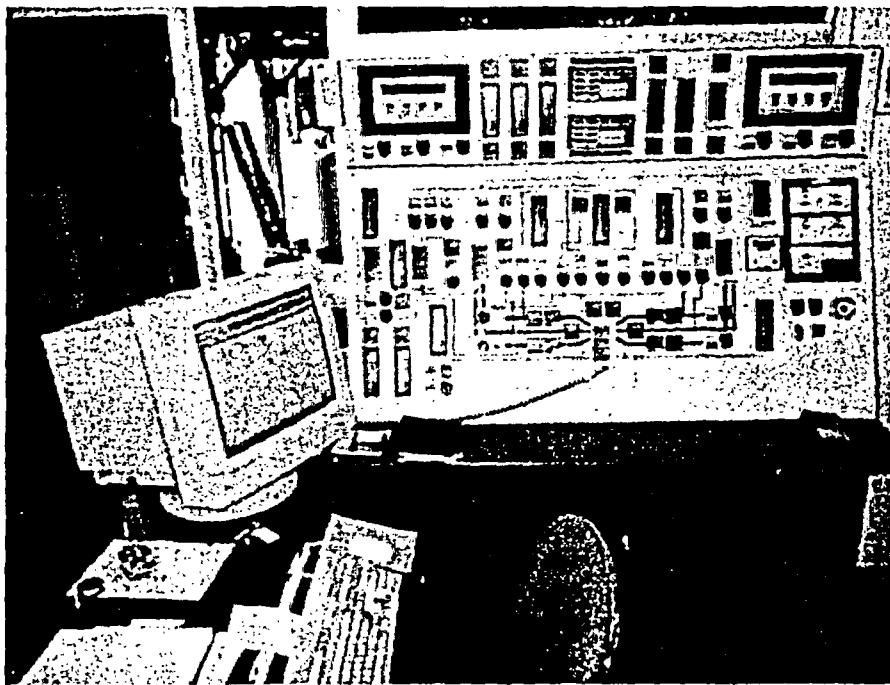


Figure 3.21. Photograph of the APEX Control Panel

The process control system consists of seven dedicated PCs with a total of 40 analog inputs and 20 analog outputs. Analog inputs are used to monitor the process, either directly or as calculated variables. They include tank level, system pressure, pump flow rate, and applied heater power. The controller performs a series of calculations to determine the likely state of the process and adjusts the analog output of the controlling device to maintain the process within defined parameters. The controlling devices include valves, power silicon control rectifiers (SCRs), and variable-speed pump controllers. The DAS and control computer are connected by a high-speed local area network.

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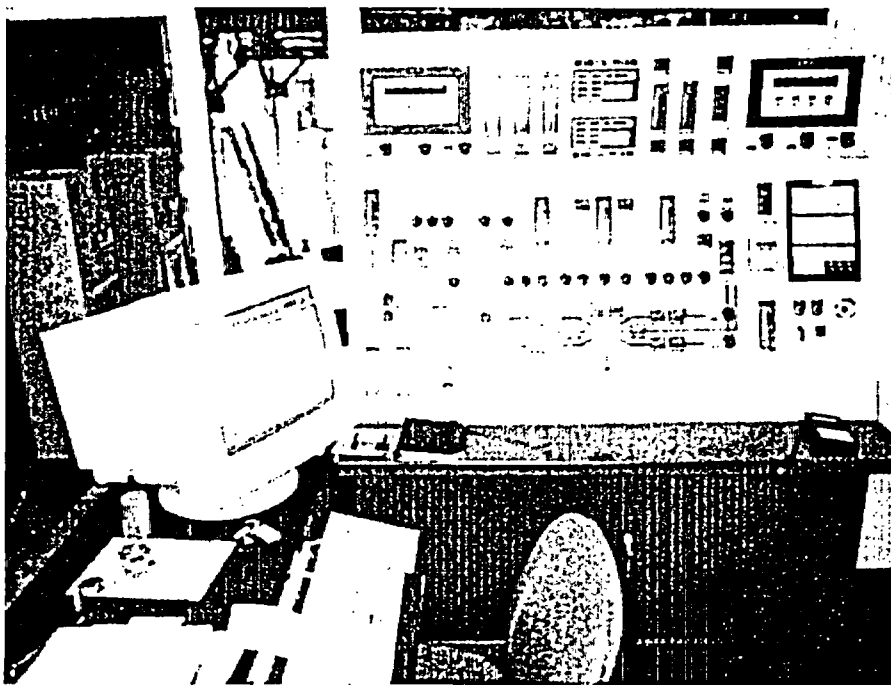


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There are six test logic routines implemented in APEX logic:

- (1) Station Blackout Routine
- (2) Small-Break Loss-of-Coolant Accident (LOCA) Routine
- (3) Large-Break LOCA Routine
- (4) Inadvertent ADS Initiation Routine
- (5) Full-Pressure ADS Routine
- (6) Natural Circulation Routine

3.8.4 Power System

The main purpose of the power system is to provide up to 1 megawatt of power to the reactor and PZR heater rods. Power comes from the local power grid at a voltage of 20,800 volts and is stepped down to a distribution voltage of 480 volts, three phase. From the 480-volt distribution power, one line (three-phase, max current $\approx 100\text{A}$) is used for the pumps in the APEX facility (RCP1 to RCP4, MFP, CVSP, RNSP, CRP, and seal WTR fan). Another line (three-phase, max current $\approx 200\text{A}$) provides the power for trace heaters. The three remaining lines are for the two Rx heater rod groups (three-phase, 500 kW max per line) and the PZR heater (three-phase, 20 kW max). Each of the heater power lines has the following components:

- 1 breaker to manually turn the power on/off
- 1 fuse for circuit protection
- 1 contactor to remotely turn the power on/off
- 1 phase angle-fired SCR to adjust the power level (SCR1 and SCR2 for Rx heater groups 1 and 2, SCR3 for the PZR heater)

During the test, the contactor controls the heater power (on/off), and the SCR signals are used to adjust the heater power level. The reactor heater rod SCRs, in conjunction with the heater controller, allow the APEX facility to simulate decay power by continually adjusting the reactor power level setpoint to follow the desired decay curve. See Figure 3.22 for a photograph of the SCR cabinet, and Figure 3.23 for a simplified sketch of the main power distribution system.



Figure 3.22. Photograph of the SCR Cabinet

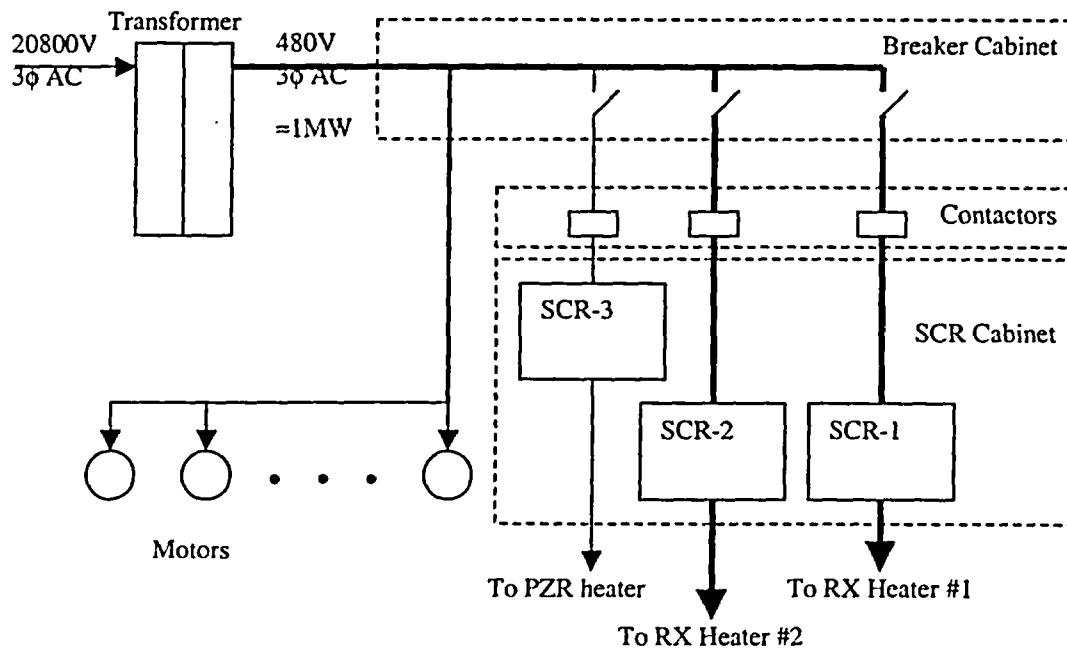


Figure 3.23. Main Power System Simple Layout



Figure 3.22. Photograph of the SCR Cabinet

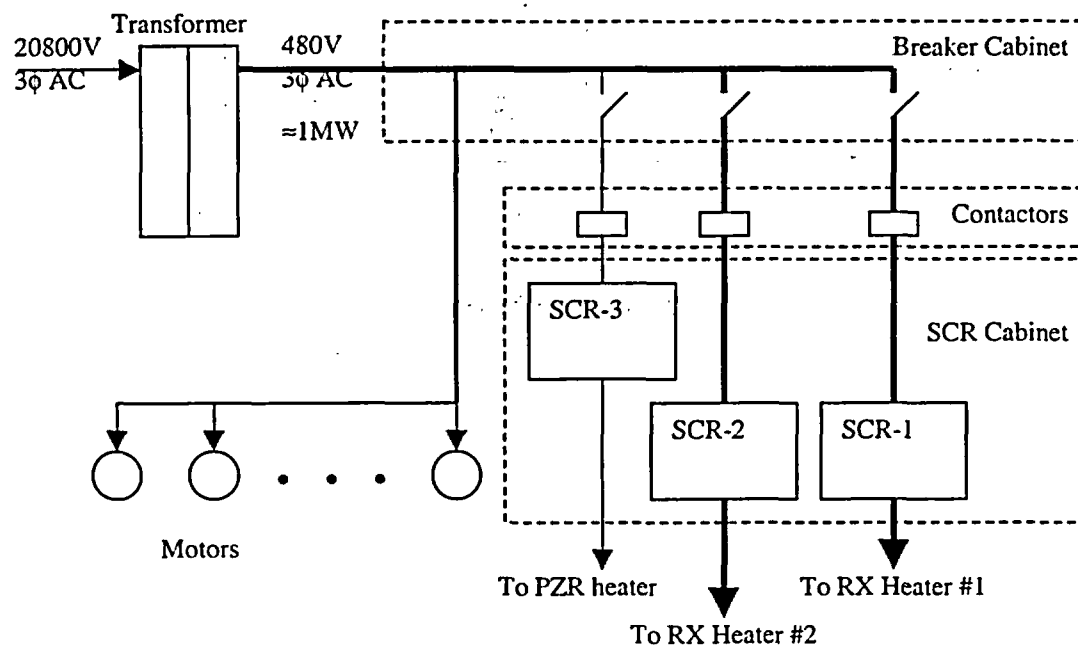


Figure 3.23. Main Power System Simple Layout

3.8.5 Break and ADS Measurement System (BAMS)

The BAMS, depicted in Figure 3.24, is used to measure two-phase volumetric flow rates from the break(s) and four stages of the ADS. All of the steam lines from the break separator, ADS4 separators, IRWST, and primary sump feed into the BAMS header and eventually vent via the exhaust header. All of the steam lines and moisture separators are heated with strip heaters to prevent condensation. Steam volumetric flow rate, pressure, and temperature are measured by vortex flow meters, pressure cells, and thermocouples respectively. Table 3.17 lists all instruments related to the ADS4-1/4-2 and break separator.

The BAMS system includes the following components:

- break separator
- two ADS4 separators
- ADS1-3 separator

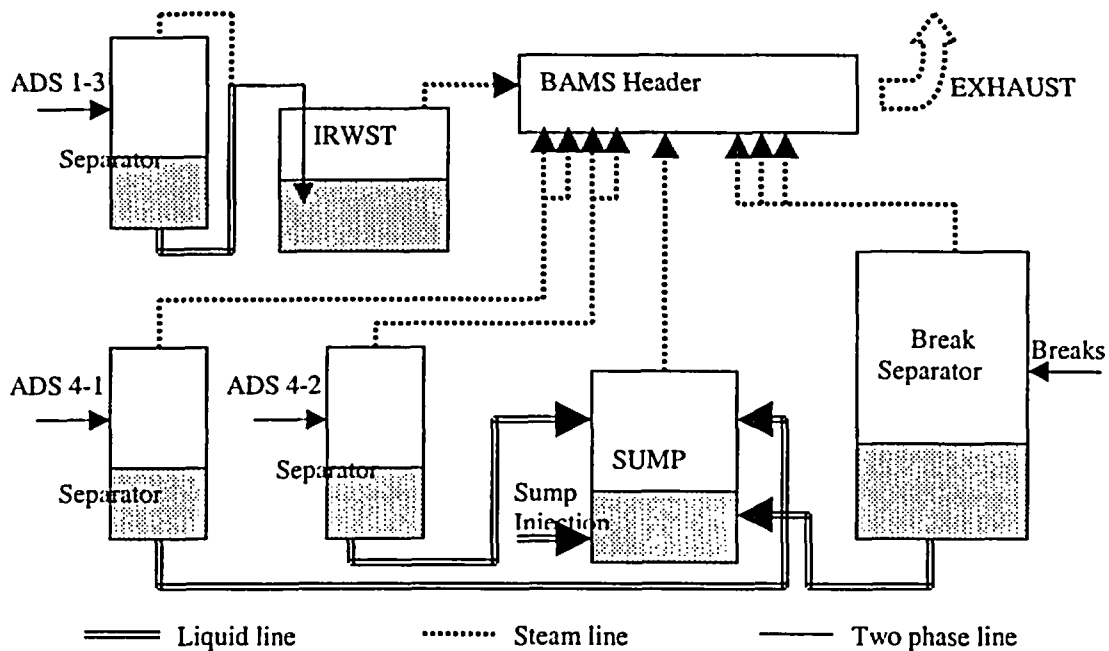


Figure 3.24. BAMS Layout

Table 3.17. ADS4-1/4-2, and Break Separator Instrument Names and Locations

LDP, FVM, FMM, DP, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
DP-905	Break Separator Entrance DP	TF-908	Break Separator Inlet Temperature
FMM-905	Break Separator Loop Seal Flow	TF-910	CRP Discharge to Primary Sump Temperature
FVM-901	BAMS HDR 6 in. Line Steam Flow	TF-911	CRP Discharge to IRWST Temperature
FVM-902	BAMS HDR 10 in. Line Steam Flow	TF-912	Break Separator Loop Seal Temperature
FVM-904	Break Separator 3 in. Line Steam Flow	TF-913	Break Separator Steam Outlet Temperature
FVM-905	Break Separator 6 in. Line Steam Flow	TF-914	CRT Outlet Temperature
FVM-906	Break Separator 8 in. Line Steam Flow	TF-915	Break Separator 6 in. Steam Line Temperature
LDP-903	CRT Uncompensated Water Level	TF-916	BAMS Header 10 in. Steam Line Temperature
LDP-905	Break Separator Uncompensated Water Level	TF-917	BAMS Header Temperature
PT-902	BAMS Header Pressure	TF-918	Break Separator 8 in. Steam Line Temperature
PT-905	Break Separator Pressure	TW-905	Break Separator Wall Temperature

The APEX test facility can model several different break locations:

- CL3 bottom break (TS-205 actuates)
- CL3 top break (TS-201 & T-205 both actuates)
- single-ended DVI break (TS-202 actuates, pressure equalization line open during warm-up, closed prior to break)
- single-ended CMT balance line break (TS-203 actuates, pressure equalization line open during warm-up, closed prior to break)
- HL2 bottom break (TS-204 actuates)
- CL4 bottom break (TS-206 actuates)
- double-ended CMT balance line break (TS-203 and TS-202 actuates)
- DEDVI break (TS-203 and TS-202 actuates)

The two-phase flow that exits the break is piped into the break separator. The primary purpose of the break separator is to separate the steam and liquid phase of two-phase flow for the convenience of measurement. Water/steam mixture enters through the middle and passes through a cyclone separator. The separated steam exits the top of the separator, while the liquid is collected and allowed to drain out of the bottom of the separator through a loop seal and into the primary sump. The wall of the separator is heated by a long strip heater to prevent steam condensation inside the separator.

The break separator steam outlet line is divided from a large pipe into three smaller parallel paths, which are recombined before the exhaust. The steam flow is routed through one of these three paths, depending on the expected flow rate. Each of these paths is controlled by an air-operated logic ball valve and measured by a vortex flow meter to control the separator liquid level within the desired range to contain the steam, while the liquid goes to the correct outlet. If the steam line size is too small for a given flow rate, the increased pressure will push the water out of the loop seal, and there will be a two-phase mixture in the liquid line (which cannot be measured). By contrast, if the selected steam line is too large, it is difficult to obtain an accurate measure of the steam flow rate because it is too small. The ADS4 separator steam line has a similar design, but uses only two paths. The primary and secondary sumps are used to simulate the containment.

The two ADS4 separators are similar in design to the break separator. The steam exiting the separators can be directed through one of two different sized pipes, depending on the expected flow rate. The reasoning behind the use of different size steam lines is the same as for the flow from the break separator. The liquid phase from each ADS4 separator is collected and directed through a loop seal and into the primary sump.

The ADS1-3 separator is a large cylinder. The exiting two-phase mixture flow from ADS1-3 valves is directed into the ADS1-3 separator through an inlet. The liquid flow exits the bottom of the separator, while the steam flow exits the separator via a different pipe located at the opposite side of the inlet. The steam volumetric flow rate is measured by a vortex flow meter (FVM-601). Liquid phase is directed out of the separator via a pipe at the bottom of the separator and measured by a magnetic flow meter. The steam and liquid phases are finally recombined and injected into the IRWST via a sparger.

In the prototype, the steam phase that exits the break condenses on the containment wall and drains back to the IRWST or sump. In the test facility, the steam phase is vented to the atmosphere. To compensate for the mass loss attributable to steam exhaust to the atmosphere, the containment condensate return system is available to inject fluid into the IRWST or sump at the same mass flow rate of the vented steam if desired. The condensate return system is fed by the feedwater storage tank (FST) into the condensate return tank (CRT) in which the water is preheated. The CRT contains heaters to preheat the water prior to injection into the IRWST or the primary sump. The outlet water temperature is measured by a thermocouple, and the measurement is feedback to the CRT heaters to maintain the proper outlet temperature. The liquid is pumped from the CRT by means of the condensate return pump (CRP) through either a recirculation line with the line resistance controlled by an orifice plate, or the IRWST or primary sump via motor-operated valves (CCS-928/927).

3.9 Balance of Plant

The APEX-AP1000 facility incorporated several of the AP1000 non-safety systems, including the CVS, RNS, SG, feedwater system, main steam system, and water purification system. These non-safety systems were designed and constructed to meet the necessary functional requirements for testing. The pipe routings and relative locations within the APEX facility are not necessarily prototypic of the AP1000 design.

3.9.1 Chemical and Volume Control System (CVS)

The CVS is used to maintain proper water chemistry in the primary coolant for a full-sized plant. The CVS pump is a Goulds 3-stage centrifugal pump. See Table 3.18 for a list of instruments related to the CVS. In the APEX facility, the CVS pump is used for the following five main purposes:

- (1) maintenance of fluid during startup
- (2) modeling AP1000 operation if desired
- (3) normal supply of makeup water to the APEX facility
- (4) hydrostatic testing
- (5) backup pump for the main feedwater pump (MFP)

Table 3.18. CVS Instrument Names and Locations

FMM, PT Cells, and Thermocouples	
Tag Name	Description
FMM-801	CVS Discharge Flow
PT-801	CVS Discharge Pressure
TF-801	CVS Discharge Temperature

3.9.2 Normal Residual Heat Removal System (RNS)

The RNS pump draws water from the IRWST or primary sump, injects it into the DVI line, and provides makeup water under low-pressure conditions. The RNS pump is used to fill the CMTs and ACCs before performing a test. See Table 3.19 for a list of instruments related to the RNS.

Table 3.19. RNS Instrument Names and Locations

FMM and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
FMM-803	RNS to DVI2 Flow	TF-802	RNSP Discharge Temperature
FMM-805	RNS Discharge Flow	TF-813	RNSP Discharge to DVI1 Temperature
PT-802	RNS Discharge Pressure	TF-814	RNSP Discharge to DVI2 Temperature

Figure 3.25 depicts the performance curve for the RNS pump [CR4-100N (5.0 HP (3.73 kW))].

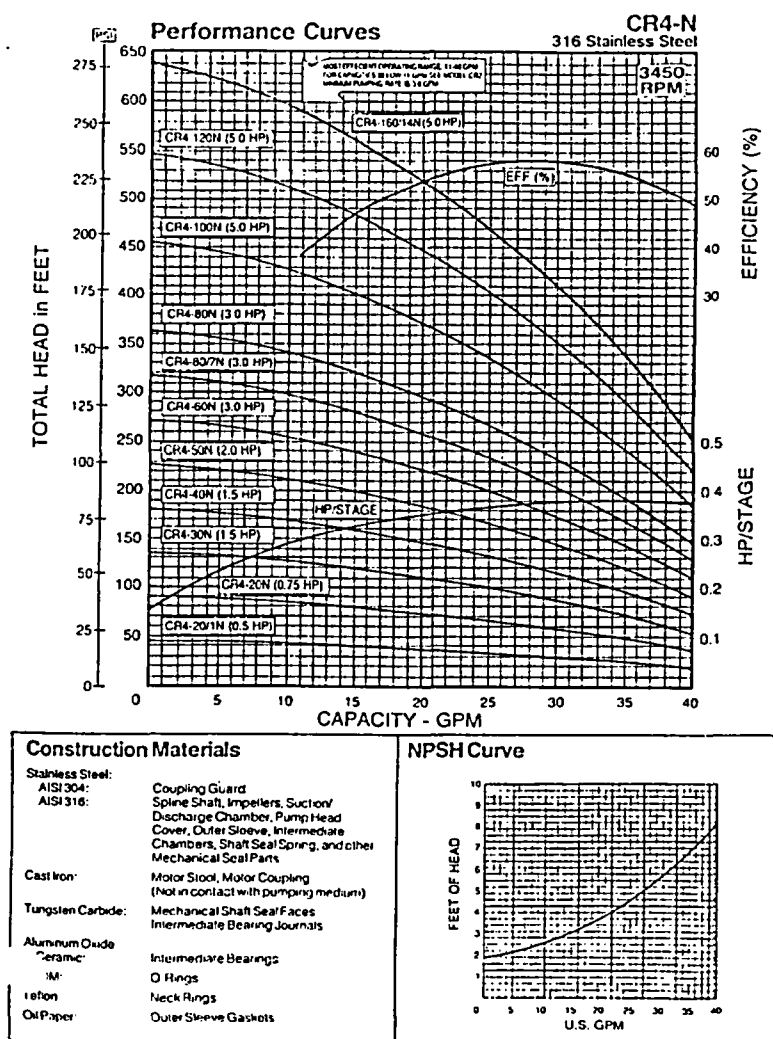


Figure 3.25. RNS Pump Performance Curves

3.9.3 Feedwater System

The purpose of the feedwater system is to provide water to the SG. The feedwater system consists of the demineralization system (DI), FST, and MFP, as shown in Figure 3.26. The FST stores water from the DI. Table 3.20 lists all instruments related to the FST, MFP, and SG steam vent.

For the main feed flow path, the MFP takes water from the FST and pumps it into both SGs. The MFP is a Goulds 3-stage centrifugal pump. The pump curve is at the end of this section. There is a magnetic flow meter (FMM-001 or FMM-002) and a motor-driven valve (MF-011 or MF-012) in each feed line (respectively) to monitor and control the feedwater flow.

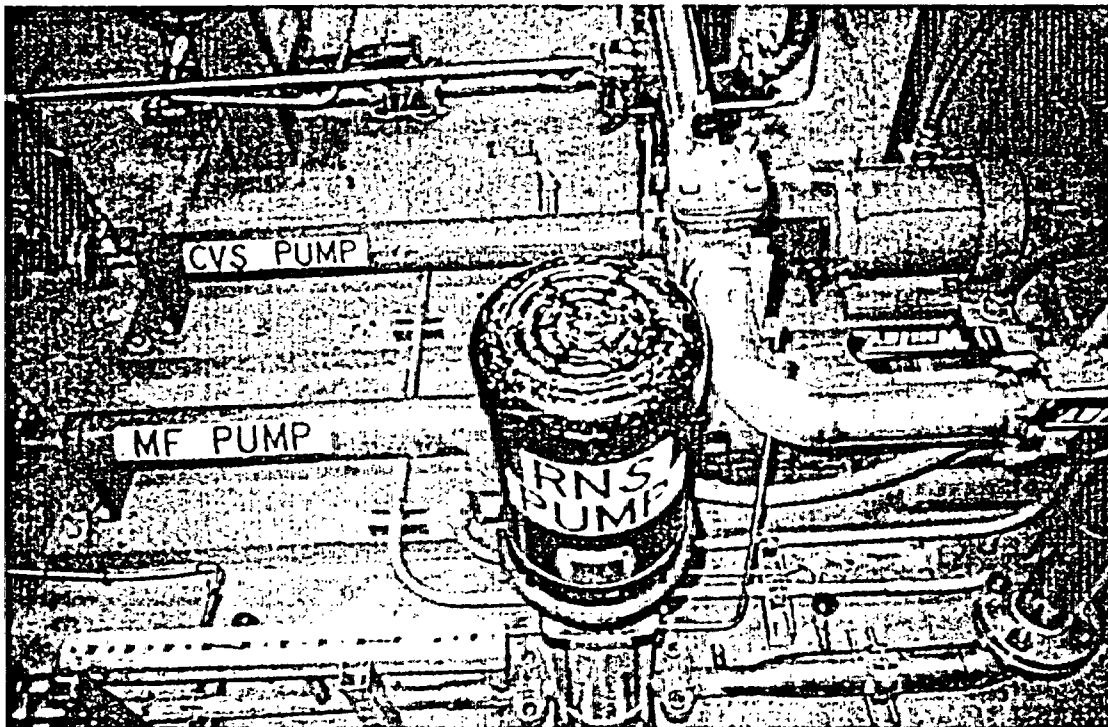


Figure 3.26. Image of RNS, CVS, and MF Pumps

When the steam exits the SG, there are two possible paths for it to follow:

- (1) One path is controlled by a normally open air-operated ball valve (MS-001 for SG1 and MS-002 for SG2) and monitored by a vortex flow meter (FVM-001 for SG1 and FVM-002 for SG2).
- (2) The other path is controlled by a normally closed air-operated ball valve (MS-009 for SG1 and MS-010 for SG2) and monitored by a vortex flow meter (FVM-009 for SG1 and FVM-010 for SG2).

Both of these lines will eventually exit the building through the steam exhaust. The difference between the two lines is that the first goes through the turbine simulation path with a motor-operated logic ball valve (MS-008) and monitored by a vortex flow meter (FVM-003), while the other is used for startup of the facility.

Table 3.20. FST, MFP, and SG Steam Vent Instrument Names and Locations

LDP, FMM, FVM, and PT Cells		Thermocouples	
Tag Name	Description	Tag Name	Description
FMM-001	SG1 Feed Flow	TF-005	Lab Ambient Temperature @ Ground Level
FMM-002	CL2 Loop Flow	TF-006	Lab Ambient Temperature @ 2 nd Level
FVM-001	SG1 Main Steam Flow	TF-007	Lab Ambient Temperature @ 3 rd Level
FVM-002	SG2 Main Steam Flow	TF-009	SG1 PORV Line Temperature
FVM-003	Main Steam Combined Flow	TF-010	SG2 PORV Line Temperature
FVM-009	SG1 PORV Steam Flow	TF-301	TF-301/SG1 (via Signal Conditioner)
FVM-010	SG2 PORV Steam Flow	TF-310	TF-310/SG2 (via Signal Conditioner)
LDP-001	FST Level	TF-311	SG1 Feed Header Temperature
PT-001	MFP Discharge Pressure	TF-312	SG2 Feed Header Temperature
PT-002	MS Header Pressure		
PT-003	Lab Barometric Pressure		
PT-009	SG1 PORV Line Pressure		
PT-010	SG2 PORV Line Pressure		
PT-301	SG1 Pressure		
PT-302	SG2 Pressure		

3.9.4 Water Purification System

The water for the feedwater system comes from potable water. The DI purifies the incoming potable water for use in the secondary loop. The water first passes through two parallel resin traps (resin traps 1 and 2). It is then demineralized by four demineralization tanks, which are arranged into two parallel groups (demineralization banks 1 and 2). The water then passes through two additional resin traps (resin traps 3 and 4). The flow rate is then measured by a vortex flow meter (FVM-004), and an injection line then allows chemicals to be injected from a chemical addition tank. The chemicals that are added to the water include ammonium hydroxide (NH₄OH) and NALCO 1254. Ammonium hydroxide is used to reduce the pH in the system and to minimize corrosion of the components. NALCO 1254 is an additive that prevents buildup of sludge within the system. After all treatments, the feedwater is sent to the FST.

4. TEST MATRIX AND OVERVIEW

Eight NRC-sponsored beyond-DBA tests (listed in Table 4.1) were run at the APEX-AP1000 facility to confirm safety margins to support AP1000 design certification. Based on experience from previous AP600 design certification activities, these tests focused on DEDVI line breaks with various failures of the ADS.

Of the 8 beyond-DBA tests, three (NRC-AP1000-01, 03, and 05) considered DEDVI line breaks with failure of the ADS1, 2, and 3 valves, and ADS4 valves on the PZR and non-PZR sides of the plant. Two CL break tests (NRC-AP1000-04 and 06) were run to examine the sensitivity of ADS4 valve failure with respect to a smaller size breaks than a DEDVI line break. A Probabilistic Risk Assessment verification test (NRC-AP1000-10) and station blackout test (NRC-AP1000-11) were run to complete the confirmatory test matrix. Finally, a Mode 5 operation test (NRC-AP1000-02) was run with the ACCs and CMTs unavailable. Appendix C presents detailed time transient plots, sequence of events, and facility configurations for each test. These beyond-DBA tests were selected, based on previous experience with the AP600 design certification, as the scenarios which would potentially be the most challenging to the AP1000 passive safety systems.

In addition, three upper plenum steady-state entrainment tests (NRC-AP1000-07, 08, and 09) were run to provide data for thermal-hydraulic code assessment, but those tests are not discussed in this report. Please note that all transient plots presented in this section are plotted against dimensionless time.

Table 4.1. APEX-AP1000 Confirmatory Test Matrix

Test Number	Description	Date Completed
NRC-AP1000-01	DEDVI Line Break with Failure of ADS1, 2, and 3. Both ADS4 trains fully functional.	6/5/03
NRC-AP1000-02	Mode 5 Operation with Loss of RNS Cooling. No break. ADS1, 2, and 3 open. SG secondary side assumed drained. CMTs and ACCs unavailable or failed (one valve on PZR side available).	9/30/04
NRC-AP1000-03	DEDVI Line Break with Failure of 2 of 4 ADS4 Valves on PZR side. ADS1, 2, and 3 valves fully functional.	6/11/03
NRC-AP1000-04	CL #4, 1" Break with Failure of 1 of 4 ADS4 Valves on non-PZR side. ADS1, 2, and 3 valves fully functional. Containment sump degraded (CMT#1, ACC #1, sump recirculation line #1 and IRST line #1 unavailable).	10/9/03
NRC-AP1000-05	DEDVI Line Break with Failure of 2 of 4 ADS4 Valves on non-PZR side. ADS1, 2, and 3 valves fully functional.	6/10/03
NRC-AP1000-06	CL #4, 2" Break with Failure of 2 of 4 ADS4 Valves on non-PZR side and PRHR. ADS1, 2, and 3 valves fully functional.	8/15/03
NRC-AP1000-07*	Upper Plenum Entrainment Test with Upper Internals Installed. Core inventory allowed to boil-off from top of hot legs to top of core. Three different power levels were run.	8/24/04
NRC-AP1000-08*	Upper Plenum Entrainment Test with Modified Power Stepping. Repeat of NRC-AP1000-07 with additional power steps.	9/7/04
NRC-AP1000-09*	Upper Plenum Entrainment Test with Upper Internals Removed. Core inventory allowed to boil-off from top of hot legs to top of core. Three different power levels were run.	9/16/04
NRC-AP1000-10	PRA Verification Test. Bottom of CL #4, 2" break with failure of 1 of 4 ADS4 valves on non-PZR side and failure of ADS1, 2, and 3 valves.	4/29/04
NRC-AP1000-11	Station Blackout. No break. Failure of 1 of 4 ADS4 valves on non-PZR side.	7/29/04

*Not discussed in this report

4.1 Typical Sequence of Events for an APEX-AP1000 SBLOCA

This section presents the typical sequence of events for a small break (SB) LOCA scenario in the APEX-AP1000 test facility [Ref. 3]. The AP1000 safety logic (Appendix B) was closely modeled in the APEX test facility. Each SBLOCA test was initiated from steady-state operating conditions and started by opening a valve located on the primary loop piping. For SBLOCAs, the bottom of CL4 was typically chosen as the break location. Fluid flow from the break was directed to the break separator, where the vapor and liquid flows were measured separately. The vapor flow was then directed to the BAMS header, and the liquid flow to the primary sump. The SBLOCA scenario can be divided into five different phases, as shown in Figure 4.1 [Ref. 3]:

- (1) High-Pressure Blowdown
- (2) Natural Circulation
- (3) ADS Blowdown
- (4) IRWST Injection
- (5) Sump Recirculation

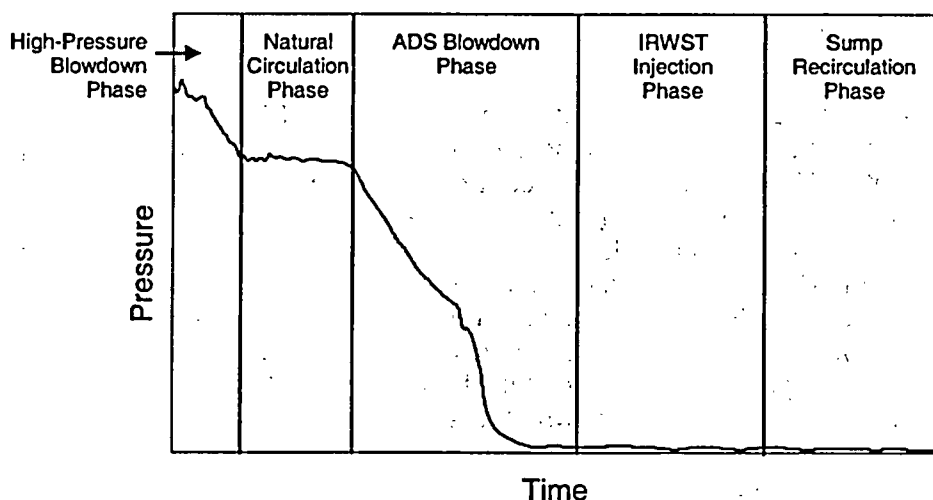


Figure 4.1 Pressure History for a Typical 2-inch Cold Leg Break in APEX [Ref. 3]

4.1.1 High-Pressure Blowdown Phase

The break in the primary loop caused a rapid initial blowdown of the system. Depending on the break size, this period was relatively short. As the PZR level decreased, it caused the issuance of an "S signal," which generated the following actions:

- PRHR isolation valves opened
- CMT isolation valves opened
- feedwater pump tripped
- steam generator steam flow isolated
- reactor coolant pumps tripped
- reactor power in decay mode to simulate a reactor scram

As the system blowdown continued, saturated conditions were reached in the HLs. The onset of saturated conditions in the HLs concluded the high-pressure blowdown phase.

4.1.2 Natural Circulation Phase

When the RCPs were tripped, the primary loop flow transitioned from forced to natural circulation. This natural circulation flow continued until voiding occurred in the primary side of the SG tubes. Operation of the PRHR and CMTs created additional paths for buoyancy-driven core heat removal. Water from the HL/ADS4 line connection rose to the PRHR inlet header and traveled through the PRHR HX. The cold water leaving the PRHR HX flowed to the CLs. In a similar manner, each CMT provided cooling to the core by recirculating its volume. Relatively hot water from the CLs rose into the CMT-PBL to the CMT's upper head. The hot water then displaced the cold water leaving the CMTs into the DVI injection line and finally into the RPV.

As the facility depressurized, steam collected or formed as a result of flashing in the CMT's upper head. This caused the CMT to drain and ceased the recirculation mode. In some cases, the CMTs partially refilled as a result of steam condensation. Eventually, the liquid level in the CMT reached the ADS1 actuation setpoint. The natural circulation phase of the transient concluded upon ADS1 actuation.

4.1.3 ADS Blowdown Phase

Both trains of the AP1000 ADS1–3 lines located on the top of the PZR were modeled in APEX. The flow nozzles used in the ADS lines were scaled to simulate choked flow, assuming pressure similitude subsequent to ADS3 actuation. The control logic opened ADS1, ADS2, and ADS3 in sequence. The ACCs typically began to inject sometime during ADS1–3 blowdown. The large flows caused by ACC injection typically delayed CMT draining. After ACC injection flow rates became low enough, the CMTs continued to drain. Eventually, the CMT liquid level dropped to the ADS4 actuation setpoint. APEX simulated both trains of the AP1000 ADS4 lines. After ADS4 actuation, the primary system depressurized to atmospheric conditions. This permitted the IRWST check valves to open in response to the hydrostatic head of the IRWST liquid. The onset of IRWST injection concluded the ADS blowdown phase.

4.1.4 IRWST Injection Phase

Upon IRWST injection, the liquid in the reactor core became subcooled. This condition persisted until the level in the IRWST was relatively low. At that time, the reduced IRWST injection flow rate was no longer sufficient to keep the core fluid subcooled. When saturated conditions were reached at the core exit, oscillations were observed in the IRWST injection flow, system pressure, RPV level, and ADS4 flow. These oscillations are an artifact of the APEX primary to secondary sump connect, were labeled "Return to Saturation Oscillations" (RSOs) in the APEX-AP600 confirmatory testing program, and became the subject of a separate parametric test. In the APEX-AP1000 and APEX-AP600 tests, these oscillations did not impact core cooling because the RPV liquid level always remained near the top of the HL. When the liquid level in the IRWST reached the sump recirculation setpoint, the sump recirculation valves opened. The oscillations were terminated at this time, and the IRWST injection phase concluded.

4.1.5 Sump Recirculation Phase

The sump recirculation phase marked the beginning of long-term cooling. Liquid from the primary sump flowed through the sump recirculation lines into the DVI lines and then into the RPV. The boiling in the core provided the density differences required to draw the water from the sump to the RPV. Steam generated in the core was vented through the ADS4 lines. Sump recirculation usually continued for 30 minutes until terminated by the operator, thus concluding the test. In some cases, the sump recirculation phase continued longer when a degraded sump was simulated.

4.2 Test NRC-AP1000-01

Test NRC-AP1000-01 simulated a DEDVI line break with a complete failure of ADS1, 2, and 3. This test was designed as a beyond-DBA scenario because of the multiple valve failures. All four ADS4 valves were available, and this test investigated the ability of the ADS4 system to accomplish system depressurization to allow for IRWST injection. The PRHR HX was inactive during this test.

The APEX-AP1000 facility models both trains of the AP1000 ADS1-3 lines located at the top of the PZR after a nozzle that models the scaled choked flow area of the AP1000. The ADS1-3 valve train typically discharges to the ADS1-3 separator, where the two-phase flow is separated and measured.

Figure 4.2 illustrates the facility configuration during this test and contains non-dimensional plots of RPV-wide collapsed liquid level, passive safety system injection flow rates (sides 1 and 2), and core heater rod temperatures. The DEDVI Line 1 break opened at zero seconds and created a rapid depressurization, which caused the CMTs to begin injection immediately. However, half of this makeup flow exited the DVI Line 1 break. As the facility depressurized, steam collected or formed as a result of flashing in the CMT's upper head. This caused the CMT to drain, terminating the natural recirculation phase of the transient. The ACCs typically begin injecting during ADS1-3 actuations, but since ADS1-3 were failed shut, ACC2 began injecting around time 1. When the liquid level in the CMTs was low enough, ADS4-1 opened and helped to depressurize the plant even further. After the ADS4 valves opened, CMT2 and ACC2 injection flow rates increased significantly. The reactor vessel collapsed liquid level remained approximately constant during ACC and CMT injection (between time 2.7 and 8) as the plant was depressurized using the ADS.

At around time 7, the plant reached atmospheric conditions. This permitted the IRWST check valves to open in response to the hydrostatic head of the IRWST liquid, thus ending the ADS blowdown phase of the transient. It should be noted that there was a noticeable overlap between when CMT2 injection flow ended and IRWST injection began, which provided adequate core cooling during this time period. As IRWST injection flow increased, the vessel collapsed liquid level began to rise around time 10. Later in the test (around time 14), CMT1 experienced short periods of refill as a result of condensation-induced pressure drops, which is an artifact of the one-quarter height scaling. For the remainder of the test, the HL water level remained high, and the core remained covered as a result of adequate injection flow from the IRWST. The test was ended before sump recirculation or long-term cooling was initiated. No heater rod high-temperature excursion was experienced, and the core remained adequately cooled during the entire test.

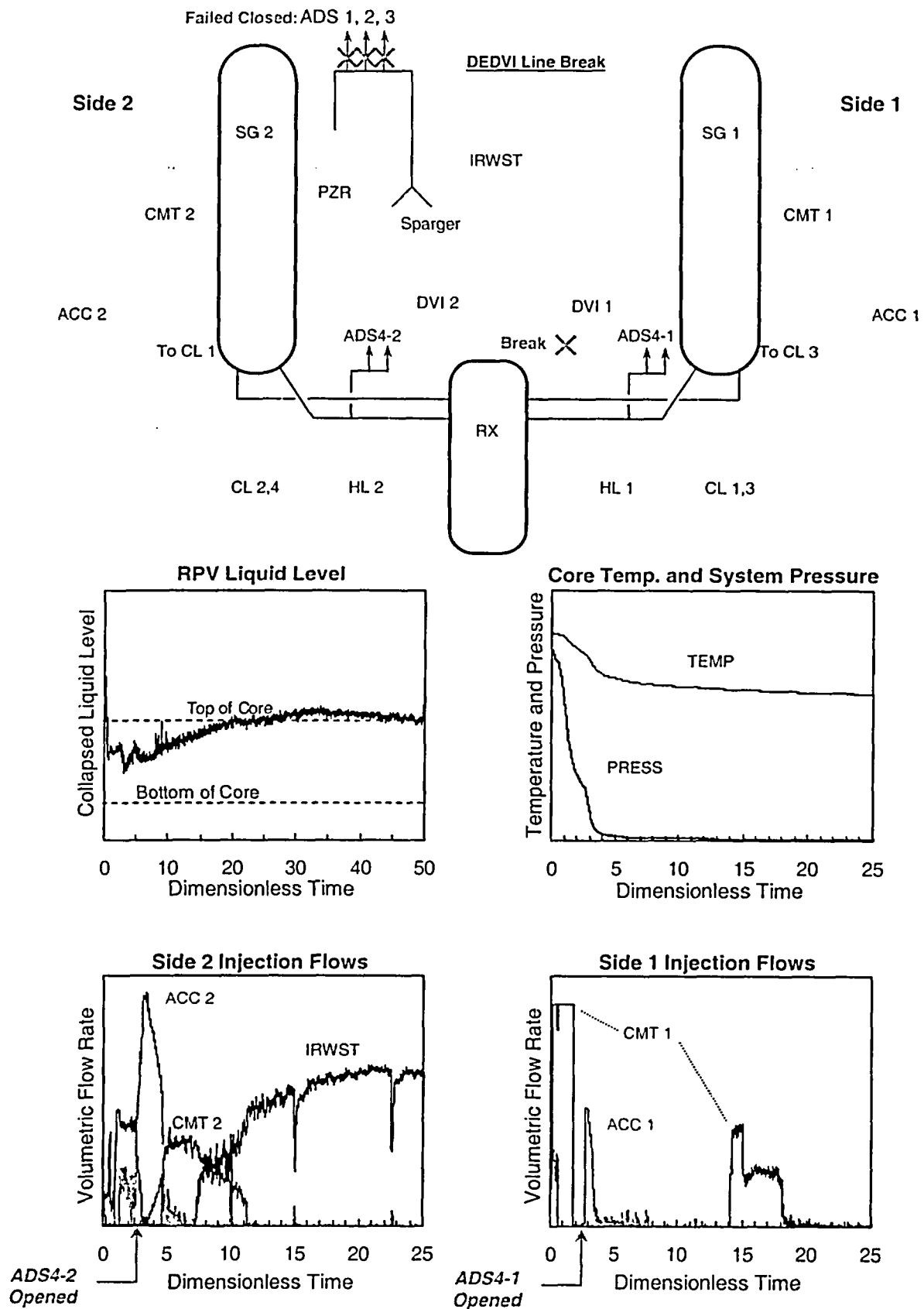


Figure 4.2 Test NRC-AP1000-01 Passive Safety System Performance.

4.3 Test NRC-AP1000-02

Test NRC-AP1000-02 investigated passive safety system performance during Mode 5 (cold shutdown) operation with a loss of the RNS. The objectives of this test were to determine system behavior during a loss of shutdown cooling. Specifically, if the RCS would pressurize sufficiently to prevent IRWST injection, and if counter-current flow limitation (CCFL) prevent the PZR from draining. There was no break in this test; ADS3 was opened at zero seconds (simulated two trains of ADS1, 2, and 3 in AP1000), the SG secondary side was assumed drained, the CMTs and ACCs were unavailable, and one ADS4 valve was failed closed. Power was increased to about 120 kW at the beginning of the test.

Figure 4.3 illustrates the facility configuration during this test, and contains non-dimensional plots of RPV-wide collapsed liquid level, IRWST injection flow rates, core heater rod temperatures, and PZR wide-range collapsed liquid level. The test was begun at zero seconds when the reactor power was at 120 kW to simulate a loss of RNS cooling. As water boiled off from the core and exited through the open ADS3 line, the RPV collapsed liquid level dropped to below the top of the core at around time 5. The ADS4-1 valve (non-PZR HL) failed to open on demand at around time 9.7 and decreased the RPV pressure to allow for IRWST injection. By time 10.2, the RPV collapsed liquid level rose above the top of the core and remained high until around time 20. The PZR completely drained just after IRWST injection began at around time 10. At about time 30, the sump recirculation valves were opened on low IRWST level, thus ending the IRWST injection phase, and the long-term cooling began. The core remained adequately cooled during the entire test.

4.4 Test NRC-AP1000-03

This test was a DEDVI line break with failure of two of the four ADS4 valves on the PZR side of the plant. The purpose of this test was to investigate the sensitivity of ADS4 valve failure on core coolability. Figure 4.4 shows the plant configuration for this test and plots of safety injection flow rates (sides 1 and 2), along with reactor vessel collapsed liquid level, and core temperature.

The break in DVI1 was opened at time zero, and the CMTs began injecting immediately as the primary system rapidly depressurized. As the CMTs emptied, the ADS1-3 valves began to actuate, beginning the ADS blowdown phase of the transient. Shortly after, ACC2 began injecting. The ADS4-1 valves opened just after time 1.7 to reduce the plant pressure to allow for IRWST injection, thus ending the ADS blowdown phase. IRWST injection began around time 14, while CMT2 injection ended around time 10. Between time 10 and 14, no makeup water was provided to the core.

As water was injected into the core from the IRWST, the core level increased. Eventually, the IRWST finished draining, and the plant successfully entered sump recirculation for long-term cooling around time 75. During the test, core temperature spiked a few times for very brief periods, but enough water was provided from the passive safety systems to keep the core adequately cooled throughout the entire test.

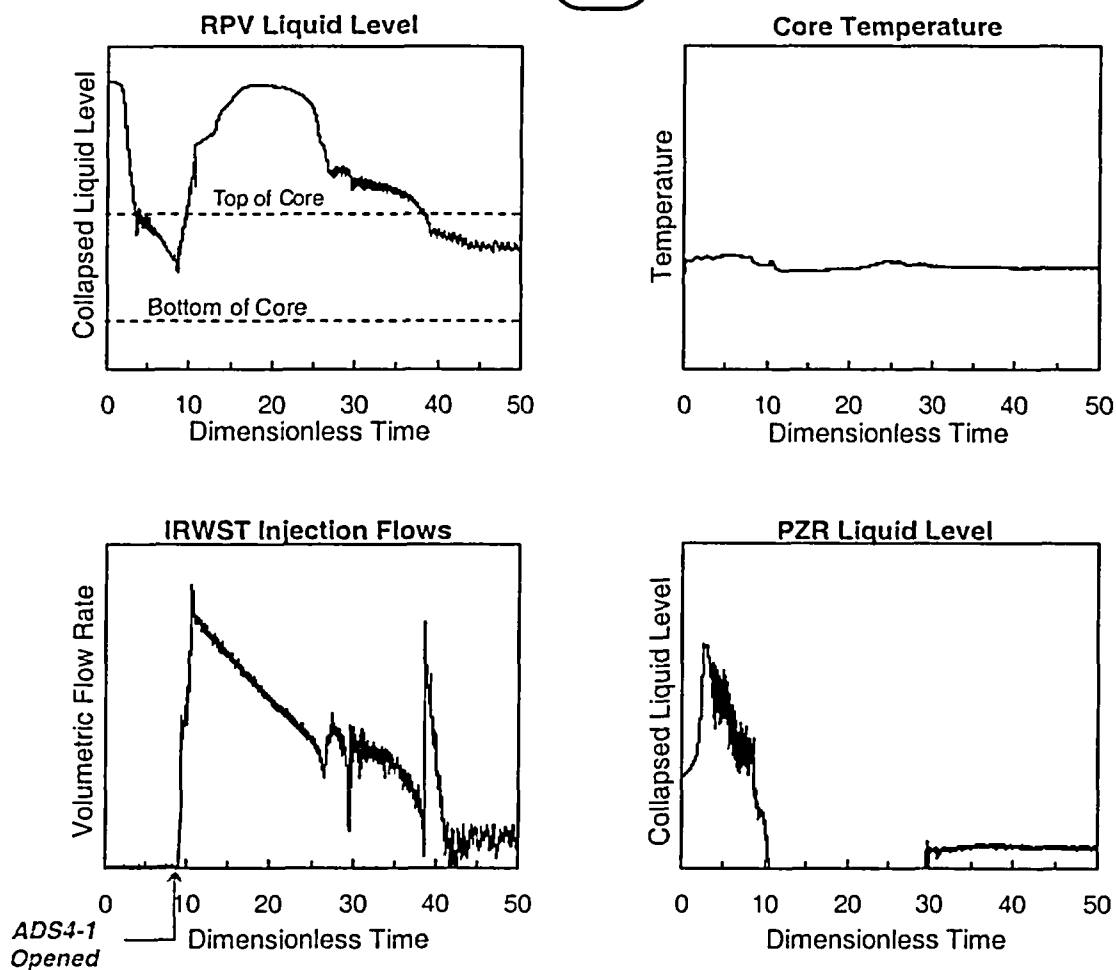
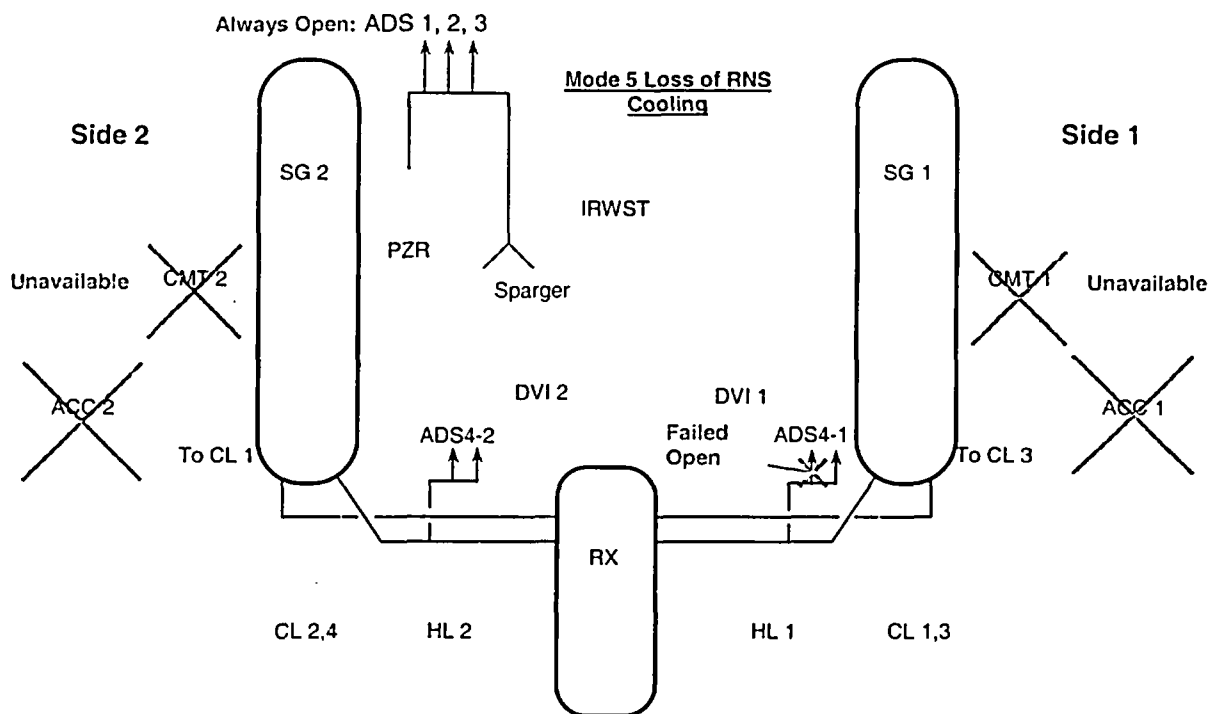


Figure 4.3 Test NRC-AP1000-02 Passive Safety System Performance.

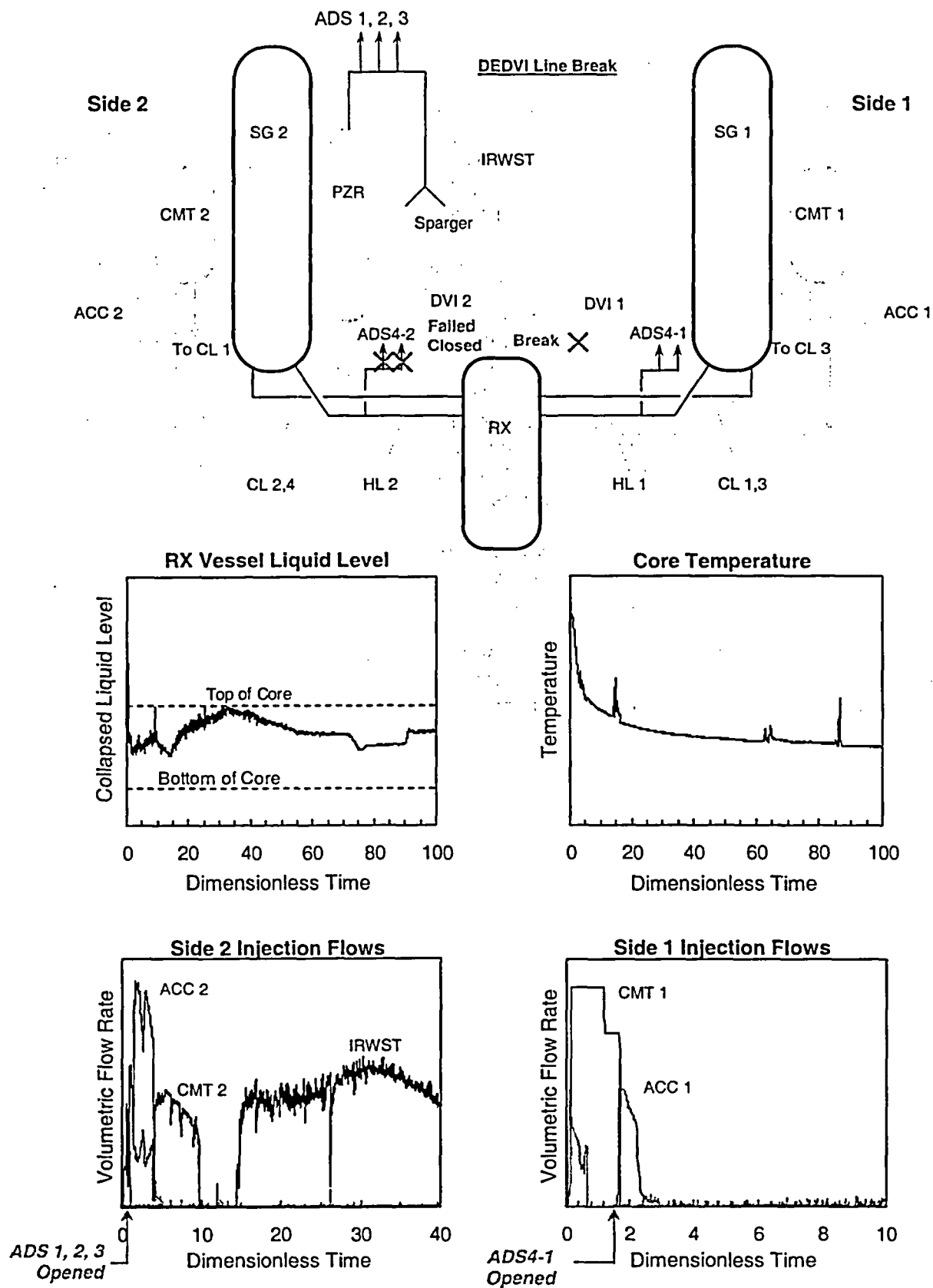


Figure 4.4 Test NRC-AP1000-03 Passive Safety System Performance.

4.5 Test NRC-AP1000-04

Test NRC-AP1000-04 was a beyond-DBA test simulating a 1-inch CL break with one ADS4 valve failed shut (50% line flow) on the non-PZR HL. In addition, CMT1, ACC1, sump recirculation line 1, and IRWST injection line 1 were unavailable. The intent of this test was to investigate the sensitivity of ADS4 valve failure on core coolability with loss of several safety injection paths, and to determine the impact of a simulated degraded sump on long-term cooling.

Figure 4.5 illustrates the facility configuration for this test, and contains plots of RPV-wide collapsed liquid level, passive safety injection flow rates (side 2), and core heater rod temperature and power. The break was initiated at zero seconds and CMT2 began injecting immediately as the natural circulation phase of the transient was entered. During the initial ADS blowdown phase, the reactor vessel collapsed water level dropped to the middle of the core. ACC2 began injecting around time 4 during ADS1–3 blowdown. The RPV collapsed liquid level continued to drop until IRWST injection began around time 7, thus ending the ADS blowdown phase of the transient. IRWST injection began before CMT2 was completely emptied, ensuring that makeup water was provided to the core at all times. At around time 20, the RPV liquid level began to decrease as IRWST injection flow rate decreased.

At about time 60, the primary sump valve was opened, which transitioned the plant from IRWST injection to long-term cooling. Primary sump overflow began, and water was recirculated from the sump to the IRWST, through the DVI2 line, and into the reactor vessel as the long-term cooling phase was entered. During sump recirculation, a drain at the bottom of the sump was opened to simulate a degraded sump. The presence of a degraded sump did not affect core coolability, and the core remained adequately cooled throughout the test. The core power was shown in Figure 4.5 to illustrate the standard decay power curve used in many APEX LOCA tests.

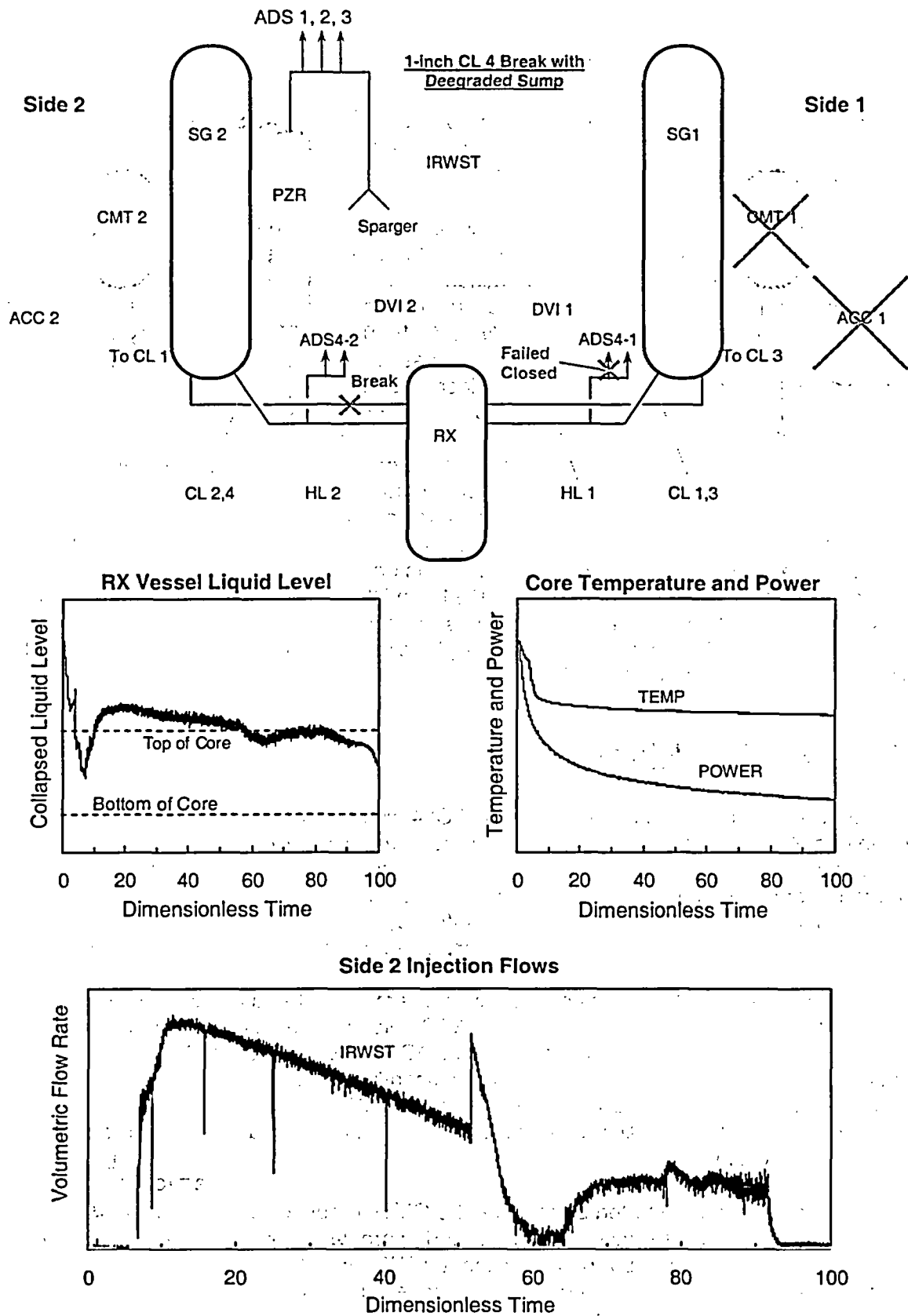


Figure 4.5 Test NRC-AP1000-04 Passive Safety System Performance.

4.6 Test NRC-AP1000-05

This test was a DEDVI line break with failure of two of the four ADS4 valves on the non-PZR side of the plant. This test was the counterpart to test NRC-AP1000-03, where two of the four ADS4 valves failed to open on the PZR side of the plant.

Figure 4.6 shows the plant configuration for this test and plots of injection flow rates (sides 1 and 2), along with reactor vessel level and core temperature. At time zero, the DVI Line 1 break was opened and the plant began to depressurize; the CMTs began injecting immediately. The plant went through the same natural circulation and ADS blowdown phases as in test NRC-AP1000-03. At around time 30 in test NRC-AP1000-05, the vessel inventory began to decrease because no injection flow was provided to the vessel. Water exiting the break and ADS4-2 line caused the vessel inventory to continue to decrease, even as the two-phase mixture level dropped below the bottom of the HL at around time 32.

Upper plenum entrainment into the HL and out the ADS4-2 line continued to deplete the reactor vessel inventory from time 30 to 40, which led to core uncover before the IRWST injection could begin. At time 40, there was an increase in core temperature and the heater rods were turned off to avoid damage. Consequently, failing closed the two ADS4 valves on the PZR side of the plant resulted in core heatup. The PZR was unable to drain during this test because of the presence of liquid entrainment out of ADS4-2 in HL2 or because of the presence of CCFL in the surge line from flow out the ADS1-3 valves. Section 5.2 of this report provides a comparison between tests NRC-AP1000-03 and 05, which explains why the core was uncovered in test NRC-AP1000-05 and not in test NRC-AP1000-03.

4.7 Test NRC-AP1000-06

This test was a 2-inch break off the bottom of CL4 with a failure of two of the four ADS4 valves on the non-PZR side of the plant. It was apparent from NRC-AP1000-05 that this type of ADS4 failure can lead to core uncover, so the purpose of this test was to determine whether moving the break from DVI1 to CL4 resulted in similar core uncover. Figure 4.7 shows the plant configuration for this test and plots passive safety system injection flow rate (side 2), along with reactor vessel level, core temperature, primary system pressure, and PZR collapsed liquid level.

As in previous tests, the break was opened at time zero. CMT1 and 2 began to inject immediately, but since the break was relatively small, the ADS setpoint (based on CMT low level) was not reached until around time 15 when the ADS1 and ADS2 valves actuated. After ADS1, 2, and 3 actuation, the total injection flow increased significantly until falling to zero by time 37, thus ending the ADS blowdown phase of the transient. The ADS blowdown phase in this test was significantly longer than the ADS blowdown phase in DVI line breaks, as would be expected from a smaller CL break.

IRWST injection had not started by the time the CMTs emptied. Without any additional safety injection, the reactor vessel water level continued to drop as a result of boiling in the core and upper plenum entrainment. Eventually, without IRWST injection, the core temperature rose as a result of boil-off of primary liquid, and a temperature excursion occurred at around time 50, similar to test NRC-AP1000-05. The heater rods were shut off to avoid damage, thus ending the test.

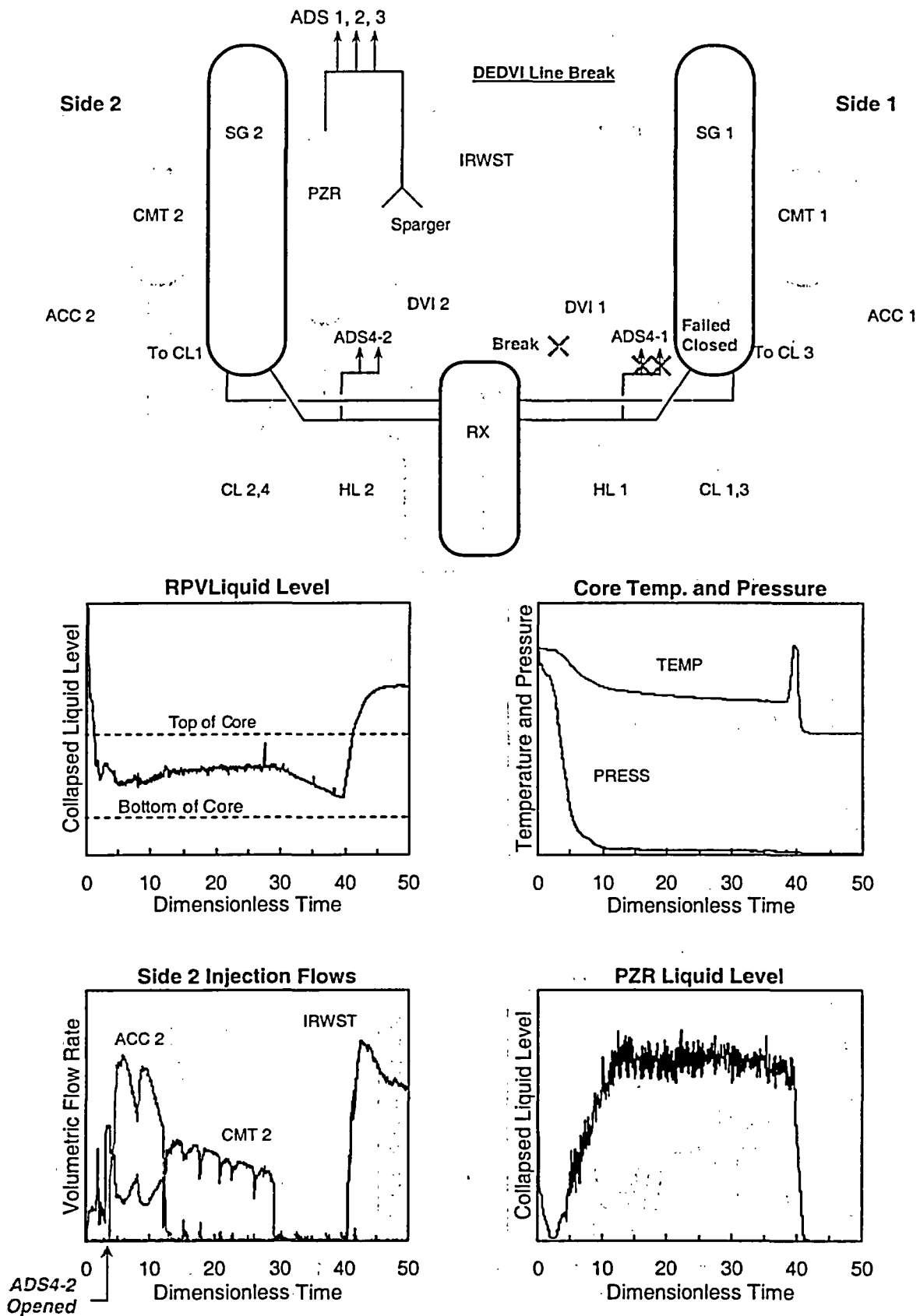


Figure 4.6 Test NRC-AP1000-05 Passive Safety System Performance.

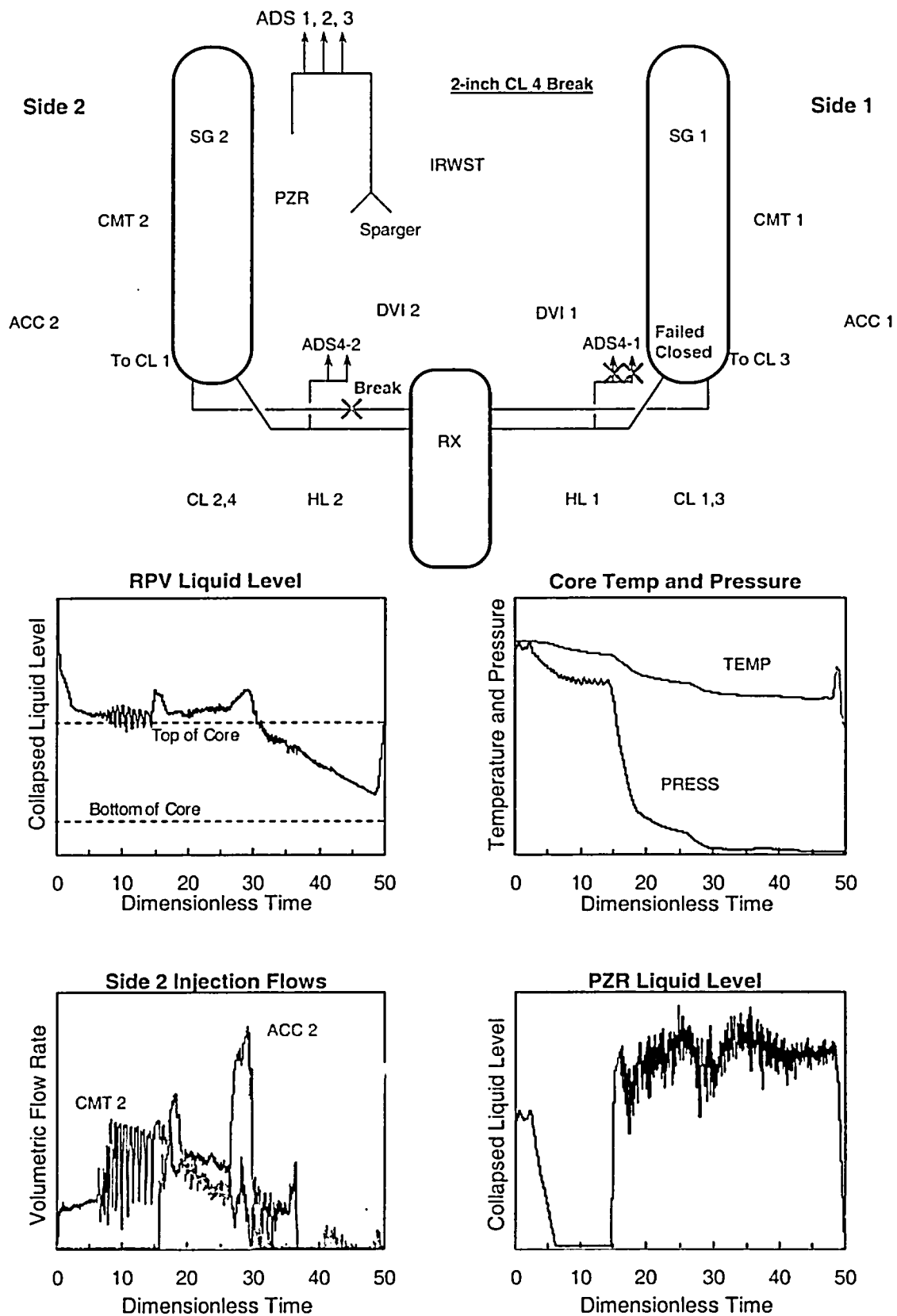


Figure 4.7 Test NRC-AP1000-06 Passive Safety System Performance.

4.8 Test NRC-AP1000-10

The objective of this test was to validate PRA assumptions with regard to multiple failures of the ADS. This test simulated a 2-inch cold leg break off the bottom of CL4. The test was initiated from normal operating temperature and pressure. For this test, ADS1–3 and one of the four ADS4 valves failed to open on the non-PZR side of the plant. The steam generator PORVs were allowed to cycle to help remove decay heat during the initial blowdown stage of the transient. The test was terminated after 30 minutes of steady-state long-term cooling.

Figure 4.8 shows the facility configuration for this test, along with figures showing the passive safety injection flow rate; RPV collapsed liquid level, and ADS4-1 and 2 flow qualities. For this test, the side 1 and side 2 injection timing and flow rates were very similar; hence, only side 2 is shown in Figure 4.8. The break was initiated at zero seconds, and the CMTs immediately began to drain. The ACCs began to inject shortly after ADS4 valve actuation at around time 3. This caused the plant to further depressurize and increased ACC injection flow rates considerably.

Between time 6 and 9, there was a noticeable oscillation of IRWST injection flow rate, core liquid level, and ADS4-2 line flow quality. By time 9, the RPV pressure was very close to atmospheric and the HLs were almost completely flooded (not shown). This oscillatory behavior is consistent with separate effects experiments run in the Air-Water Test Loop for Advanced Thermal-hydraulic Studies (ATLATS) [Ref. 4], which investigated the intermittent nature of liquid entrainment from the HLs into a vertical ADS4 line. At around time 10, only liquid exited the ADS4 valves as water from the IRWST was injected at a high rate to the core.

The RPV liquid inventory reached a maximum around time 15, and then began to slowly decrease as the IRWST injection flow rate decreased. Oscillations were experienced again from time 26 to 35. These RSOs are consistent with previous AP600 tests, and are described in Section 4.1.4 of this report. The plant entered long-cooling at time 43, when the sump recirculation lines were opened, thus ending the IRWST injection phase of the transient. No high-temperature excursion was experienced and the core remained covered and adequately cooled throughout the test.

4.9 Test NRC-AP1000-11

This test simulated a station blackout with a failure of one of the four ADS4 valves on the non-PZR side of the plant. Previous tests (NRC-AP1000-05 and 06) showed that failure of ADS4 valves on the non-PZR side of the plant are the most challenging to the AP1000 passive safety systems.

The APEX-AP1000 control logic (Appendix B) was modified to simulate a station blackout (loss of all AC power). The core operated at a reduced power (600 kW) and with a modified decay power curve to preserve the integrated core energy. The SG PORVs were set to cycle between two relatively high pressures. When the SG water level decreased to a specified level as a result of PORV cycling, an “S” signal was sent to open the CMT injection valves and the PRHR HX outlet valve. The ADS was actuated at around time 68 based on the control logic.

Figure 4.9 shows the plant configuration for this test and plots of passive safety system injection flow rates (side 2), along with reactor vessel collapsed liquid level, PZR pressure and temperature, and core temperature. For the first several hours of the station blackout test, the PORVs cycled on and off. The “S” signal was generated around time 68, and the ADS1 valve actuated. The

plant immediately began to depressurize, and the ADS control logic depressurized the plant to allow passive safety system injection. The injection flow decreased very close to zero around time 70, but only for a short while until IRWST injection began. No temperature excursion was experienced, and the core remained covered and adequately cooled throughout the test, even with one of the four ADS4 valves failing to open on the non-PZR side.

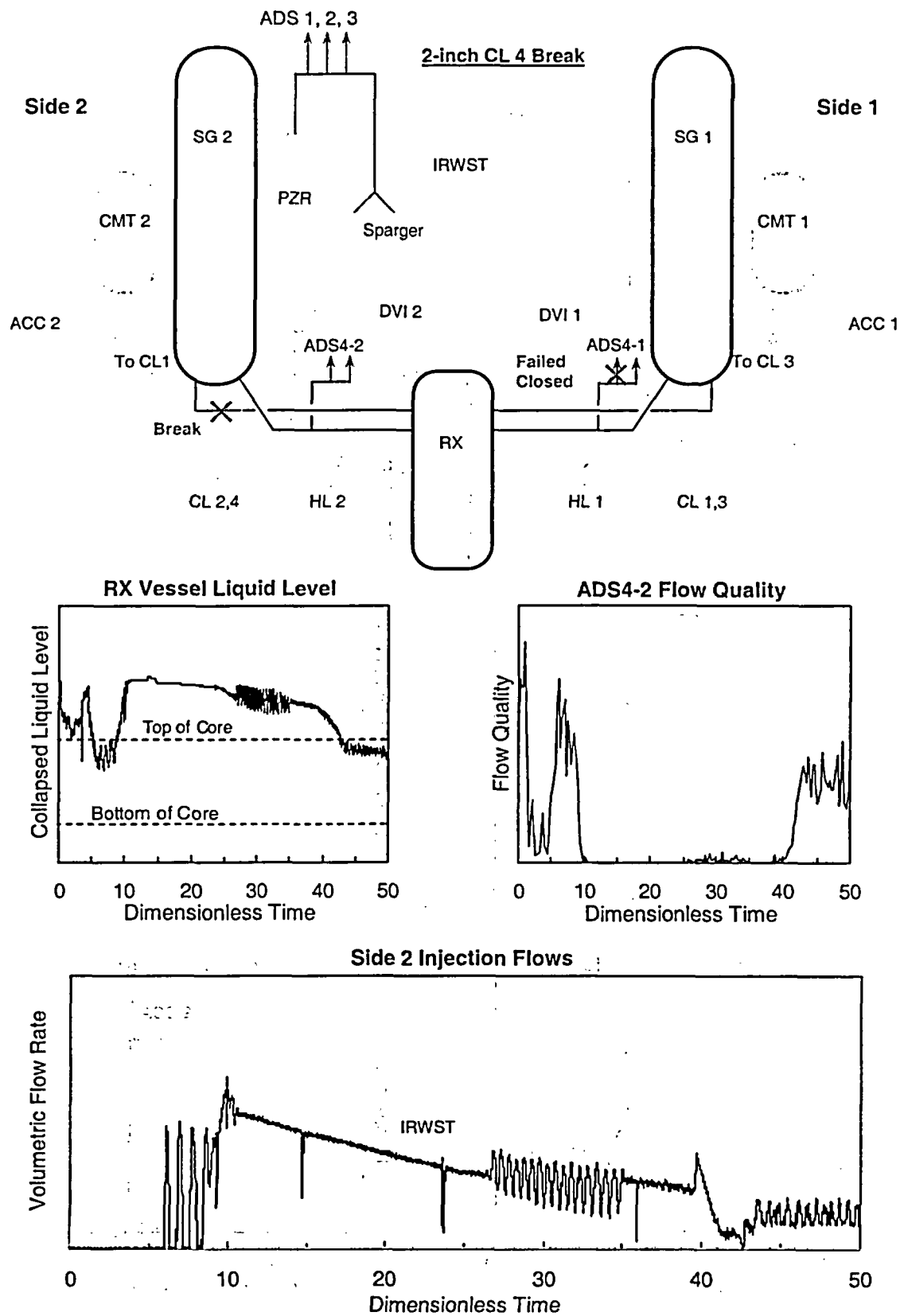


Figure 4.8 Test NRC-AP1000-10 Passive Safety System Performance.

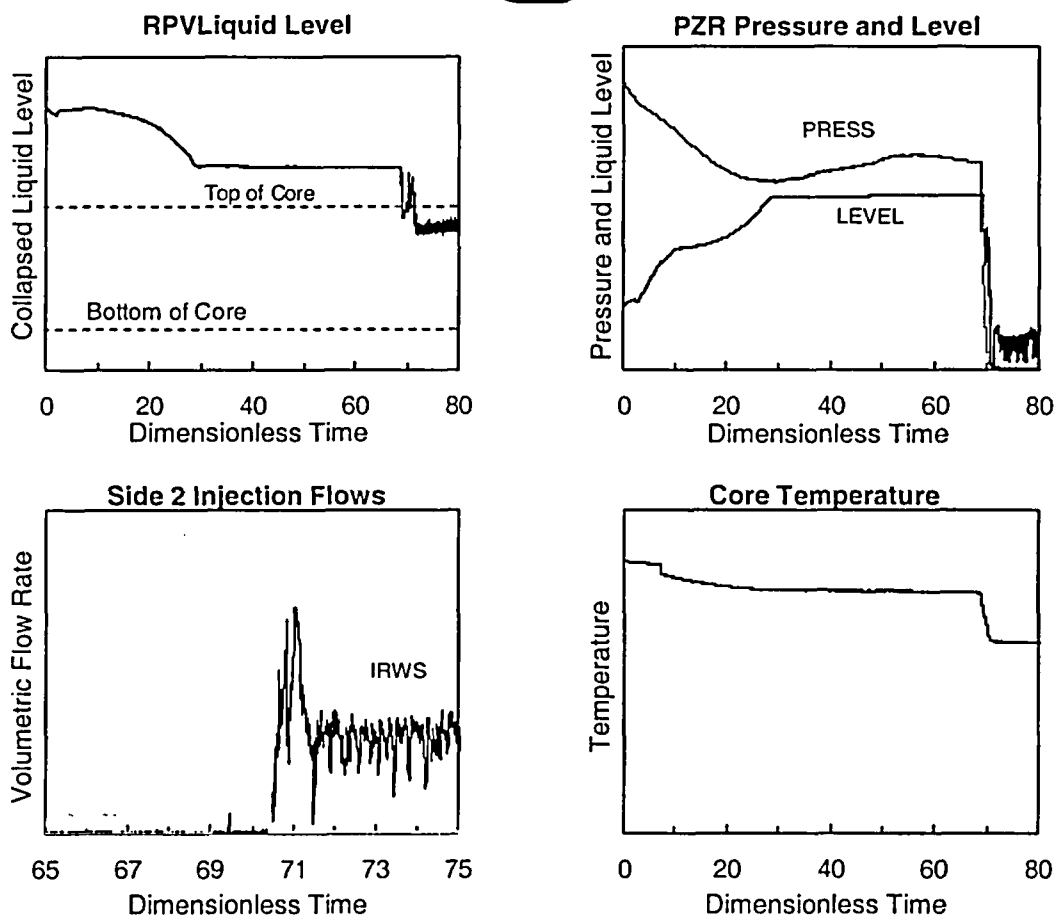
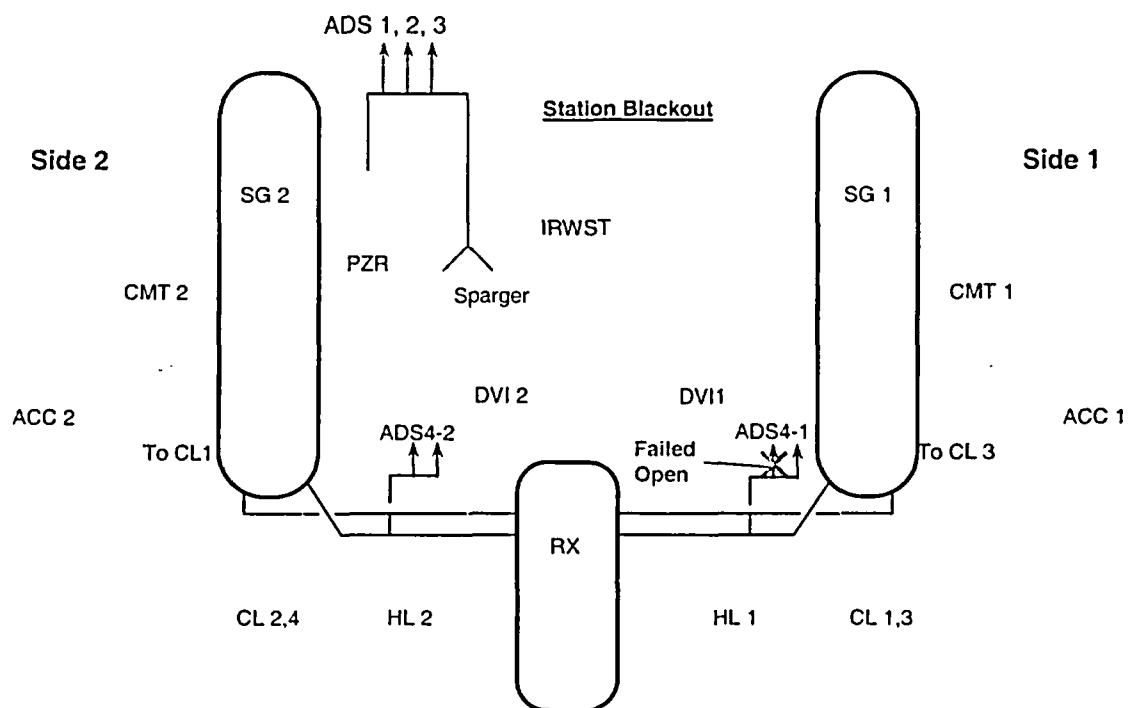


Figure 4.9 Test NRC-AP1000-11 Passive Safety System Performance.

5. COMPARISONS AND DISCUSSION

This section provides comparisons between design-basis test DBA-02 and beyond-DBA test NRC-AP1000-05, and between tests NRC-AP1000-03 and NRC-AP1000-05. The comparisons illustrate the fact that under select beyond-DBA scenarios, core uncover was experienced in APEX-AP1000, while the similar design-basis test did not lead to core uncover. In addition, comparison of beyond-DBA tests NRC-AP1000-03 and NRC-AP1000-05 helps to explain why the core uncovered when two of the four ADS4 valves were failed on the non-PZR side of the plant, compared to the same ADS4 failure on the PZR side of the plant.

5.1 Test DBA-02 versus Test NRC-AP1000-05

It is interesting to compare design-basis test DBA-02 [Ref. 5] to beyond-DBA test NRC-AP1000-05. Both tests simulated a DEDVI line break with ADS4 valve failure on the non-PZR side of the plant. The only difference between the two tests was that in DBA-02, only one of the four ADS4 valves were failed closed, while in NRC-AP1000-05, two of the four ADS4 valves were failed closed. Figure 5.1 shows a comparison of reactor vessel collapsed level for DBA-02 and NRC-AP1000-05. As previously shown in Figure 4.6, the core uncovered in NRC-AP1000-05 as a result of the increased rate at which water was entrained out of the upper plenum, into the HL, and out ADS4-2. In DBA-02, IRWST injection was significantly delayed as shown in Figure 5.2. In NRC-AP1000-05, the reactor vessel liquid level dropped fast enough and IRWST injection never began, since the heater rods were shut off around time 32 to avoid damage to the facility. It is also important to note that there existed a significant amount of time in DBA-02 (between time 23 and 28) when the reactor vessel did not receive any injection flow as shown in Figure 5.2. During this period, core cooling was maintained by boil-off of the existing vessel inventory.

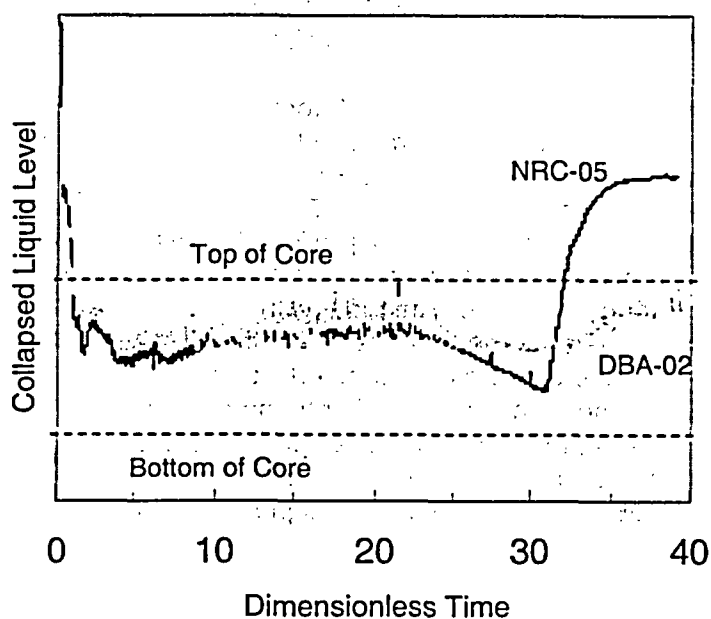


Figure 5.1 Reactor Vessel Liquid Level (DBA-02 and NRC-AP1000-05).

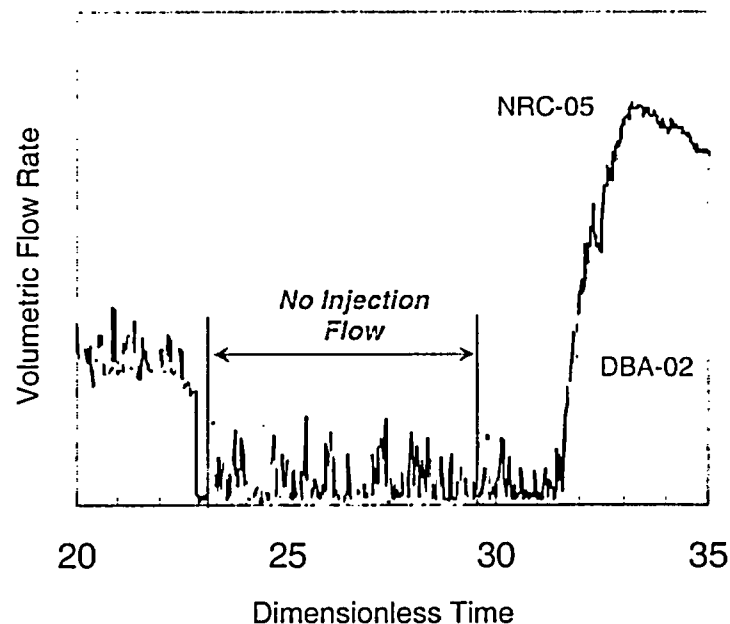


Figure 5.2 IRWST Injection Flow Rates (DBA-02 and NRC-AP1000-05).

Figure 5.3 compares the PZR water level for both tests. At around time 10, the PZR was able to drain as the plant depressurized in DBA-02, providing additional makeup water to the core, but in NRC-AP1000-05, the PZR wasn't able to drain until the heater rods were turned off at around time 30. The PZR was unable to drain in NRC-AP1000-05 because of liquid entrainment in HL2 flowing out the ADS4-2 line. This phenomenon is discussed in more detail in Section 5.2.

Examination of the ADS4-2 flow quality (Figure 5.4) for both tests shows significant liquid carryover from the reactor vessel and entrainment from the HL out the ADS4-2 line. Even after the two-phase mixture dropped below the bottom of the HL in NRC-AP1000-05 (time 25 in Figure 5.1) the ADS4-2 quality was still relatively low (~ 0.6). The primary mechanism through which water left the reactor vessel at low vessel liquid levels (liquid level below the bottom of the HLs) was upper plenum entrainment. Droplets from the two-phase reactor vessel mixture level were entrained by the steam, passed through the upper internals (with some droplets de-entraining), and entered the hot leg. From there, some droplets struck the HL pipe walls and created an annular flow of liquid out the ADS4 line or were de-entrained into the HL liquid level and entrained out the vertical ADS4 line by a mechanism of liquid entrainment in horizontal pipes with vertical-up branches [Ref. 4]. In DBA-02, there was still one operational ADS4 valve on the non-PZR side of the plant, providing another outlet for the steam. In NRC-AP1000-05, all of the steam exited the ADS4-2 line and the DEDVI break. Hence, a higher flow quality was observed in NRC-AP1000-05 than in DBA-02.

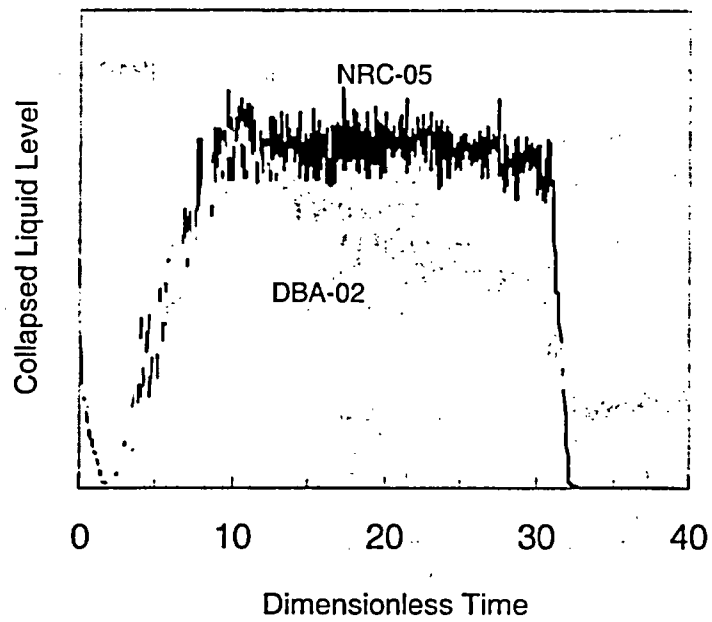


Figure 5.3 PZR Liquid Levels (DBA-02 and NRC-AP1000-05).

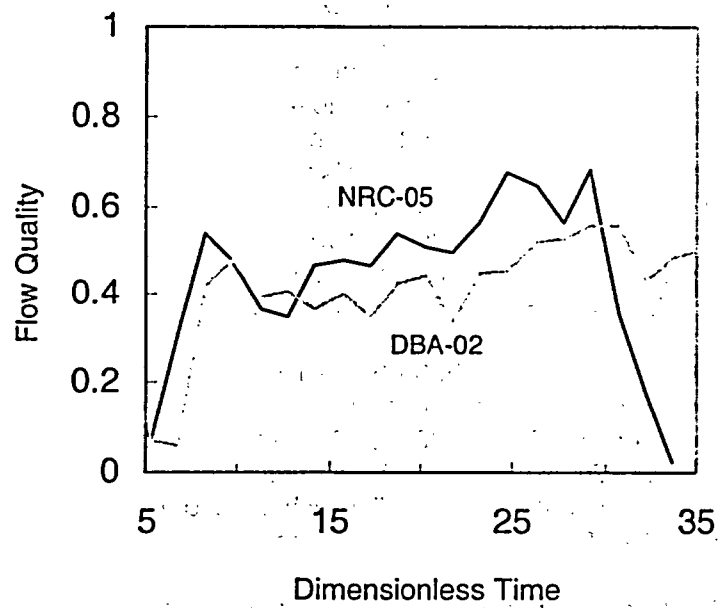


Figure 5.4 ADS4-2 Flow Qualities (DBA-02 and NRC-AP1000-05).

5.2 Test NRC-AP1000-03 versus NRC-AP1000-05

As previously shown, core uncover was experienced in NRC-AP1000-05, but not in NRC-AP1000-03. The only difference between these two DVI line break tests was the location of the ADS4 valve failures. In NRC-AP1000-03 (no core uncover), two of the four ADS4 valves were failed closed on the PZR side of the plant, while in NRC-AP1000-05 (core uncover), two of the four ADS4 valves were failed closed on the non-PZR side of the plant. As the plant went through the ADS blowdown phase of the transient, water was entrained through the ADS4-2 line in NRC-AP1000-05 and the ADS4-1 line in NRC-AP1000-03. Both tests had the exact same timing (i.e., control logic), except that the heater rods were turned off in NRC-AP1000-05 at around time 25 to avoid damage to the facility.

The pressure transient was almost exactly the same for both tests, as shown in Figure 5.5. There was a slight difference between tests NRC-AP1000-03 and NRC-AP1000-05 in system pressure at around time 10. For both tests, there was no injection flow to the core between time 17 and 25, as shown in Figure 5.6. During this time of no injection flow, the quality out of the open ADS4 valves for both tests was relatively low, ~0.6 for test NRC-AP1000-05 and ~0.4 for test NRC-AP1000-03, as shown in Figure 5.7.

As shown in Figure 5.8, the RPV collapsed liquid level began to decrease in both tests at around the same time (time 18). However, the RPV liquid level decreased faster in test NRC-AP1000-05 than in test NRC-AP1000-03. At around time 21, the two-phase mixture level in the vessel for both tests dropped below the bottom of the HL, as shown in Figure 5.9. Figure 5.10 shows an oscillation in the HL2 liquid level in both tests at about the same time the RPV two-phase mixture level dropped below the bottom of the HL. Examination of the HL1 liquid level (Figure 5.11) does not reveal any noticeable oscillations between time 21 and 25. In test NRC-AP1000-05, the liquid in HL2 was entrained out the ADS4-2 line, while no liquid was entrained out the ADS4-2 line in test NRC-AP1000-03, since it was failed closed in that test. Hence, the source of the initial oscillations in HL2 was not attributable to the presence of HL entrainment. Examination of the PZR surge line liquid level (Figure 5.12) reveals that the PZR began to slowly drain in surges during the HL2 oscillations. Therefore, the oscillations in hot leg level were attributable to the PZR draining. In addition, in test NRC-AP1000-03, the oscillations in HL2 slowly diminished over time, while they were maintained in test NRC-AP1000-05 by the presence of liquid entrainment out of ADS4-2. Figure 5.13 shows the PZR liquid level for both tests.

In summary, compared to test NRC-AP1000-03, the RPV liquid level dropped faster in test NRC-AP1000-05 because of the presence of the PZR, which enhanced liquid entrained out the open ADS4 line in test NRC-AP1000-05. As shown in Figure 5.14, IRWST injection was significantly delayed in NRC-AP1000-03, but never began in NRC-AP1000-05. (Test NRC-AP1000-05 was terminated at time 25, which caused IRWST injection to begin.) Lack of injection water from the IRWST caused the core to uncover in test NRC-AP1000-05.

In similar full-scale AP600 tests run in ROSA [Ref. 3], core uncover was not experienced. This is because the APEX facility has a reduced IRWST head, since it was scaled to one-quarter height. Hence, the delay in IRWST injection is a known conservatism in the APEX test facility.

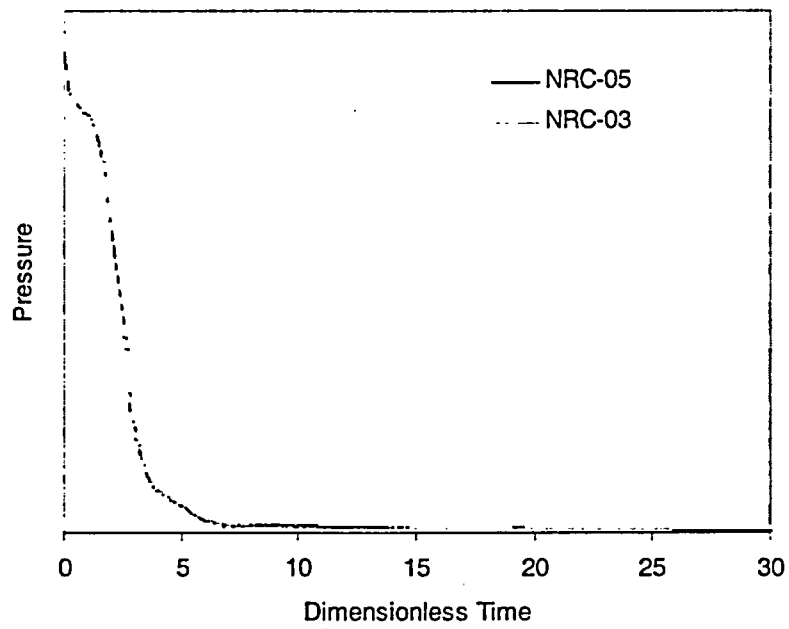


Figure 5.5 System Pressures (NRC-AP1000-03 and 05)

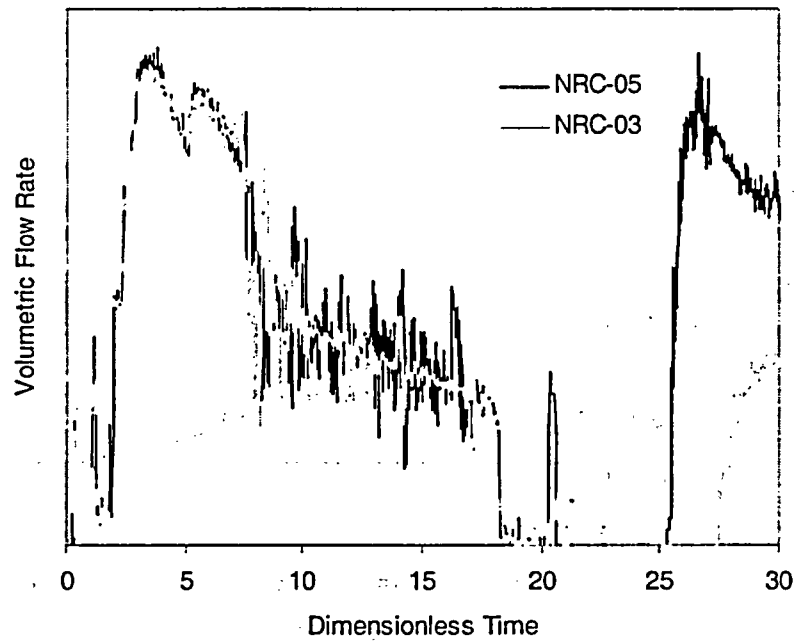


Figure 5.6 Safety Injection Flow Rates (NRC-AP1000-03 and 05)

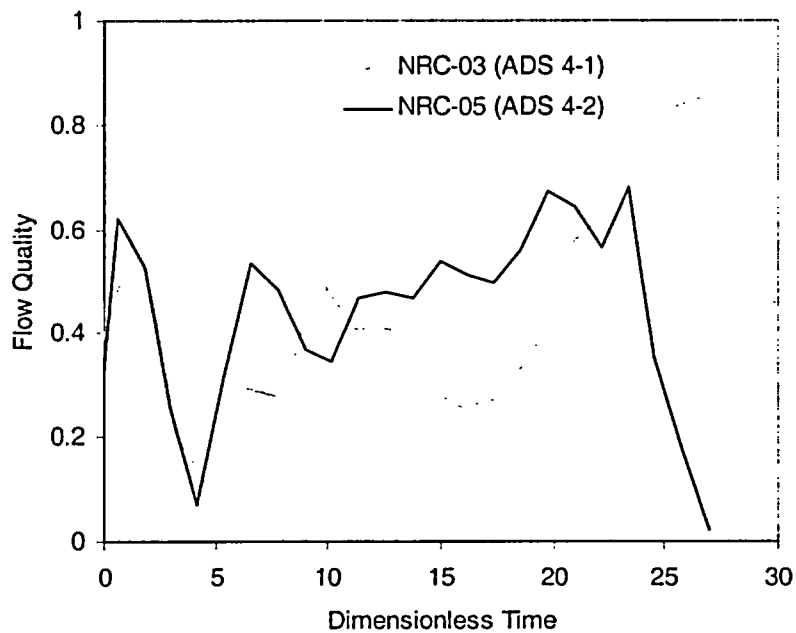


Figure 5.7 ADS4 Flow Qualities (NRC-AP1000-03 and 05)

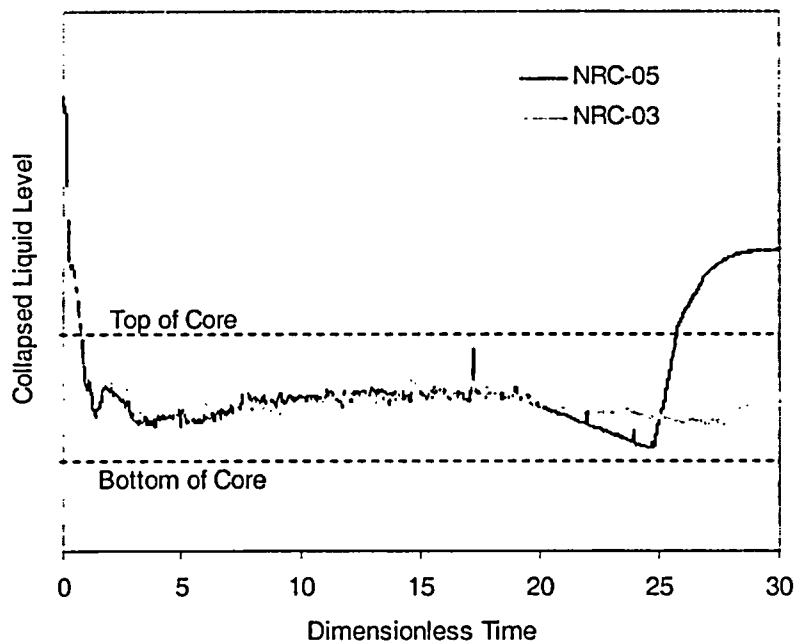


Figure 5.8 RPV Collapsed Liquid Levels (NRC-AP1000-03 and 05)

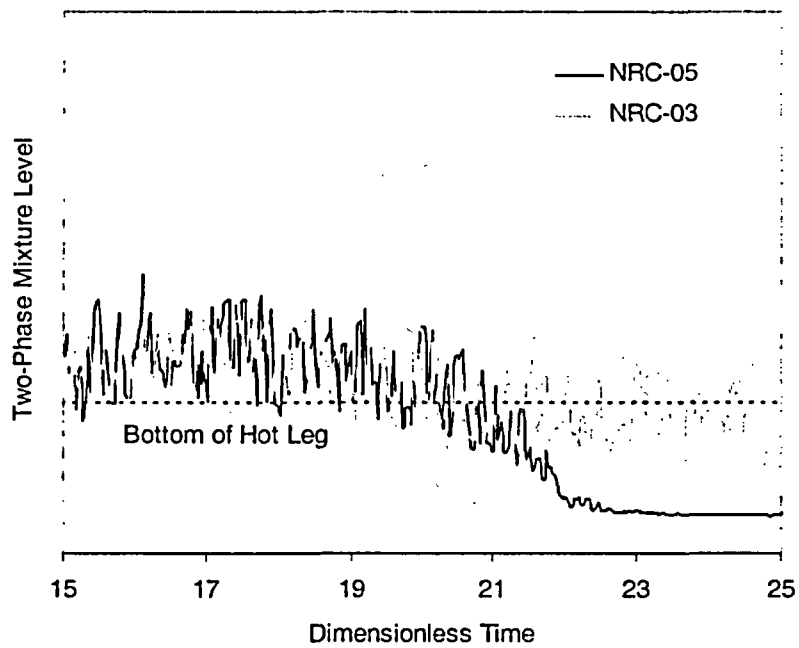


Figure 5.9 RPV Two-Phase Mixture Levels (NRC-AP1000-03 and 05)

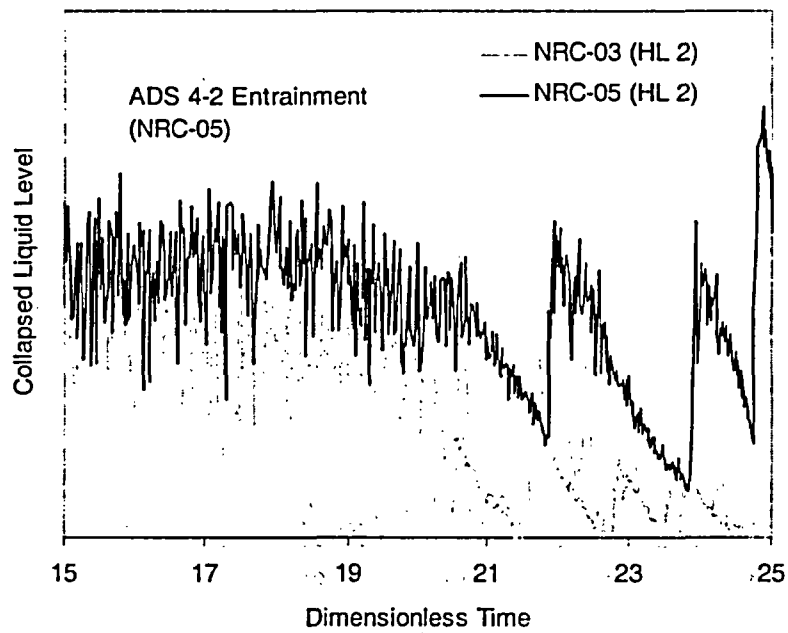


Figure 5.10 HL2 Collapsed Liquid Levels (NRC-AP1000-03 and 05)

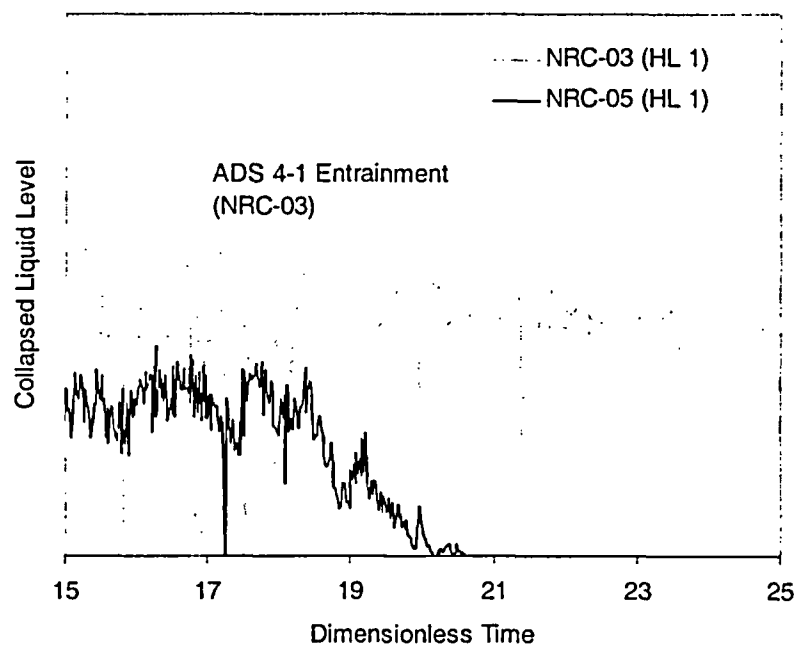


Figure 5.11 HL1 Collapsed Liquid Levels (NRC-AP1000-03 and 05)

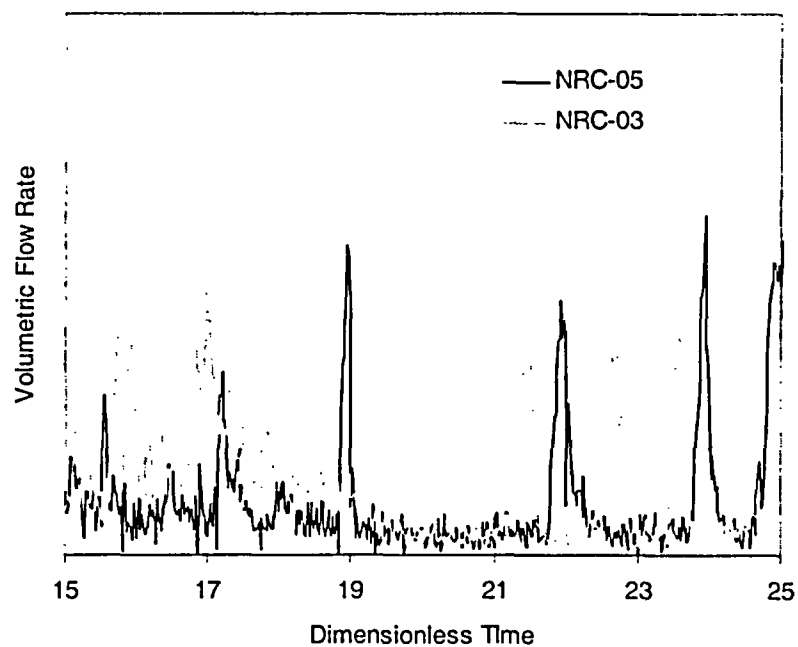


Figure 5.12 PZR Surge Line Liquid Levels (NRC-AP1000-03 and 05)

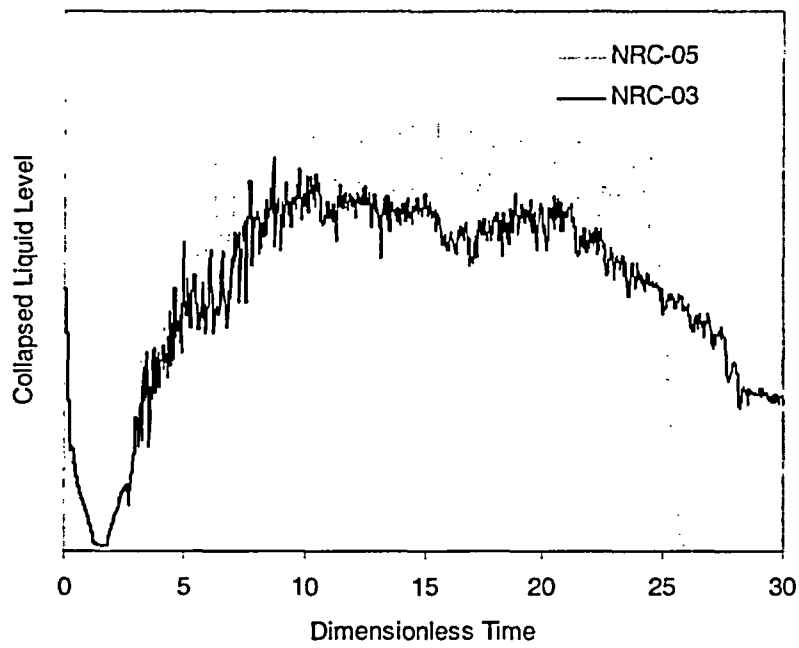


Figure 5.13 PZR Collapsed Liquid Levels (NRC-AP1000-03 and 05)

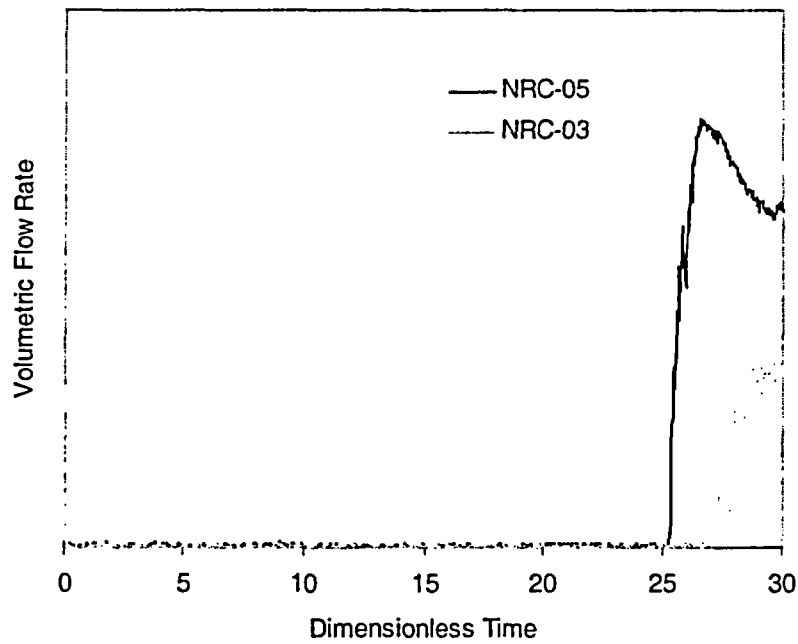


Figure 5.14 IRWST Injection Flow Rates (NRC-AP1000-03 and 05)

6. SUMMARY AND CONCLUSIONS

The APEX facility is a unique thermal-hydraulic integral system test facility used to assess the performance of passive safety systems in the Westinghouse AP600 and AP1000 designs. To address performance specific to the AP1000 design, the APEX facility underwent significant modifications in 2002 in order to more accurately represent the AP1000 reactor. Those facility modifications included an increase in the maximum core power; new PZR and surge lines; larger CMTs; larger-diameter ADS4 system piping; and decreased line resistances for the CMTs, ADS4, and PRHR HX. A comprehensive scaling analysis, performed by Reyes and presented in Appendix A, guided the facility modifications to ensure that AP1000 conditions were preserved in the APEX experiments.

The accident scenarios investigated in the APEX-AP1000 facility included 1- and 2-inch CL breaks, DEDVI line breaks, Mode 5 operation with loss of RNS cooling, and station blackout. Based on experience from analyzing previous AP600 tests, one of the main purposes of the APEX-AP1000 test program was to investigate the sensitivity of ADS failure on core coolability.

Based on the experiments run in APEX, the following conclusions can be made:

- (1) The APEX-AP1000 tests confirm significant liquid entrainment and carryover of water to the ADS4 system during and after ADS4 valve actuation.
- (2) Test results from NRC-AP1000-03, 05, and DBA-02 show that failure of ADS4 valves on the non-PZR side of the plant results in a greater delay in IRWST injection than failure of ADS4 valves on the PZR side of the plant.
- (3) Failure of two out of four ADS4 valves on the non-PZR side of the plant results in core uncover (based on the two-phase mixture level) during simulated DEDVI line and cold leg breaks.
- (4) Review of the APEX-AP1000 test results conclusively show that the core remains cooled and heatup was not experienced for most of the beyond-DBA tests.

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APPENDIX A.

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APPENDIX A. SCALING ANALYSIS

The following scaling analysis was performed by Reyes and was used to guide the APEX-AP1000 test facility modifications. The basis for the majority of this work is the original AP600 Scaling Analysis, WCAP-14270, which was performed to support the design of the existing Advanced Plant Experiment (APEX) facility at Oregon State University (OSU) [Ref. 1]. The analyses presented herein provide the scaling criteria that need to be implemented to model the AP1000 design changes in the APEX test facility. This analysis, in conjunction with the AP1000 design information, has been used to identify and guide the design modifications needed to make the APEX facility suitable for AP1000 testing.

A.1 Introduction

As part of the AP600 design certification, the APEX test facility was constructed at OSU. The APEX facility is a low-pressure, one-quarter height, integral systems test facility that can model the long-term core cooling phenomena associated with an advanced passive plant using passive safety systems. Extensive scaling studies were performed so that the AP600 thermal-hydraulic phenomena of interest would be accurately modeled in the APEX facility. The APEX facility operates at one-half time scale and at a reduced pressure and temperature scale. Using the scaled parameters, a test in the APEX facility occurs twice as fast as a transient in the actual design. A total of 28 integral system tests were successfully performed for Westinghouse and the U.S. Department of Energy in support of the AP600 design certification. In addition, a total of 47 confirmatory tests were successfully performed for the NRC.

A.1.1 Comparison of the AP600 and AP1000 Design Parameters

The most significant difference between AP600 and AP1000 is the increased core power. The reactor vessel volume remains unchanged. The SG tube surface area, PZR volume, and RCP flow have all increased to accommodate the increased core power. Table A.2 compares the changes to the passive safety system design. In particular, the volume of the CMTs and the IRWST has been increased; the flow capacity for the IRWST, ADS4, and PRHR has been increased by reducing the resistance in each line; and the PRHR surface area has also increased. The Westinghouse Plant Parameters document [Ref. 8] provides the details of the AP1000 design. Table A.1 compares the key design parameters of the AP1000 design with those of the AP600 reactor.

Table A.1 Important NSSS Design Changes [Ref. 8]

Parameter	AP600	AP1000
Reactor Core Power, MWt	1933	3400
Hot Leg Temperature, °F	600	610
Number of Fuel Assemblies	145	157
Active Fuel Length, ft	12	14
Average Linear Power, kW/ft	4.10	5.707
Average Heat Flux, Btu/(hr-ft ²)	142,869	198,933
Steam Generator Heat Transfer Area per unit, ft ²	75,180	123,538
Reactor Coolant Pump Flow, gpm	51,000	78,750
Pressurizer Volume, ft ³	1,600	2,100

Table A.2 Changes to Passive Safety System Design Features

Component	AP600	AP1000	Comment
IRWST			
Volume, ft ³	70,798	75,300	The IRWST level has been increased in the AP1000 by using more accurate level instruments. This permits a high operating level.
Water Level, ft	28.0	28.79	
Line Resistance, %	100%	32%	
Design Flow Rate, %	100%	184%	
CORE MAKEUP TANKS			
Number	2	2	The CMT volume and flow rate have been increased to provide additional safety injection flow. CMT elevations are maintained at the AP600 level. The duration of CMT injection is maintained similar to AP600.
Volume, ft ³	2000	2512	
Line Resistance, %	100%	64%	
Design Flow Rate, %	100%	124%	
ACCUMULATORS			
Number	2	2	The accumulators are the same as AP600. Accumulator sizing is based on LBLOCA performance and is determined largely on reactor vessels volume.
Volume, ft ³	2000	2000	
Pressure, psig	700	700	
AUTOMATIC DEPRESSURIZATION STAGES 1-3			
Location	Top PZR	Top PZR	The first three stages of ADS are the same as AP600. Their sizing basis is to reduce pressure to permit adequate injection from the accumulators and to permit transition to 4 th stage ADS.
Configuration	6 paths	6 paths	
Vent Area, %	100%	100%	
AUTOMATIC DEPRESSURIZATION STAGE 4			
Location	Hot Leg	Hot Leg	The ADS4 th stage vent area is increased more than the ratio of the core power. The 4 th stage ADS venting is the most important design feature to allow for stable IRWST/sump injection during long-term core cooling.
Configuration	4 paths	4 paths	
Line size	10-inch	10-inch	
Nominal Vent Area, %	100%	176%	
Line Resistance	100%	28%	
Capacity	100%	189%	

Table A.2 Changes to Passive Safety System Design Features

Component	AP600	AP1000	Comment
PASSIVE RHR HEAT EXCHANGER			
Type	C-Tube	C-Tube	The AP1000 PRHR HX retains the AP600 configuration. The heat transfer surface area is increased by extending the length of the heat exchanger. The inlet and outlet piping has been increased resulting in higher flow rates.
Surface Area, %	100%	122%	
Design Flow Rate, %	100%	174%	
Design Heat Trans., %	100%	172%	
CONTAINMENT			
Diameter, ft	130	130	The AP1000 containment volume and design pressure are increased to accommodate higher mass and energy releases.
Overall Height, ft	189.83	215.33	
Design Pressure, psig	45	59	
Net Free Volume, ft ³	173 x10 ⁶	2.07 x10 ⁶	
PASSIVE CONTAINMENT COOLING SYSTEM			
Water Storage Tank Volume (Top of Overflow), gallons	580,000	580,000	The PCS water storage tank was increased to accommodate higher flow rates. The PCS flow rates have been increased based on the increased in core power.

A.1.2 Modifications to the APEX Test Facility

Based on a review of the design changes listed in Tables A.1 and A.2, and their detailed description in the AP1000 Plant Parameters document [Ref. 8], the set of modifications listed in Table A.3 were made to APEX to best simulate AP1000 thermal-hydraulic behavior.

Table A.3 Proposed Modifications to the APEX Test Facility

Component	Modification to APEX
Reactor Power	Increase core power by 67%. (Maximum of 1 MW)
Pressurizer	Increase PZR volume. Reduce PZR surge line diameter.
Steam Generator Heat Transfer Area	No change required for testing.
Reactor Coolant Pump Flow	No change required for testing.
Core Makeup Tanks	Increase CMT volumes by 25%. Reduce line resistance to 64% of original value.
Accumulators	No changes to original design.
IRWST	Increase IRWST liquid level.
Automatic Depressurization Stages 1-3	No changes to original design.
Automatic Depressurization Stage 4	Increase ADS4 flow area by 76%. Reduce line resistance to 28% of original value.
Passive Residual Heat Removal (PRHR) Heat Exchanger (HX)	Increase PRHR flow capacity by 74% by reducing line resistance. No change in surface area/tube number required for testing.
Containment Sump Flood-Up Elevation	Change flood-up elevation in primary sump tank.
Passive Containment Cooling System	Not part of APEX testing program.

A.1.3 Rationale for APEX Modifications

This section presents the rationale for the proposed modifications. An increase in the reactor core power is needed to preserve the proper power-to-volume scaling ratio. This is a key feature of the original scaling analysis and is essential to simulating decay heat behavior, loop natural circulation and primary system depressurization rates. The APEX power increase is limited to 1 MW without having to replace the power distribution system. This power represents ~2.8% decay power for the AP1000 on a scaled basis. An increase in PZR volume is essential because it is a major source of liquid to the core during primary system blowdowns. The NRC identified a need for the reduction in PZR surge line diameter at the conclusion of the AP600 research program [Ref. 2]. This modification is needed to ensure properly scaled PZR draining behavior during primary system blowdowns, and properly scaled surge line pressure drop behavior during ADS1-3 operation.

Increases to the APEX SG tube volume and heat transfer area were not deemed necessary for several reasons. First, their tube volume is small compared to the remainder of the primary system. Second, they are oversized for the decay power operations involved in testing. That is, they have much more surface area than needed to remove core heat. One impact of not increasing the SG surface area is an increase in the core fluid temperature rise, but this is well

within the design constraints of the existing facility. The increased number of tubes, however, significantly reduces the primary loop pressure drop because of the increased number of parallel flow paths in the SG. As a result, the APEX facility is not able to match the scaled primary loop natural circulation flow rates that arise early in SBLOCA transients. However, all of the passive safety system and sump recirculation natural circulation flows can be properly scaled.

An increase in RCP flow capacity was not necessary because the pumps are tripped at the start of each transient. Their primary contribution during testing is their resistance, which will be preserved.

The CMT volumes will be increased because they are an essential part of the passive safety system response. ADS actuation is dependent on the CMT liquid volume. The CMT line resistance shall also be reduced to simulate the scaled CMT draining rates. CMT volume and flow rate are critical to the transition from ADS4 blowdown to IRWST injection. Full-pressure ADS4 blowdown transition tests are being considered.

The IRWST injection flow rate has a significant impact on core cooling. Therefore, the IRWST lines will be modified to increase their flow capacity to match the AP1000 design on a scaled basis. The onset of IRWST injection is dependent on the liquid level height in the tank. The APEX IRWST minimum liquid volume will be preserved to match the design change. However, the scaled liquid height and IRWST liquid volume cannot be exactly preserved simultaneously. The containment sump flood-up curb height will be adjusted accordingly.

The fourth-stage valves of the automatic depressurization system (ADS4) ensure that the primary system pressure will be reduced below the IRWST liquid level head so that injection can begin. The increased flow area is needed to properly simulate the AP1000 ADS4 operation. In addition, the resistance of each ADS4 line will be decreased accordingly to properly match the pressure drop behavior under non-choked flow conditions.

Increases to the PRHR heat exchanger tube volume and surface area were not deemed necessary for the experiment. As with the SG, the PRHR tube volume is small compared to the primary loop volume. Furthermore, it is oversized for the decay power operations involved in testing. That is, they have much more surface area than needed to remove core heat. The impact of not increasing the PRHR will be an increase in the core fluid temperature rise. This is well within the design constraints of the existing facility. Properly scaled natural circulation flow rates are ensured by adjusting the PRHR loop resistance.

The ADS1-3 valves and the accumulators remain the same as the original AP600 design. Therefore, these components will not be modified for the AP1000 testing program.

A.1.4 Applicability of the AP600 Scaling Analysis

The original scaling analysis performed in support of the design of the APEX test facility for AP600 certification is documented in WCAP-14270. The comprehensive report represents the first successful application of the hierarchical two-tiered scaling (H2TS) methodology for the design and construction of an experimental test facility. Westinghouse issued the report in January 1995 [Ref. 1]. The objective of the scaling study was to obtain the physical dimensions of a test facility that would simulate the flow and heat transfer behavior of importance to the AP600 passive safety system operation. The report includes all of the scaling criteria that were needed to define the geometry and operating conditions of the reduced-scale APEX test facility.

Figure A.1 shows the general scaling methodology used to design the APEX test facility for the AP600 test program. First, the general objective of the test program was stated. The general objective was to assess the passive safety system operation for loss-of-coolant-accidents (LOCAs). A small-break loss-of-coolant accident (SBLOCA) phenomena identification and ranking table (PIRT) was then developed to identify the important thermal-hydraulic phenomena that should be preserved in the test facility. The next step was to perform a scaling analysis for each of the AP600 operational modes during the LOCA. The four key modes of operation identified were natural circulation, system depressurization, venting/drainage/injection, and recirculation. The analyses resulted in a set of dimensionless groups and similarity criteria that had to be preserved in the test facility. These similarity criteria were derived from the governing equations of mass, momentum, and energy conservation for the system, subsystems, and components for each of the four operating modes. The similarity criteria were used to obtain the scaling ratios needed to design the test facility geometry and operating conditions.

As shown in Figure A.1, the scaling ratios were developed for a specific set of experiment objectives, which produce a specific set of system responses (i.e., operation modes and thermal-hydraulic phenomena) within a specific plant geometry. A review of the scaling ratios reveals that they are also directly applicable to the design of the APEX-AP1000 test facility for the following reasons.

First, the experiment objectives of the APEX-AP1000 test program are a subset of the AP600 experiment objectives. Therefore, the same operation modes and thermal-hydraulic phenomena will be produced.

Westinghouse recently issued an AP1000 PIRT and Scaling Assessment, which reviews the original scaling analysis effort and assesses the applicability of the original AP600 test program to the AP1000 design [Ref. 6]. Westinghouse concluded that the AP1000 PIRT was the same as the AP600 PIRT, with the exception of the potential higher importance of HL entrainment during the post-ADS4 actuation phases of the SBLOCA. Therefore, entrainment scaling of the post-ADS4 actuation phase was of particular interest to the present study.

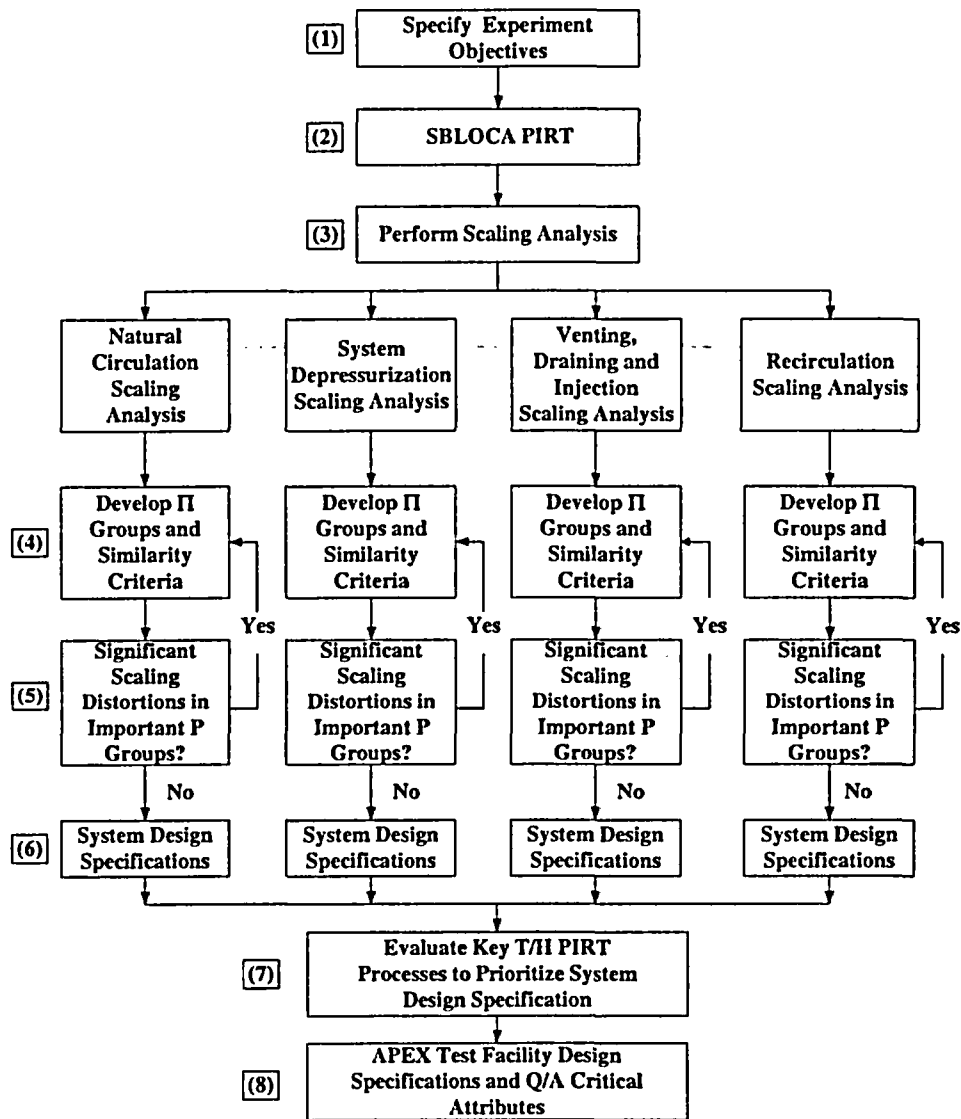


Figure A.1 General Scaling Methodology for the APEX Test Facility [Ref. 1]

Second, the AP1000 design is geometrically similar to the AP600 design. This means that there is a one-to-one correspondence of primary loop components, arranged in the same sequence, and all of the important AP1000 geometric scales, (i.e., cross-sectional flow areas, volumes, lengths) can be related to the AP600 design by constant scaling factors.

In conclusion, the general scaling methodology remains the same. Therefore, the scaling ratios obtained in the original scaling analysis, with a few exceptions, can be directly applied to the design of an APEX-AP1000 test facility. The following section describes the scope of the scaling assessment for the APEX-AP1000 test facility.

A.1.5 Scope of the Current Scaling Assessment

The following analyses have been included in the OSU APEX-AP1000 Scaling Report to guide the design of the APEX test facility modifications presented in Table A.3:

- Core Decay Power Scaling Analysis
- IRWST, CMT, and PZR Liquid Volume and Height Scaling Analysis
- IRWST, CMT, PRHR, and Sump Recirculation Line Scaling
- Pressurizer Surge Line Scaling Analysis
- RCS Depressurization Scaling Analysis
- ADS4 Blowdown Scaling Analysis
- Upper Plenum Pool Entrainment Scaling Analysis

The core decay power analysis was needed to develop the revised decay power algorithm for the tests. The original power scaling ratios were used in the decay power scaling analysis. The IRWST, CMT, and PZR volume scaling analyses were straightforward and implemented the original volume scaling ratios. Similarly, the original line resistance scaling ratios were used to scale the IRWST, CMT, PRHR, and sump recirculation line pressure drops. The PZR surge line scaling analysis represents a change to the original scaling analysis. That is, it is intended to provide a better representation of the PZR draining process. The PZR surge line scaling analysis resulted in a new diameter scaling ratio for the PZR surge line. The ADS4 blowdown scaling analysis represents an improved depressurization scaling analysis technique based on the energy equation. Of particular interest to this study, is the transition from ADS4 blowdown to IRWST injection. The upper plenum pool entrainment scaling analysis is intended to provide a better simulation of the upper plenum entrainment and de-entrainment processes. This analysis also includes an upper core plate flow area scaling analysis to better simulate counter-current flooding in the upper core plate.

A.2 Hierarchical Two-Tiered Scaling (H2TS) Methodology

The H2TS methodology was used to develop the similarity criteria necessary to scale the APEX-AP1000 systems and processes of importance to an SBLOCA transient. The H2TS methodology was developed by the NRC and is fully described in Appendix D to NUREG/CR-5809 [Ref. 9]. This is the same methodology that was used to develop the similarity criteria for the original APEX facility.

Figure A.2 is taken from NUREG/CR-5809. It presents the four basic elements of the H2TS analysis methodology. The first element consists of subdividing the plant into a hierarchy of systems. Each system was subdivided into interacting subsystems, which were further subdivided into interacting modules, which were further subdivided into interacting constituents (materials), which were further subdivided into interacting phases (liquid, vapor, or solid). Each phase could be characterized by one or more geometrical configurations, and each geometrical configuration could be described by three field equations (mass, energy, and momentum conservation equations). Each field equation could be characterized by several processes.

After identifying and subdividing the system of interest, the next step was to identify the scaling level at which the similarity criteria should be developed. This was determined by examining the phenomena being considered. For example, if the phenomenon being considered involved mass, momentum, or energy transport between materials such as water and solid particles, the scaling analysis was performed at the constituent level. If the phenomenon of interest involved mass, momentum, or energy transport between vapor and liquid, the scaling analysis was performed at the phase level. Therefore, identifying the scaling level depended on the phenomenon being addressed.

Thermal-hydraulic phenomena involving integral RCS interactions, such as primary system depressurization or loop natural circulation, were examined at the "system" level. Thermal-hydraulic phenomena, such as SG heat transfer, were examined at the "subsystem" level. Specific interactions between the steam-liquid mixture and the stainless steel structure were examined at the "constituent" level.

Chapter 3 presents the scaling analyses that were performed for the different APEX-AP1000 test facility modifications. It identifies the thermal-hydraulic phenomena of interest, the system level (i.e., control volume) at which the analysis was performed, the geometrical configuration, the applicable balance equations and the processes important to the thermal-hydraulic phenomena of interest.

The H2TS methodology required performing a "top-down" (system) scaling analysis, which examined the synergistic effects on the system caused by complex interactions between the constituents which are deemed important by the PIRT. Its purpose was to use the conservation equations at a given scaling level to obtain characteristic time ratios and similarity criteria. It also identified the important processes to be addressed in the bottom-up scaling analysis.

The H2TS methodology also required performing a "bottom-up" (process) scaling analysis, which developed similarity criteria for specific processes, such as flow pattern transitions and flow-dependent heat transfer. The focus of the bottom-up scaling analysis was to develop similarity criteria to scale individual processes of importance to system behavior as identified by the PIRT.

A.2.1 Time Ratios

The basic objective of the H2TS methodology was to develop sets of characteristic time ratios for the transfer processes of interest. This was done by writing the control volume balance equations for each constituent "k" as follows:

$$\frac{d V_k \psi_k}{dt} = \Delta [Q_k \psi_k] \pm \sum (j_{kn} A_{kn}) + S_k \quad (\text{A.1})$$

where

$$\Delta [Q_k \psi_k] = [Q_k \psi_k]_{\text{in}} - [Q_k \psi_k]_{\text{out}} \quad (\text{A.2})$$

In equation (A.1) the ψ_k term represents the conserved property; $\psi_k = \rho$, ρu or $\rho \varepsilon$ (mass, momentum, or energy per unit volume); V_k is the control volume; Q_k is the volumetric flow rate; j_{kn} is the flux of property ψ_k transferred from constituent "k" to "n" across the transfer area A_{kn} . Hence, $\Delta [Q_k \psi_k]$ represents the usual mass, momentum, or energy convection terms, and $\sum j_{kn} A_{kn}$ represents transport process terms such as condensation, and S_k represents the distributed sources, such as decay power or body forces acting internal to the control volume. Equation (A.1) can be put in dimensionless form by specifying the following dimensionless groups in terms of the constant initial and boundary conditions:

$$V_k^+ = \frac{V_k}{V_{k,0}}, \psi_k^+ = \frac{\psi_k}{\psi_{k,0}}, Q_k^+ = \frac{Q_k}{Q_{k,0}}, j_{kn}^+ = \frac{j_{kn}}{j_{kn,0}}, A_{kn}^+ = \frac{A_{kn}}{A_{kn,0}}, S_k^+ = \frac{S_k}{S_{k,0}} \quad (\text{A.3})$$

Substituting these groups into equation (A.1) yields:

$$V_{k,0} \psi_{k,0} \frac{d V_k^+ \psi_k^+}{dt} = Q_{k,0} \psi_{k,0} \Delta [Q_k^+ \psi_k^+] \pm \sum (j_{kn,0} A_{kn,0}) j_{kn}^+ A_{kn}^+ + S_{k,0} S_k^+ \quad (\text{A.4})$$

Dividing both sides of this equation by $Q_{k,0} \psi_{k,0}$ yields:

$$\tau_k \frac{d V_k^+ \psi_k^+}{dt} = \Delta [Q_k^+ \psi_k^+] \pm \sum \Pi_{kn} j_{kn}^+ A_{kn}^+ + \Pi_{sk} S_k^+ \quad (\text{A.5})$$

where the *residence time* of constituent "k" is

$$\tau_k = \frac{V_{k,0}}{Q_{k,0}} \quad (\text{A.6})$$

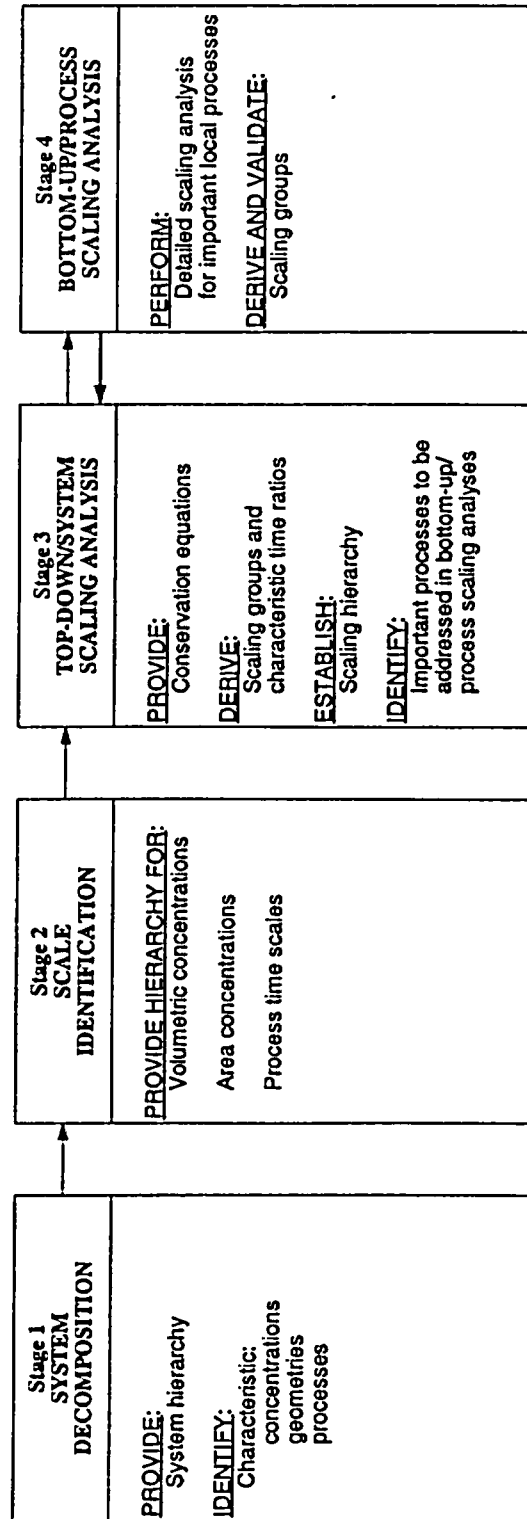


Figure A.2 Flow Diagram for the Hierarchical, Two-Tiered Scaling Analysis [Ref. 9]

and the *characteristic time ratio* for a transfer process between constituents "k" and "n" is given by:

$$\Pi_{kn} = \frac{j_{kn,0} A_{kn,0}}{Q_{k,0} \psi_{k,0}} \quad (A.7)$$

The characteristic time ratio for the distributed source term within the control volume is given by:

$$\Pi_{sk} = \frac{S_{k,0}}{Q_{k,0} \psi_{k,0}} \quad (A.8)$$

Because each transfer process has a characteristic time ratio, it is possible to rank the importance of each process by comparing the time ratios. If a specific transfer process is to have the same effect in the prototype and the model, the characteristic time ratios must be preserved.

A.2.2 Process Ranking Using Characteristic Time Ratios

Let us define $M[(P_{ij}), (P_{i+1,j}), \dots, (P_{N_i, N_j})]$ as the set of time ratios that characterize all of the individual processes that occur during the evolution of a transient. The subscripts i, j, N_i, N_j identify the specific process, the hierarchical level, the total number of specific processes, and the total number of hierarchical levels, respectively.

Because of differences in geometrical scale and fluid properties, it is impossible to exactly duplicate the "time ratio set" for the full-scale prototype, M_p , in a reduced-scale model. That is, exact similitude for all processes cannot be preserved; therefore:

$$M_p \neq M_m \quad (A.9)$$

The subscript, p , refers to the full-scale prototype and the subscript, m , refers to the reduced-scale model.

It is possible to design a reduced-scale test facility that preserves the similitude of a subset of time ratios $T[\Pi_{ij}]$, that characterize the processes of greatest importance to the transient. This optimizes the model design to investigate the important processes, while distorting the less-important processes.

To determine which processes govern the overall evolution of a transient, numerical estimates of the characteristic time ratios for the prototype and the model must be obtained for each hierarchical level of interest. Physically, each characteristic time ratio, Π_i , is composed of a specific frequency, ω_i , which is an attribute of the specific process, and the residence time constant, τ_{cv} , for the control volume. That is:

$$\Pi_i = \omega_i \tau_{cv} \quad (A.10)$$

The specific frequency defines the mass, momentum, or energy transfer rate for a particular process. The residence time defines the total time available for the transfer process to occur within the control volume. A numerical value of:

$$\Pi_i < 1 \quad (A.11)$$

means that only a small amount of the conserved property would be transferred in the limited time available for the specific process to evolve. As a result, the specific process would not be important to the overall transient. A numerical value of:

$$\Pi_i \geq 1 \quad (\text{A.12})$$

means that the specific process evolves at a high enough rate to permit significant amounts of the conserved property to be transferred during the time period, τ_{cv} . Such processes would be important to the overall transient behavior.

A.2.3 Scaling Criteria Development

The scaling analysis results in a set of characteristic time ratios (dimensionless Π groups) and similarity criteria for each mode of operation. Because it is impossible to identically satisfy all of the similarity criteria simultaneously, the set only includes those criteria that must be satisfied in order to scale the most important phenomena identified by the PIRT.

Scaling criteria were developed by requiring that the characteristic time ratios for a subset of specific processes in the prototype (usually those of greatest importance) are matched in the model at each hierarchical level. That is,

$$T \{ \Pi_i \}_m = T \{ \Pi_i \}_p \quad (\text{A.13})$$

These criteria were satisfied by adjusting the physical geometry, fluid properties, and operating conditions of the model, thereby optimizing the model design for the specific process of interest.

A.2.4 Evaluation of Scale Distortion

The scaling criteria were evaluated to determine if the scale model geometry, boundary conditions, or operating conditions would introduce significant scaling distortions. Distortions were also evaluated relative to other modes of operation.

The effect of a distortion in the model for a specific process can be quantified as follows:

$$DF = \frac{[\Pi_i]_p - [\Pi_i]_m}{[\Pi_i]_p} \quad (\text{A.14})$$

The distortion factor, DF, physically represents the fractional difference in the amount of conserved property transferred through the evolution of a specific process in the prototype to the amount of conserved property transferred through the same process in the model during their respective residence times. A distortion factor of zero would indicate that the model ideally simulates the specific process. A distortion factor of +0.05 would indicate that the specific process in the model transfers 5 percent less of the conserved property (on a scaled basis) than the same process in the prototype. The distortion factor can also be written as:

$$DF = 1 - [\omega_i]_R [\tau_{cv}]_R \quad (\text{A.15})$$

or

$$DF = 1 - [II_i]_R \quad (A.16)$$

The degree to which a specific transfer process could impact a particular transient can be determined by comparing the *maximum* characteristic time ratio for each of the transfer processes that arise during the transient.

Upon satisfying the important scaling criteria, the component geometries and operating conditions were specified for the APEX-AP1000 test facility.

A.3 Scaling Analysis for the APEX-AP1000 Modifications

This chapter presents the scaling analyses performed to obtain the component geometries and system operating conditions for the APEX-AP1000 test facility. Tables A.4 and A.5 present the scaling ratios that were derived in WCAP-14270 and used for the design of the APEX-AP1000 test facility modifications.

Table A.4 APEX-AP1000 Primary Loop Scaling Ratios from WCAP-14270 [Ref. 1]

Parameter	Desired Scaling Ratio
CORE	a,b,c
Length Ratio	
Flow Area Ratio	
Fluid Velocity Ratio	
Power Ratio	
Fluid Residence Time Ratio	
Mass Flow Ratio	
Volume Ratio	
Power/Volume Ratio	
HOT AND COLD LEGS	
Length Ratio	
Diameter Ratio	
Flow Area Ratio	
Volume Ratio	
Fluid Velocity Ratio	
Fluid Residence Time Ratio	
Mass Flow Ratio	
PRESSURIZER	
Volume Ratio	
Liquid Height Ratio	

Table A.5 APEX-AP1000 Passive Safety System Scaling Ratios
from WCAP-14270

Parameter	Desired Scaling Ratio	a,b,c
CORE MAKEUP TANK		
Length Ratio		
Flow Area Ratio		
Draining Mass Flow Rate Ratio		
Volume Ratio		
ACCUMULATOR		
Volume Ratio		
Mass Flow Ratio		
IRWST		
Length Ratio		
Flow Area Ratio		
Draining Mass Flow Rate Ratio		
Volume Ratio		
LOWER CONTAINMENT SUMPS		
Length Ratio		
Flow Area Ratio		
Draining Mass Flow Rate Ratio		
Volume Ratio		

The horizontal HL and CL scaling ratios were established based on preserving flow regime transitions in the legs.

The 1:2 time scaling requirement has been imposed on all of the system components and operations. The scaling ratios presented in Tables A.4 and A.5 have been applied in the following sections to obtain the revised APEX component geometries as needed to match the new AP1000 design.

A.3.1 Core Decay Power and Flow Area Scaling Analysis

One of the key changes to the AP1000 is the increase in core thermal power from 1,933 MW thermal to 3,400 MW thermal. Three modifications were made to the APEX test facility as a result of the power change:

- A higher power core was installed.
- The core flow area was adjusted.
- The decay power algorithm was modified.

A.3.1.1 Maximum Core Power

Based on the power scaling ratio given in Table A.4, the new core power needed in APEX to match a 3% decay power in the AP1000 was:

(A.17)

This resulted in a desired power in APEX of 1.06 MW thermal. A new 48 rod bundle core with a []^{a,b,c} thermal power was installed. This represents a []^{a,b,c} decay power.

A.3.1.2 Core Flow Area

Based on the core flow area ratio given in Table A.4, the new core flow area needed in APEX to properly match the scaled core flow area in AP1000 was:

(A.18)

The AP1000 effective core flow area is []^{a,b,c}. Using the scaling ratio in equation (A.18), the desired APEX-AP1000 core flow area is []^{a,b,c} or []^{a,b,c}. Using 48 heaters, each having a []^{a,b,c} diameter, results in an actual core flow area of []^{a,b,c}.

A.3.1.3 Decay Power Algorithm

Establishing the initial conditions for ADS4 operation and long-term cooling requires that the total energy input into the system, to the point of reaching the transition pressure be properly scaled. The integrated core power ratio is written as follows:

$$E_{\text{core,R}} = \frac{\int_0^{t_m} q_{\text{core,m}} dt_m}{\int_0^{t_p} q_{\text{core,p}} dt_p} \quad (\text{A.19})$$

where t_m is the time it takes in APEX-AP1000 to reach the ADS4 opening pressure, and t_p is the time it takes in AP1000 to reach the ADS4 opening pressure. Since the ideal core power scaling ratio given in Table A.4 is []^{a,b,c} and the ideal time scaling ratio is 1:2, the integrated core power ratio should be []^{a,b,c}.

The 1979 Decay Heat Standard for Light-Water Reactors was used to model the decay power curve for the AP1000 [Ref. 11]. Figure A.3 shows the decay power algorithm for the APEX-AP1000 test facility. The power algorithm is designed to match the ideally scaled AP1000 decay power after ~160 seconds. Similarly, as shown in Figure A.4, the total integrated decay power matches after 160 seconds.

a,b,c



Figure A.3 Comparison of the APEX-AP1000 Decay Power Algorithm and the Ideally Scaled AP1000 Decay Power Curve

a,b,c

Figure A.4 Comparison of the APEX-AP1000 Integrated Decay Power
to the Ideally Scaled AP1000 Decay Power

A.3.2 IRWST, CMT, Sump, and Pressurizer Geometric Scaling Analysis

Table A.6 presents the results of applying the scaling ratios of Table A.5 to the AP1000 IRWST, CMT, sump, and PZR.

Table A.6 Results of IRWST, CMT, Sump, and Pressurizer Geometry Scaling

Parameter	Scaling Ratio	AP1000*	APEX Ideal	APEX Actual	Units	AP1000*	APEX Ideal	APEX Actual	Units	a,b,c
IRWST Liq. Volume (min.)										
IRWST Liq. Level (min.)										
IRWST Liq. Surface Area										
IRWST Level Setpoint for Sump Recirculation										
IRWST Liq. Head on DV										
CMT Volume										
CMT Internal Diameter										
CMT Internal Height										
CMT Volume for ADS-1 Actuation										
CMT Volume for ADS4 Actuation										
Sump Liq. Volume Below DVI Elevation										
Difference Between DVI and Sump Flood-up Elevations**										
Sum Liq. Surface Area										
Pressurizer Volume										
Pressurizer Liq. Volume										
Pressurizer Inside Diameter										

* AP1000 Plant Parameters Document [Ref. 8]

** Assumes break occurs in loop compartment

A.3.3 ADS4, IRWST, CMT, PRHR, and Sump Recirculation Line Scaling

A detailed analysis of the pressure drops in the passive safety system balance and injection lines was provided in Section A.7 of WCAP-14270 [Ref. 1]. The pressure drop for a section of pipe having a constant diameter is given by the following equation:

$$\Delta P = \frac{1}{2} \left(\frac{f l}{D} + K \right) \rho v^2 \quad (\text{A.20})$$

where f is the Darcy friction factor, l/D is the piping length to diameter ratio, K is the form loss coefficient due to fittings and bends, and v is the fluid velocity in the section of pipe. For single-phase, non-choked, fluid flow with fluid property similitude, the ratio of the model to the prototype can be written as:

$$\Delta P_R = F_{T,R} v_R^2 \quad (\text{A.21})$$

In this equation, $F_{T,R}$ is the ratio of the total friction and form loss coefficients. To preserve the line pressure drops, it is required that the pressure drop ratio, ΔP_R , be 0.25 and that the velocity ratio, v_R , be 0.5. Substituting these scaling ratios into the equation above yields the following requirement:

$$F_{T,R} = 1 \quad (\text{A.22})$$

For the piping under consideration, the form loss coefficients, K , dominate. That is, the presence of valves, elbows, and other fittings make the value of K much larger than the value of f/D . In light of this fact, the line resistance can be adjusted using a flow orifice.

The AP1000 line resistance data, R (ft/gpm²), is expressed in terms of head loss over the square of volumetric flow rate. That is, the line resistance is expressed in terms of measured quantities as follows:

$$R = \frac{g_c \Delta P}{g \rho Q^2} \quad (\text{A.23})$$

The resistance is related to the friction and form loss factors as follows:

$$R = \frac{1}{2} \left(\frac{f l}{D} + K \right) \frac{1}{a^2} \quad (\text{A.24})$$

where a is the flow area of the pipe. Therefore, the units of line resistance are often expressed as 1/ft⁴. The flow area scaling ratio is given as 1:48. Therefore, the line resistance scaling ratio for single-phase fluid under non-choked flow conditions is given as:

$$R_R = 48^2 = 2304 \quad (\text{A.25})$$

Table A.7 lists the range of line resistance values required for the IRWST and sump recirculation lines in the APEX-AP1000 test facility. Table A.8 presents similar values for the CMT and PRHR lines.

The ADS4/HL nozzle diameter and resistance was scaled as with previous lines. However, the two ADS4 branch lines that comprise a single ADS4 train on a HL require a different scaling approach because the intent is to model two ADS4 branch lines with a single line in the APEX-AP1000 test facility. That is, the flow area of one APEX ADS4 branch line must equal the scaled flow area of two AP1000 branch lines:

$$a_{\text{APEX}} = \frac{2a_{\text{AP1000}}}{48} \quad (\text{A.26})$$

In terms of a diameter scaling ratio, the ratio of a single ADS4 branch line diameter in APEX to a single ADS4 branch line in the AP1000 is:

$$D_{\text{ADS,R}} = \frac{1}{\sqrt{24}} \quad (\text{A.27})$$

Table A.9 presents the ADS4 line diameters and resistance assuming that two AP1000 ADS4 branch lines are modeled with a single branch line in APEX.

Table A.7 IRWST and Sump Recirculation Line Resistance Values (ft/gpm²) [Ref. 8]

Path/Line	AP1000				IDEAL APEX			
	I.D. (In)	Min	Nom	Max	I.D. (In)	Min	Nom	Max
IRWST TO SUMP TEE								
Line A								
Line B								
SUMP TEE TO MOV ISOLATION VALVE								
Line A								
Line B								
MOV ISOLATION VALVE TO CHECK SQUIB VALVE								
Line A								
Line B								
CHECK/SQUIB VALVES PARALLEL PATHS								
Line A								
Line B								
CHECK/SQUIB VALVES TO DVI INJECTION LINE TEE								
Line A								
Line B								
IRWST INJECTION LINE TO DVI NOZZLE								
Line A								
Line B								
SUMP RECIRC. PATH TO IRWST INJECTION LINE TEE								
Line A								
Line B								
IRWST DRAIN TO CONTAINMENT								
Line A								
Line B								

a,b,c

Table A.8 CMT and PRHR Line Resistance Line Values (ft/gpm²) [Ref. 8]

Component	AP1000				IDEAL APEX				a,b,c
	I.D. (in)	Min	Nom	Max	I.D. (in)	Min	Nom	Max	
CORE MAKEUP TANK									
CL Balance Line									
CMT to ACC Tee									
ACC to DVI									
PRHR									
RCS HL to ADS4 Reducer									
ADS4 Reducer to PRHR Reducer									
PRHR Reducer to PRHR HX Inlet									
PRHR HX Inlet									
PRHR HX Tube									
PRHR HX Outlet									
PRHR HX Outlet to SG									

Table A.9 ADS-4 Line Resistance Values(ft/gpm²) [Ref. 8]

ADS4	AP1000				IDEAL APEX				a,b,c
	I.D. (in)	Min	Nom	Max	I.D. (in)	Min	Nom	Max	
ADS4/HL Nozzle									
ADS4 Branch Line									
ADS4-1 (50%)									
ADS4-1 100%)									
ADS4-2 (50%)									
ADS4-2 (100%)									

A.4 Pressurizer Surge Line Scaling

This section represents a change to the original PZR surge line scaling analysis presented in WCAP-14270, which focused on preserving the two-phase flow regime transitions. However, a recent NRC analysis performed by Bessette and Di Marzo suggests that preserving the PZR draining behavior is more important to the outcome of SBLOCA transients [Ref. 2]. Based on a thorough review of the NRC analysis, the PZR surge line was modified to properly simulate the AP1000 PZR draining behavior.

Bessette and Di Marzo expressed the governing momentum balance equation for the PZR surge line filling and draining process, in dimensionless form, as follows:

$$\dot{Z} \left| \dot{Z} \right| + AZ = B \quad (\text{A.28})$$

where:

$$A = \frac{\frac{C}{\rho g} + 1}{\frac{\Phi_{LO}^2 \left(\frac{S_{PZR}}{S_{SL}} \right)^2 \left(f \frac{L}{D} + K \right)}{2}} \quad (\text{A.29})$$

$$B = \frac{\frac{C}{\rho g} - \frac{P_{PZR}}{\rho g H_{PZR}} - (1 - \alpha) \frac{H_{SL}}{H_{PZR}}}{\frac{\Phi_{LO}^2 \left(\frac{S_{PZR}}{S_{SL}} \right)^2 \left(f \frac{L}{D} + K \right)}{2}} \quad (\text{A.30})$$

and

$$C = \rho g \frac{S_{PZR}}{S_{SL}} \quad (\text{A.31})$$

Integrating equation (A.28) yields the PZR surge line filling and draining period:

$$\tau_{SL} = 2 \left(\frac{H_{PZR}}{g} \right)^{1/2} \left[\left(\frac{B^{1/2}}{A} \right)_{\alpha=0} + \left(\frac{B^{1/2}}{A} \right)_{\alpha=0.8} \right] \quad (\text{A.32})$$

For the APEX-AP1000, a 1:2 scale time period is required. Preserving a one-half time scale PZR surge line filling and draining period requires that:

$$(H_{PZR})_R^{1/2} = \frac{1}{2} \quad (\text{A.33})$$

and that:

$$\left(\frac{B^{1/2}}{A} \right)_R = 1 \quad (\text{A.34})$$

The APEX-AP1000 PZR liquid height, H_{PZR} , is []^{a,b,c}. Therefore, the scaling criterion given by equation (A.33) is met.

Table A.10 presents the results obtained for equation (A.34). The value is close to unity. It has been assumed that the ratio of the Martinelli-Nelson two-phase flow multiplier, Φ_{LR} , is unity.

In addition to preserving the surge line drain and fill rates, it is desired that the pressure drop ratio in the surge line be []^{a,b,c}. That is:

(A.35)

This requires:

(A.36)

As shown in Table A.10, for the line size selected, the friction factor ratio is []^{a,b,c} and the velocity ratio in the surge line is []^{a,b,c}. This yields the desired DP ratio of []^{a,b,c}.

Table A.10 Results of Pressurizer Surge Line Scaling Analysis

Parameter	AP1000	APEX	a,b,c
Roughness (in)			
ID (in)			
Relative Roughness			
Reynolds Number			
Friction Factor			
Calculated Pressure Drop Ratio			
Friction Factor Ratio			
(fL/d) Ratio			
Pressurizer ID (in)			
$H_{PZR(n)}$			
Head at 1 atm (ft)			
HsL (ft)			
A_R (Bessette & di Marzo)			
B_R (Bessette & di Marzo)			
$(B_R)^{1/2}/A$			

A.5 Reactor Coolant System Depressurization Scaling Analysis

This section presents a revised depressurization scaling analysis for the APEX-AP1000 test facility. It represents a more comprehensive analysis than that presented in the original WCAP-14270. Figure A.5 presents the scaling analysis flow diagram for primary system depressurization. First, the governing set of equations for the depressurization of a two-phase fluid system was developed. This resulted in obtaining a depressurization rate equation. Next, a top-down system level scaling analysis was performed for the RCS, assuming multiple vent and injection paths. This included the development of scaling criteria for sizing the break and ADS flow areas. Last, a bottom-up analysis was performed to describe the scaling of local transport processes, such as the critical flow through the breaks and ADS valves.

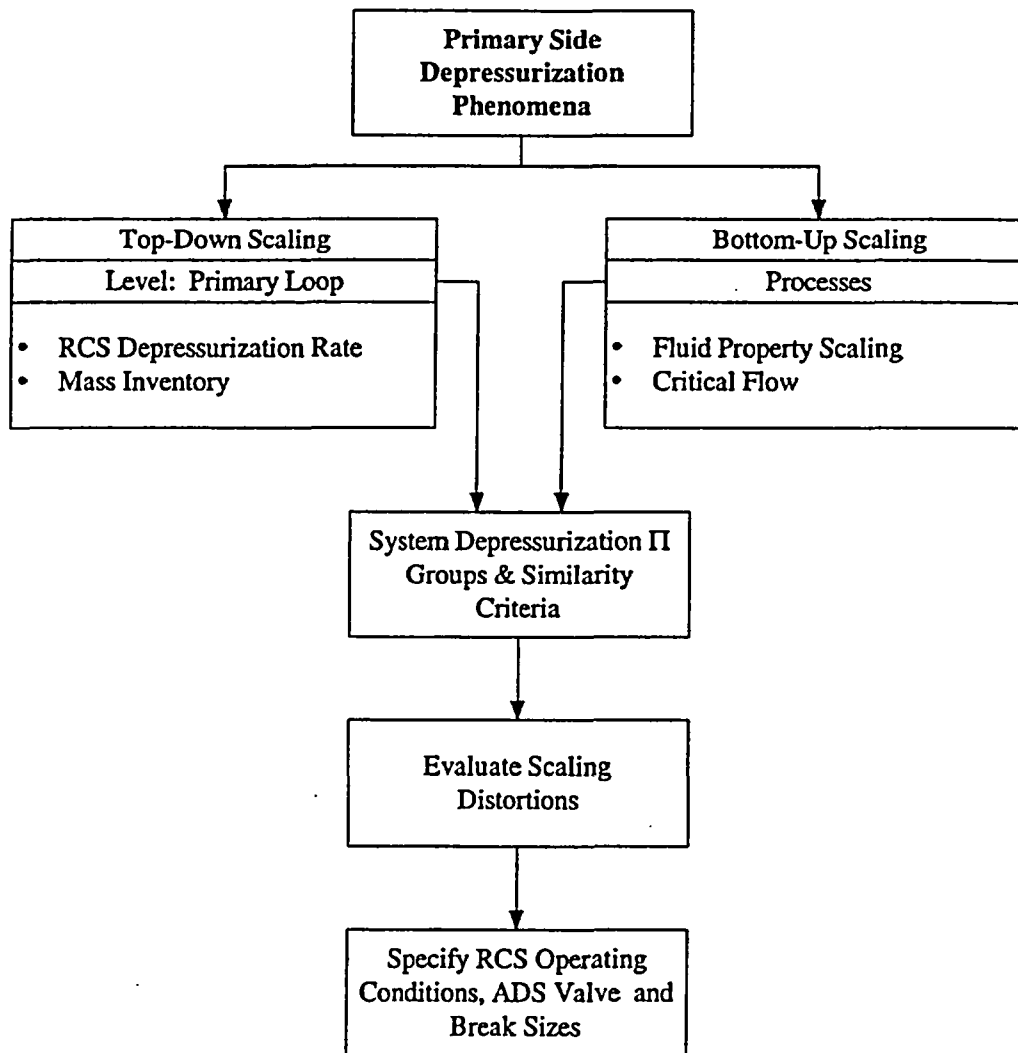


Figure A.5 Flow Chart of the Primary Side Depressurization Scaling Analysis

A.5.1 Reference Pressure for LOCA Transients

A variety of primary loop blowdown tests will be performed in APEX. The integral system tests will be performed under pressure-scaled conditions to observe all of the passive safety system functions. A series of *full-pressure* tests shall also be performed to examine the transition from ADS4 operation to IRWST injection.

Figure A.6 presents typical trends for the RCS and SG pressures during a SBLOCA transient in the APEX facility. The opening of a break is immediately followed by a period of subcooled blowdown, during which the primary system depressurizes to a pressure equivalent to the SG PORV setpoint. Hence, the primary and secondary system pressures will meet at the onset of saturation conditions in the primary as shown in the figure. The AP600 scaling analysis was the first research to recognize that the onset of primary loop saturation offered a common reference point for the purpose of scaling. This fact, coupled with the concept that the depressurization of systems under phase equilibria conditions exhibits self-similarity, offered the possibility of performing pressure-scaled testing.

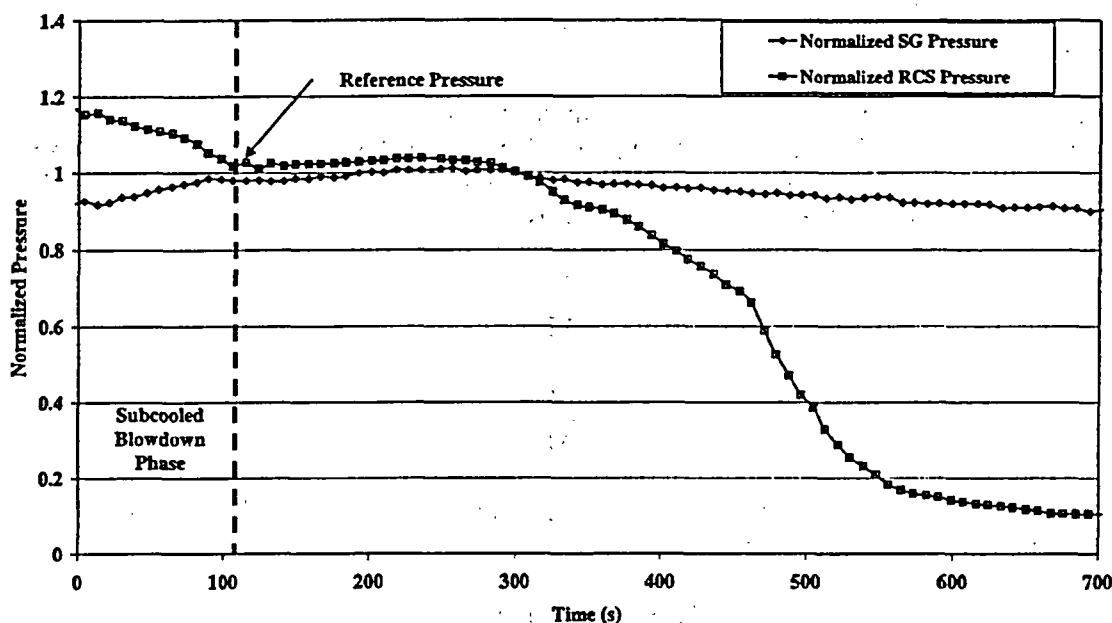


Figure A.6 Primary and Secondary Side Pressures During a Typical 2-Inch Break LOCA in APEX

For the AP1000, the reference pressure for the onset of saturation conditions in the primary loop coincides with the SG PORV pressure setpoint of 1,200 psia. For the APEX-AP1000, this value will be set at 345 psia. The goal of the pressure-scaled testing is to provide the full range of passive safety system behavior for a given transient in the proper event sequence. This data can be used to benchmark the thermal-hydraulic safety analysis codes. However, by scaling the break and ADS1-3 flow areas relative to the saturation reference pressure, the timing of the subcooled blowdown portion of the transient will not proceed at one-half time scale. For rapid blowdowns, such as the DEDVI line break, this effect is negligible. This was demonstrated by the excellent comparisons obtained between the APEX and the full-pressure ROSA AP600 DEDVI tests.

The AP600 test program revealed that the transition from ADS4 operation to the start of IRWST injection was important to core cooling. Therefore, this test program will include a series of full-pressure ADS4 blowdown tests to carefully examine the ADS4 transition under prototypic fluid pressures and temperatures.

A.5.2 Governing Equations for RCS Two-Phase Fluid Depressurization

The mass conservation equation for an RCS control volume undergoing a depressurization event is given by:

$$\frac{dM}{dt} = \sum \dot{m}_{in} - \sum \dot{m}_{out} \quad (A.37)$$

where M is the fluid mass within the RCS and \dot{m} represents the mass flow rate entering or leaving the RCS. The energy conservation equation for the RCS fluid is expressed as follows:

$$\frac{dU}{dt} = \sum (\dot{m}h)_{in} - \sum (\dot{m}h)_{out} + q_{SG} + q_{core} + q_{loss} - P \frac{dV}{dt} \quad (A.38)$$

where U is the bulk internal energy of the fluid within the RCS; h is the enthalpy of the fluid entering or leaving the RCS; q_{SG} , q_{core} and q_{loss} are the SG energy transfer rate, core power, and heat loss, respectively; P is the RCS pressure; and V is the RCS volume. The specific internal energy and specific volume are defined, respectively, as follows:

$$e = \frac{U}{M} \quad (A.39)$$

$$v = \frac{V}{M} \quad (A.40)$$

The total change in specific internal energy is written in terms of partial differentials with respect to pressure and specific volume, as follows:

$$de = \left(\frac{\partial e}{\partial P} \right)_v dP + \left(\frac{\partial e}{\partial v} \right)_P dv \quad (A.41)$$

Substituting equation (A.39) into (A.38) yields:

$$\frac{dMe}{dt} = \sum (\dot{m}h)_{in} - \sum (\dot{m}h)_{out} + q_{SG} + q_{core} + q_{loss} - P \frac{dV}{dt} \quad (A.42)$$

Expanding the term on the left-hand side of equation (A.42), substituting equation (A.37), and rearranging yields:

$$M \frac{de}{dt} = (\sum \dot{m}_{in}) (h_{in} - e) - (\sum \dot{m}_{out}) (h_{out} - e) + q_{SG} + q_{core} + q_{loss} - P \frac{dV}{dt} \quad (A.43)$$

In equation (A.43), it has been assumed that h_{in} is the same for all the injection locations, and h_{out} is the same for all the vent paths. Substituting equation (A.41) into (A.43), and rearranging yields:

$$M \left(\frac{\partial e}{\partial P} \right)_v \frac{dP}{dt} = (\sum \dot{m}_{in})(h_{in} - e) - (\sum \dot{m}_{out})(h_{out} - e) + q_{SG} + q_{core} + q_{loss} - P \frac{dV}{dt} - M \left(\frac{\partial e}{\partial v} \right)_p \frac{dv}{dt} \quad (A.44)$$

Using equation (A.40) and the mass conservation equation, the last term on the right-hand side of equation (A.44) is written as:

$$M \left(\frac{\partial e}{\partial v} \right)_p \frac{dv}{dt} = \left(\frac{\partial e}{\partial v} \right)_p \frac{dV}{dt} - v \left(\frac{\partial e}{\partial v} \right)_p (\sum \dot{m}_{in} - \sum \dot{m}_{out}) \quad (A.45)$$

Substituting back into equation (A.44) yields:

$$M \left(\frac{\partial e}{\partial P} \right)_v \frac{dP}{dt} = (\sum \dot{m}_{in}) \left[h_{in} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] - (\sum \dot{m}_{out}) \left[h_{out} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] + q_{SG} + q_{core} + q_{loss} - \left[P + \left(\frac{\partial e}{\partial v} \right)_p \right] \frac{dV}{dt} \quad (A.46)$$

which is the "depressurization rate equation." For the RCS control volume, which has rigid boundaries, equation (A.46) becomes:

$$M \left(\frac{\partial e}{\partial P} \right)_v \frac{dP}{dt} = (\sum \dot{m}_{in}) \left[h_{in} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] - (\sum \dot{m}_{out}) \left[h_{out} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] + q_{SG} + q_{core} + q_{loss} \quad (A.47)$$

The net energy transfer rate is given as:

$$q_{net} = q_{SG} + q_{core} + q_{loss} \quad (A.48)$$

Equation (A.47) is the governing equation for depressurization behavior in the RCS.

A.5.3 Top-Down Reactor Coolant System Depressurization Scaling Analysis

The mass conservation equation, equation (A.37), is expressed in dimensionless form by dividing each term by its respective initial condition and further dividing by the mass flow rate of the fluid leaving the break. This results in the following dimensionless mass balance equation:

$$\tau_{RCS} \frac{dM^+}{dt} = \Pi_m \sum \dot{m}_{DVI}^+ - \sum \dot{m}_{Brk}^+ \quad (A.49)$$

where the superscript "+" indicates normalization with respect to initial conditions. The residence time constant, (τ_{RCS}), for the depressurization transient is given by:

$$\tau_{RCS} = \frac{M_o}{\sum \dot{m}_{Brk,o}} \quad (A.50)$$

and the characteristic time ratio is given by:

$$\Pi_m = \frac{\sum \dot{m}_{DVI,o}}{\sum \dot{m}_{Brk,o}} \quad (A.51)$$

Π_m is the system mass flow rate ratio. For a constant injection flow rate, Π_m represents the total liquid mass injected into the RCS during the residence time (τ_{RCS}).

Equation (A.47) can be expressed in dimensionless form by dividing each term by its respective initial condition. The normalized terms are as follows:

$$M = M_o M^+ \quad (A.52)$$

$$P = P_o P^+ \quad (A.54)$$

$$q_{net} = q_{net,o} q_{net}^+ \quad (A.53)$$

$$\sum \dot{m}_{DVI} = \sum \dot{m}_{DVI,o} \sum \dot{m}_{DVI}^+ \quad (A.55)$$

$$\sum \dot{m}_{Brk} = \sum \dot{m}_{Brk,o} \sum \dot{m}_{Brk}^+ \quad (A.56)$$

$$\left[h_{DVI} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] = \left[h_{DVI} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o \left[h_{DVI} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]^+ \quad (A.57)$$

$$\left[h_{Brk} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] = \left[h_{Brk} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o \left[h_{Brk} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]^+ \quad (A.58)$$

Substituting these equations into (A.47) and dividing through by

$\dot{m}_{Brk,o} \left[h_{Brk} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o$ yields the dimensionless depressurization rate equation:

$$M^+ \left(\frac{\partial e}{\partial P} \right)_v^+ \tau_{RCS} \frac{\partial P^+}{\partial t} = \frac{\Pi_h}{\Pi_\epsilon} \Sigma \dot{m}_{DVI}^+ \left[h_{DVI} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]^+ - \frac{\Sigma \dot{m}_{Brk}^+}{\Pi_\epsilon} \left[h_{Brk} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]^+ + \frac{\Pi_\Gamma}{\Pi_\epsilon} q_{net}^+ \quad (A.59)$$

where the characteristic time ratios are given by:

$$\Pi_h = \frac{\Sigma \dot{m}_{DVI,o} \left[h_{DVI} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o}{\Sigma \dot{m}_{Brk,o} \left[h_{Brk} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o} \quad (A.60)$$

$$\Pi_\Gamma = \frac{q_{net,o}}{\Sigma \dot{m}_{Brk,o} \left[h_{Brk} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o} \quad (A.61)$$

$$\Pi_\epsilon = \epsilon_o = \frac{p_o \left(\frac{\partial e}{\partial P} \right)_{v,o}}{\left[h_{Brk} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o} \quad (A.62)$$

Π_h is the energy flow rate ratio. It represents the ratio of the total energy change due to fluid injection to the energy change caused by the break flow. Π_Γ is the power ratio. It represents the ratio of the net heat into the system to the rate of fluid energy transport through the break. Π_ϵ is the fluid mixture dilation property group.

Equation (A.62) reveals that the fluid dilation property group couples the system intensive energy change to the intensive energy at the break. For high pressure systems venting to ambient, the fluid properties at the break are determined at critical flow conditions.

Evaluating the RCS time constant, τ_{RCS} , and the dimensionless groups Π_m , Π_h , Π_n requires knowledge of the pressure-scaled fluid properties and the critical mass flux. These parameters are evaluated in the bottom-up scaling analysis that follows.

A.5.3.1 *Similarity of Pressure Trajectories in Dimensionless Phase Space*

One of the goals of the test program is to operate the APEX facility such that the pressure trends that evolve in APEX for a given scenario would be the same for a similar scenario in AP1000 when the results are plotted in dimensionless phase space. That is, plotting scenario pressure histories as P/P_o versus t/τ_{RCS} , or P/P_o versus M/M_o , would yield overlaying curves for the two facilities. This condition can be achieved by satisfying the following requirements:

The scenarios are initiated from the same initial condition in dimensionless phase space. In this case P^* at $t^*=0$, is 1. The rate of change, (i.e., slope), is preserved in dimensionless phase space. This imposes the following scaling criterion:

$$\left(\frac{dP^*}{dt^*} \right)_R = 1 \quad (A.63)$$

Satisfying the requirement given by equation (A.63) means preserving the dimensionless Π groups on the right-hand side of equation (A.59). If the two requirements listed above are satisfied, the following is true:

$$\left(\frac{P}{P_o} \right)_{APEX} = \left(\frac{P}{P_o} \right)_{AP1000} \quad (A.64)$$

This means that the dimensionless pressure at any point along the scenario trajectory will be the same in APEX and AP1000.

Figure A.7 shows how the saturation pressures in APEX would relate to the saturation pressures in AP1000. In this figure, P_o for AP1000 is 8.27 MPa (1200 psia), while P_o for APEX is 2.36 MPa (342 psia). These pressures correspond to the turbine bypass pressure relief setpoints on the secondary side.

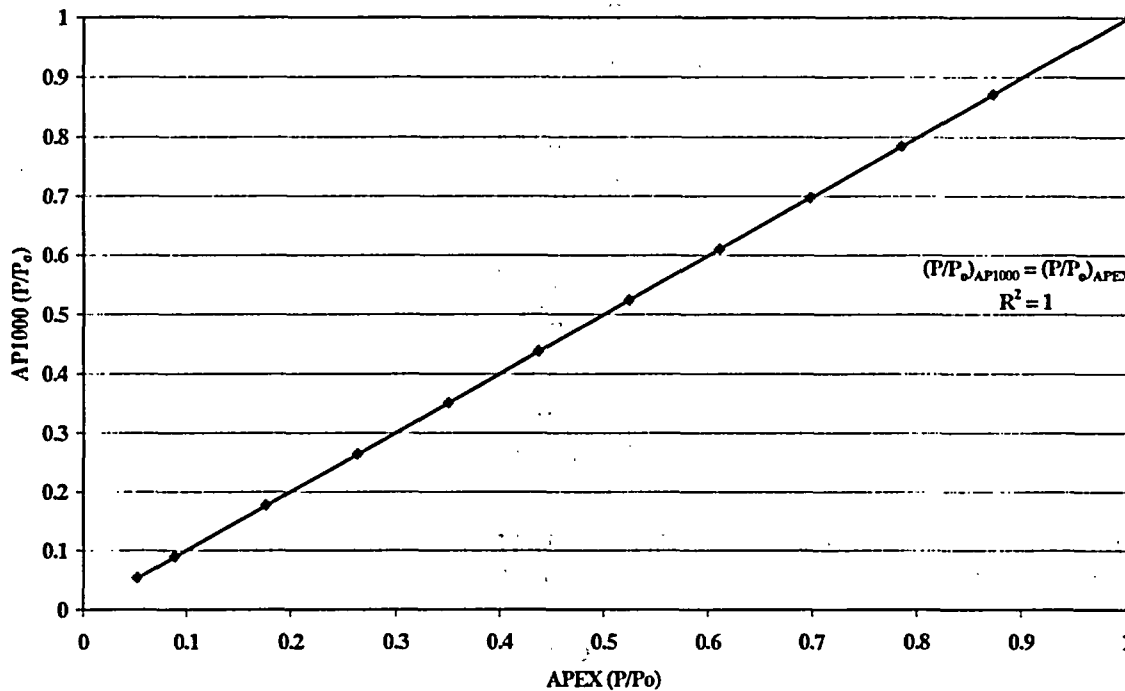


Figure A.7 Scaling Relationship Between AP1000 and APEX Saturation Pressure

A.5.4 Bottom-Up Scaling Depressurization Scaling Analysis

The objective of the bottom-up scaling analysis was to obtain the closure relations needed to evaluate the scaling ratios developed through the top-down analysis. These closure relations are dependent on fluid properties. Therefore, the first step in the bottom-up analysis was to develop the method to relate fluid properties in AP1000 to those at reduced pressure in APEX.

A.5.4.1 Self-Similarity of Fluid Properties in Phase Equilibria (P_{sat} Scaling)

The equation of state for many of the important thermodynamic properties, $\psi(P)$, of the saturated fluid can be described by a simple power function as follows:

$$\psi = \psi_o \left(\frac{P}{P_o} \right)^\xi \quad (A.65)$$

where ψ_o can be evaluated at an arbitrary reference pressure, P_o , within the range of applicability of equation (A.65) and ξ is an empirically determined constant. For saturated water, having a pressure between atmospheric and approximately 15 MPa (2175 psia), the following thermodynamic properties are well-correlated by equation (A.65) as demonstrated in Figures A.8 through A.11.

$$\frac{Pv_{fg}}{h_{fg}} = \left(\frac{Pv_{fg}}{h_{fg}} \right)_o \left(\frac{P}{P_o} \right)^{0.11} \quad (\text{A.66})$$

$$s_f = s_{f,o} \left(\frac{P}{P_o} \right)^{0.20} \quad (\text{A.67})$$

$$v_g = v_{g,o} \left(\frac{P}{P_o} \right)^{-1.02} \quad (\text{A.68})$$

$$v_{fg} = v_{fg,o} \left(\frac{P}{P_o} \right)^{-1.06} \quad (\text{A.69})$$

The form of equation (A.65) has the special property of being "invariant" with respect to a two-parameter transformation in scale. That is, rescaling the variables such that:

$$\psi = C_1 \psi^* \quad (\text{A.70})$$

$$\psi_o = C_1 \psi_o^* \quad (\text{A.71})$$

$$P = C_2 P^* \quad (\text{A.72})$$

$$P_o = C_2 P_o^* \quad (\text{A.73})$$

where C_1 and C_2 are constants, and substituting these rescaled variables into equation (A.65) yields:

$$\psi^* = \psi_o^* \left(\frac{P^*}{P_o^*} \right)^{\frac{1}{2}} \quad (\text{A.74})$$

The form of the equation of state remains unchanged. This type of transformation is known as a "stretching" or "similarity" transformation. The special feature of invariance with scale implies that the points and slopes of any curves in the (ψ, P) phase space can be related to corresponding points and slopes in the (ψ^*, P^*) phase space [Ref. 12]. This type of scale invariance is known as "self-similarity." Self-similarity can be defined as a repetition of detail at descending scales. If the dimensionless pressure ratios are preserved in the scale model, self-similarity dictates that the dimensionless fluid properties (ψ/ψ_o) will also be preserved.

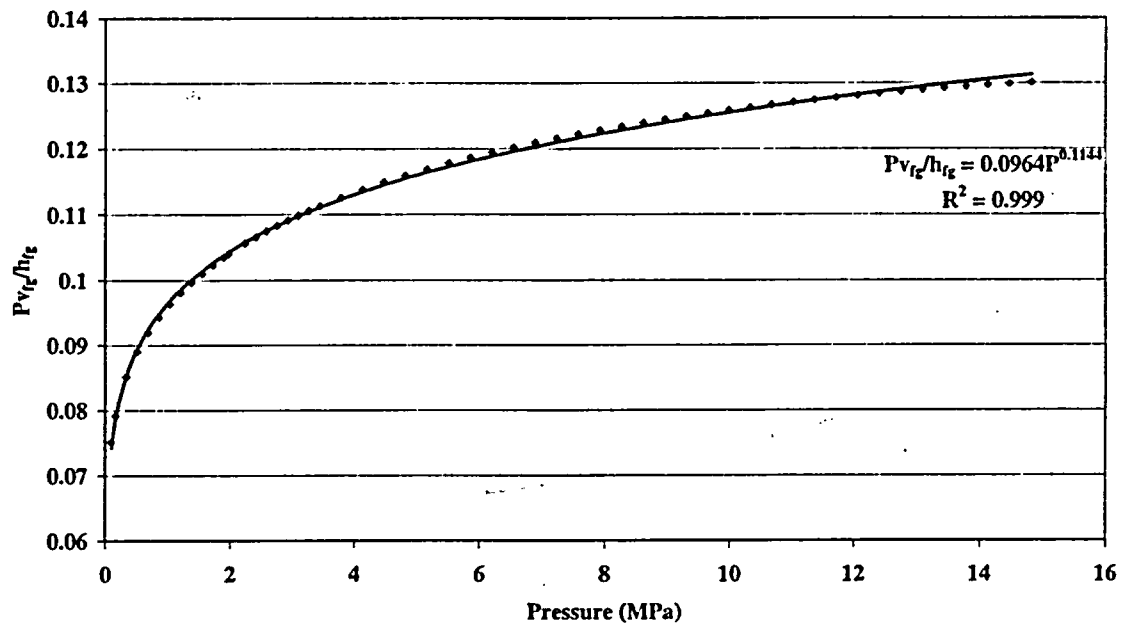


Figure A.8 Power Law for Pv_{fg}/h_{fg} as a Function of Pressure

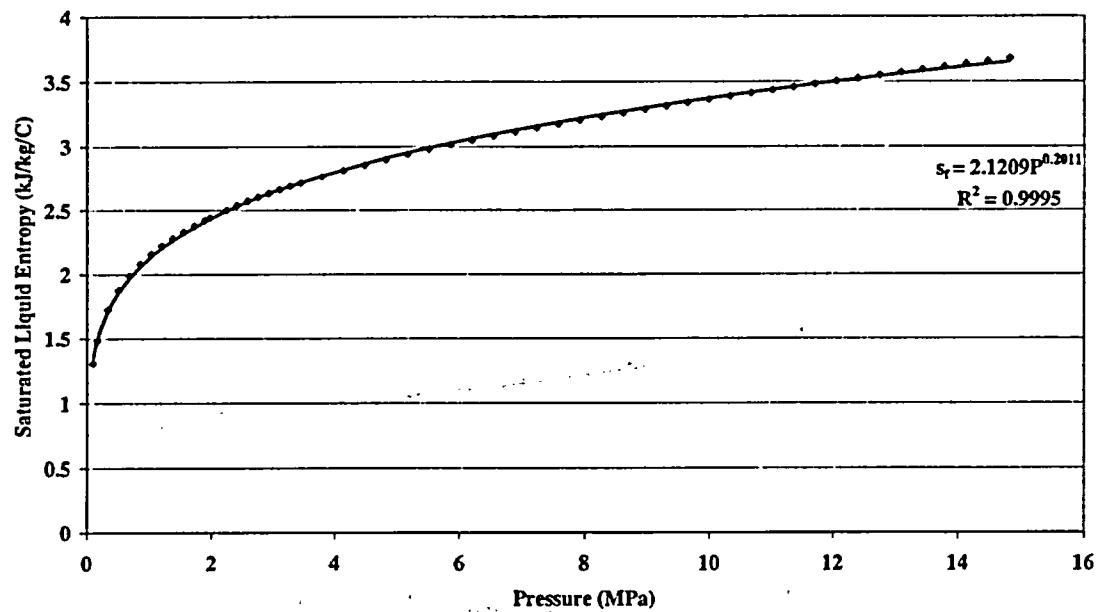


Figure A.9 Power Law for s_f as a Function of Pressure

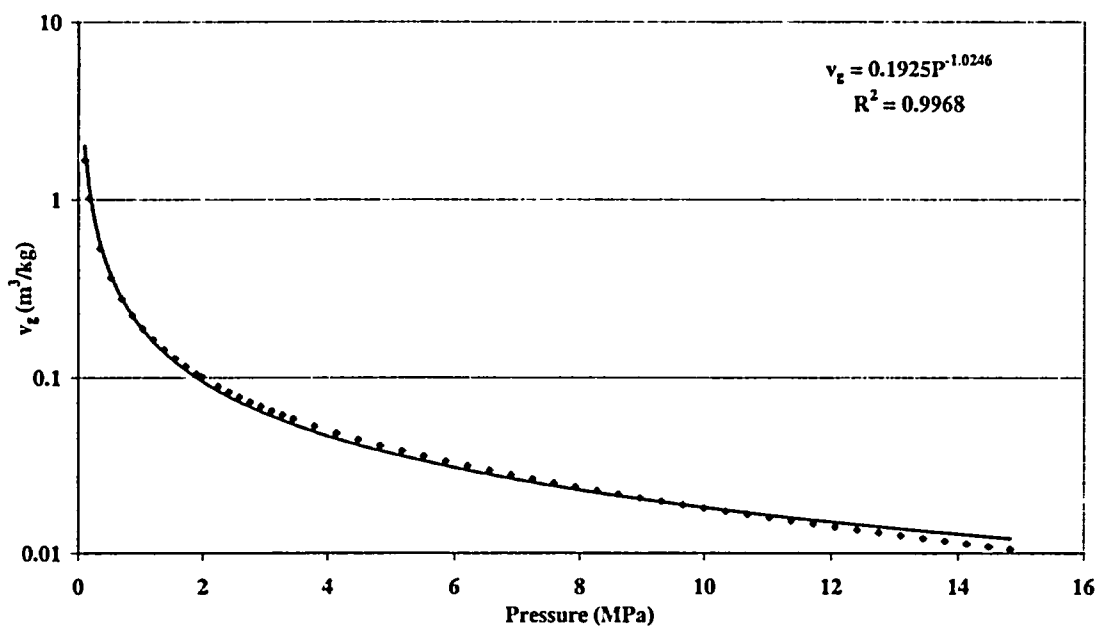


Figure A.10 Power Law for v_g as a Function of Pressure

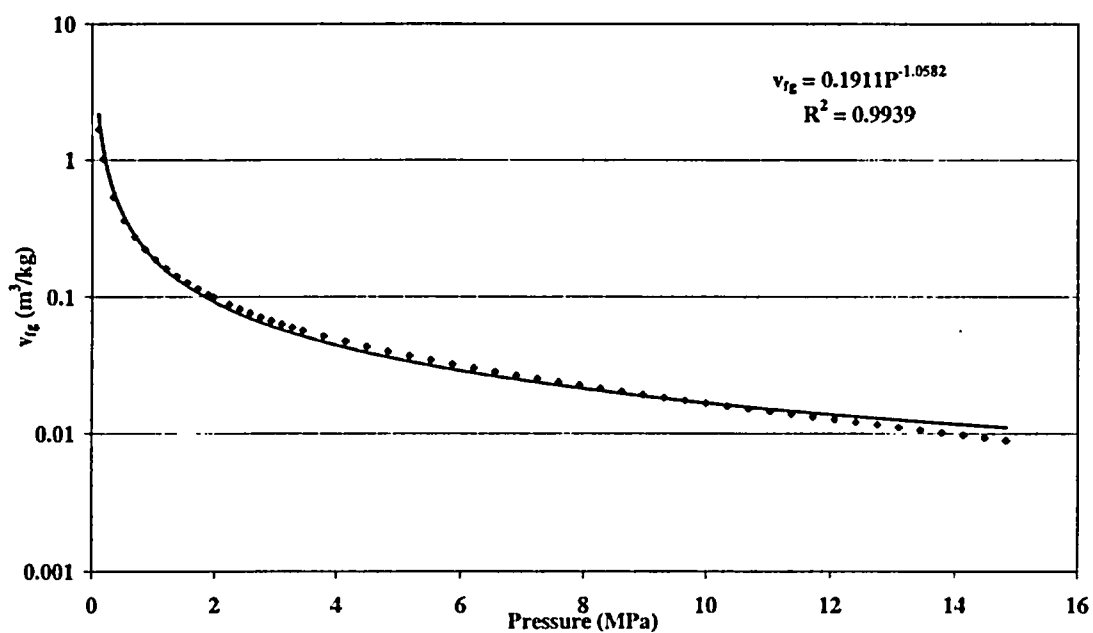


Figure A.11 Power Law for v_{fg} as a Function of Pressure

A.5.4.2 Equations of State for Saturated Pressure and Temperature (T_{sat} Scaling)

The Clausius-Clapeyron equation is the classical differential equation that defines the slope dP/dT , for a phase equilibrium curve. It is derived assuming that the Gibb's free energies for the two-phases being considered are equal [Ref. 12]. Using the saturated definition for the Gibb's free energy and relating the change in entropy to the latent heat of vaporization and the saturation temperature yields the well-known Clausius-Clapeyron equation:

$$\frac{dP}{dT} = \frac{h_{fg}}{v_{fg} T} \quad (A.75)$$

An analytical expression for an equation of state relating saturation pressure to saturation temperature can be obtained as follows. Substituting equation (A.66) into (A.75), where ξ is 0.11 for water, and rearranging yields:

$$\left(\frac{P}{P_o}\right)^{\xi-1} dP = \left(\frac{h_{fg}}{v_{fg}}\right)_o \frac{1}{T} dT \quad (A.76)$$

Integrating from P_o to P_{sat} and from T_o to T_{sat} yields the desired relationship between P_{sat} and T_{sat} .

$$P_{sat}(T_{sat}) = P_o \left[1 + \xi \left(\frac{h_{fg}}{P v_{fg}} \right)_o \text{Ln} \left(\frac{T_{sat}}{T_o} \right)^{1/\xi} \right] \quad (A.77)$$

Figure A.12 shows that equation (A.77) is quite accurate for the range of conditions examined.

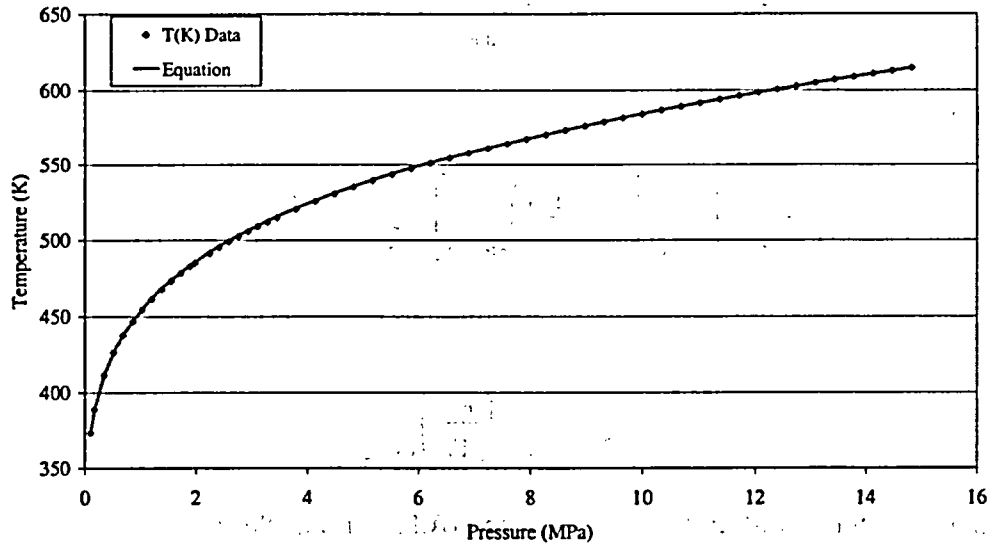


Figure A.12 Comparison of Equation (A.77) to Steam Tables

Equation (A.77) can be rearranged to obtain saturation temperature in terms of saturation pressure. The result is:

$$T_{sat}(P_{sat}) = T_o \exp \left\{ -\frac{1}{\xi} \left(\frac{P v_{fg}}{h_{fg}} \right)_o \left[1 - \left(\frac{P_{sat}}{P_o} \right)^\xi \right] \right\} \quad (A.78)$$

This equation can be accurately approximated using the following identity:

$$\exp(\beta) \approx 1 + \beta \quad (A.79)$$

for $\beta \ll 1$ which is applicable to the current situation. Thus equation (A.78) is approximated by:

$$T_{sat} = T_o \left\{ 1 - \frac{1}{\xi} \left(\frac{P v_{fg}}{h_{fg}} \right)_o \left[1 - \left(\frac{P_{sat}}{P_o} \right)^\xi \right] \right\} \quad (A.80)$$

Rearranging equation (A.80) yields:

$$\left(\frac{h_{fg}}{P v_{fg}} \right)_o \left[1 - \left(\frac{T_{sat}}{T_o} \right) \right] = \frac{1}{\xi} \left[1 - \left(\frac{P_{sat}}{P_o} \right)^\xi \right] \quad (A.81)$$

This equation is valid for both APEX and AP1000 for the range of saturated conditions being examined. Writing this equation for APEX yields:

$$\left(\frac{h_{fgo}}{P_o v_{fgo}} \right)_{APEX} \left[1 - \left(\frac{T_{sat}}{T_o} \right)_{APEX} \right] = \frac{1}{\xi} \left[1 - \left(\frac{P_{sat}}{P_o} \right)_{APEX}^\xi \right] \quad (A.82)$$

and for AP1000:

$$\left(\frac{h_{fgo}}{P_o v_{fgo}} \right)_{AP1000} \left[1 - \left(\frac{T_{sat}}{T_o} \right)_{AP1000} \right] = \frac{1}{\xi} \left[1 - \left(\frac{P_{sat}}{P_o} \right)_{AP1000}^\xi \right] \quad (A.83)$$

Recalling that:

$$\left(\frac{P_{sat}}{P_o} \right)_{APEX} = \left(\frac{P_{sat}}{P_o} \right)_{AP1000} \quad (A.84)$$

it is recognized that the right-hand side of equation (A.82) and (A.83) are identical. Therefore, they can be set equal to obtain:

$$\left(\frac{h_{fgo}}{P_o v_{fgo}} \right)_{APEX} \left[1 - \left(\frac{T_{sat}}{T_o} \right)_{APEX} \right] = \left(\frac{h_{fgo}}{P_o v_{fgo}} \right)_{AP1000} \left[1 - \left(\frac{T_{sat}}{T_o} \right)_{AP1000} \right] \quad (A.85)$$

Rearranging this equation yields the desired saturation temperature scaling relation:

$$\left(\frac{T_{sat}}{T_o}\right)_{AP1000} = \left(\frac{h_{fgo}}{P_o v_{fgo}}\right)_R \left(\frac{T_{sat}}{T_o}\right)_{APEX} - \left[\left(\frac{h_{fgo}}{P_o v_{fgo}}\right)_R - 1\right] \quad (A.86)$$

Equation (A.86) is linear as shown in Figure A.13 for the APEX and AP1000 reference temperatures (i.e., the saturation temperatures for the corresponding APEX and AP1000 reference pressures). Figure A.13 compares the approximate solution given by equation (A.86) to the exact result obtained using the steam tables.

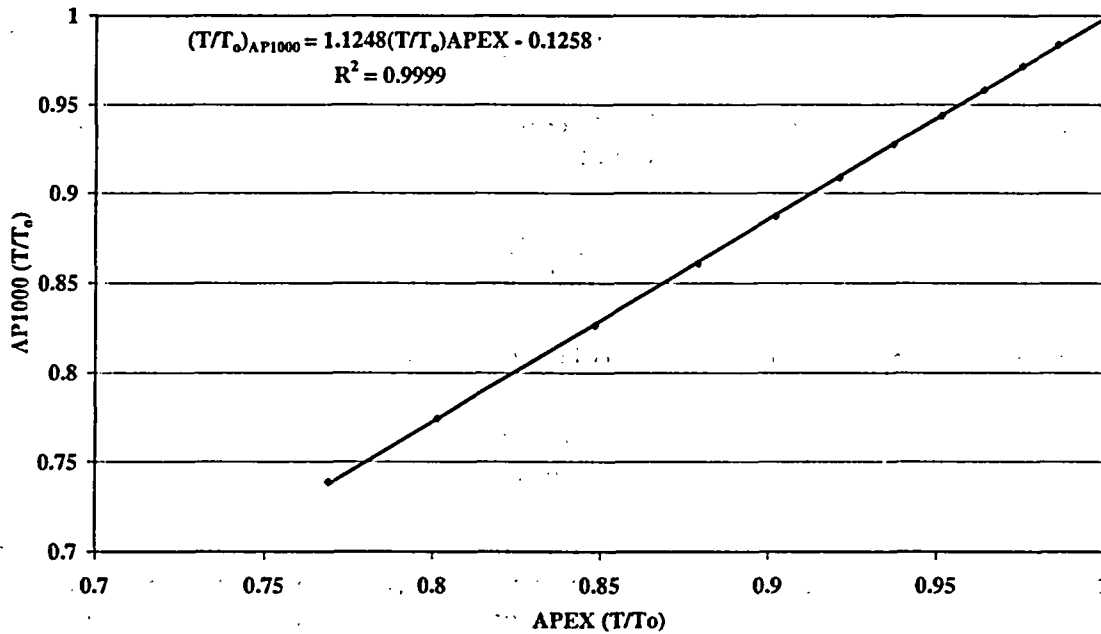


Figure A.13 Scaling Relationship Between AP1000 and APEX Saturation Temperature

A.5.4.3 Dilation Property Group for Saturated Liquid-Vapor Blowdowns

This section demonstrates how the dilation property group, Π_c , given by equation (A.62), is evaluated for different fluid conditions. For a two-phase fluid mixture in phase equilibrium, the following thermodynamic relations are applicable for the mixture specific internal energy and the mixture specific volume, respectively:

$$e = e_f + x e_{fg} \quad (A.87)$$

$$v = v_f + x v_{fg} \quad (A.88)$$

Eliminating the fluid mixture equilibrium quality, x , between equations (A.87) and (A.88) yields the following expression for specific internal energy:

$$e = e_f + \frac{v - v_f}{v_{fg}} e_{fg} \quad (\text{A.89})$$

The partial derivative of this equation with respect to specific volume, at constant pressure, yields:

$$\left(\frac{\partial e}{\partial v} \right)_P = \frac{e_{fg}}{v_{fg}} \quad (\text{A.90})$$

Lastly, the latent heat of vaporization is given by:

$$h_{fg} = P v_{fg} + e_{fg} \quad (\text{A.91})$$

Substituting equations (A.87) through (A.91) into equation (A.62) yields the following expression for the saturated mixture dilation property group:

$$\Pi_e = \frac{1}{[v_f + x_{Brk} v_{fg}]} \left(\frac{P v_{fg}}{h_{fg}} \right) \left(\frac{\partial e}{\partial P} \right)_v \quad (\text{A.92})$$

where the equilibrium vapor quality at the break is given by x_{Brk} :

$$x_{Brk} = \frac{h_{Brk} - h_f}{h_{fg}} \quad (\text{A.93})$$

Let us examine the pressure dependencies of the terms that comprise the fluid mixture dilation property group given by equation (A.92). The property group $(P v_{fg}/h_{fg})$ has already been evaluated as shown in Figure A.8 and found to be described by equation (A.66), a power law that exhibits self-similarity for a wide range of saturation pressures.

The last term on the right-hand side of equation (A.92), $(\partial e/\partial P)_v$, is a partial derivative that requires examining the change in the fluid mixture internal energy with respect to pressure *while holding the mixture specific volume, v , constant*. It should not be confused with the total specific internal energy change with respect to pressure. An adequate model for this term can be obtained by developing an expression for the mixture internal energy as a function of pressure while at constant specific volume and taking the derivative with respect to pressure. Therefore, the term $(\partial e/\partial P)_v$ shall be evaluated assuming that the system expands along a trajectory which maintains the specific volume of the mixture at a constant value, v_o , which is the initial specific volume of the saturated mixture. That is,

$$e = e_f + e_{fg} \left(\frac{v_o - v_f}{v_{fg}} \right) \quad (\text{A.94})$$

For the depressurization transients of interest to this analysis, the saturated mixture blowdown begins with the system nearly filled with saturated liquid with the exception of a small vapor volume located in the pressure vessel head. Since the density of the liquid phase is much greater than that of the vapor phase, the initial system vapor quality is very low and hence the

initial fluid mixture specific volume is essentially the same as the saturated liquid phase specific volume. Thus the value of v_o , implemented in equation (A.94) is closely approximated by v_{fo} . Figure A.14 shows how the mixture internal energy varies with pressure assuming a constant specific volume, $v_o = v_{fo}$, during the depressurization process. The plot has been made dimensionless to collapse the trends for a variety of initial pressures.

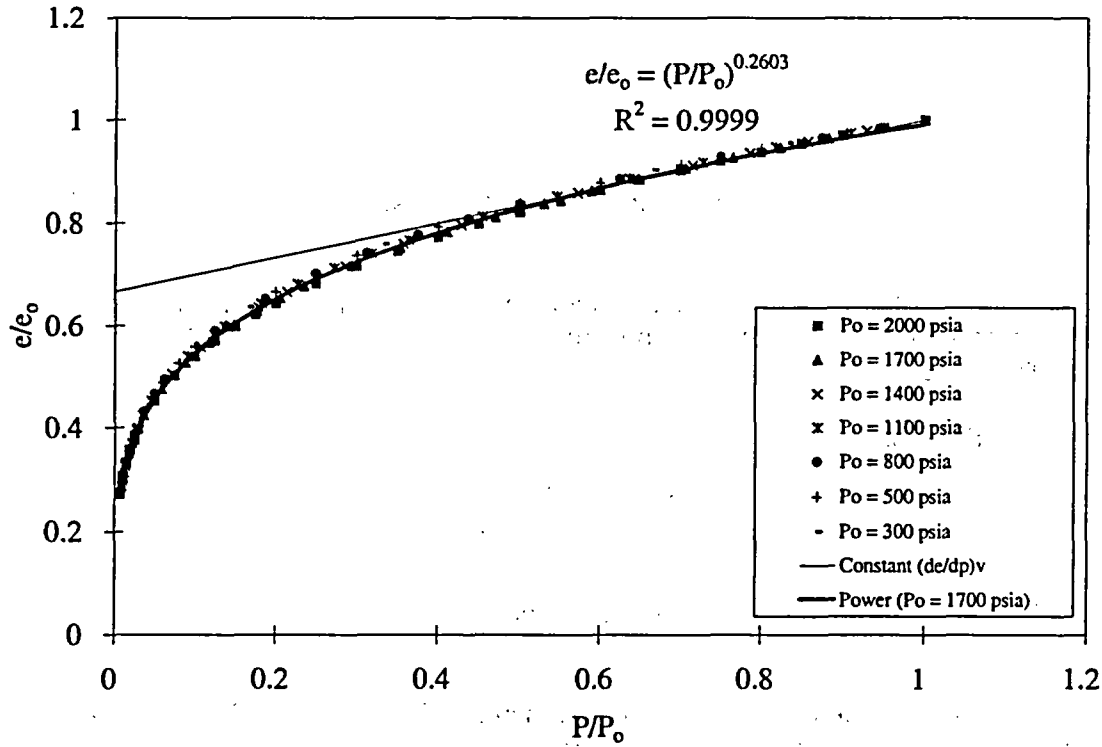


Figure A.14 Plot of Dimensionless Mixture Specific Energy as a Function of Dimensionless Pressure

Note that for pressure ratios greater than ~0.5, the trend is linear, indicating that the slope, $(\partial e / \partial P)_v$, is a constant in this region. As shown in the figure, the following power law ($R^2 = 0.9999$) accurately describes the mixture-specific internal energy ratio for a wide range of normalized pressures.

$$\left(\frac{e}{e_o} \right)_{v_o} = \left(\frac{P}{P_o} \right)^{0.2603} \quad (\text{A.95})$$

Taking the derivative of this equation with respect to pressure yields the expression for the desired partial derivative:

$$\left(\frac{\partial e}{\partial P} \right)_{v_o} = 0.2603 \frac{e_{fo}}{P} \left(\frac{P}{P_o} \right)^{0.2603} \quad (\text{A.96})$$

It should be noted that the numerical constants arising in equations (A.95) and (A.96) are particular to the case where the initial fluid mixture-specific volume and specific energy are given by v_{fo} and e_{fo} , respectively. Different constants are obtained at different initial vapor qualities for the saturated mixture.

Substituting equations (A.66) and (A.96) into (A.92) yields the following equation for the dilation property group.

$$\Pi_{\epsilon} = \frac{0.2603}{[v_f + x_{Brk} v_{fg}]} \left(\frac{e_f v_{fg}}{h_{fg}} \right)_o \left(\frac{P}{P_o} \right)^{-0.6257} \quad (A.97)$$

Equation (A.97) can be readily evaluated for two bounding cases, saturated liquid breaks and saturated vapor breaks.

The fluid conditions for breaks located at low points in the RCS can be approximated assuming saturated liquid at the break. For these conditions, x_{Brk} would be approximately zero, and equation (A.97) would become:

Saturated Liquid Breaks:

$$\Pi_{\epsilon_l} = 0.2603 \left(\frac{e_f v_{fg}}{v_f h_{fg}} \right)_o \left(\frac{P}{P_o} \right)^{-0.6257} \quad (A.98)$$

Here it has also been assumed that v_f does not change significantly over the range of pressure of interest.

The fluid conditions for breaks located at high points in the RCS (e.g., ADS1-3) can be approximated assuming saturated vapor at the break. For these conditions, x_{Brk} would equal one and equation (A.97) would become:
saturated vapor breaks:

$$\Pi_{\epsilon_v} = 0.2603 \left(\frac{e_f}{h_{fg}} \right)_o \left(\frac{P}{P_o} \right)^{0.4443} \quad (A.99)$$

To obtain this equation, use has been made of equation (A.68), the power law for the vapor-specific volume. Equations (A.97) and (A.99) are written in terms of scaling ratios, as follows:

$$(\Pi_{\epsilon_l})_R = \left(\frac{e_f v_{fg}}{v_f h_{fg}} \right)_{o,R} \quad (A.100)$$

and

$$(\Pi_{\epsilon_v})_R = \left(\frac{e_f}{h_{fg}} \right)_{o,R} \quad (A.101)$$

where equation (A.64) has been implemented to eliminate the pressure ratios.

A.5.4.4 Critical Flow Models

For the blowdown cases of interest to this study, all of the break flows are assumed to be choked. This section presents two critical flow models (a saturated vapor model and a saturated liquid model) used to estimate the break mass flow rate:

In general, the break mass flow rate is expressed as:

$$\dot{m}_{Brk} = C_D G_c A_{Brk} \quad (A.102)$$

where C_D is the discharge coefficient, G_c is the critical mass flux and A_{Brk} is the break flow area.

A.5.4.4.1 Saturated Steam

This initial critical mass flow rate for saturated steam, approximated as a perfect gas, is given by Moody [Ref. 13]:

$$\dot{m}_{Brk,o} = C_D A_{Brk} \left(\frac{2}{\gamma + 1} \right)^{\frac{\gamma+1}{2(\gamma-1)}} [\gamma \rho_{go} P_o]^{1/2} \quad (A.103)$$

where C_D is the discharge coefficient, A_{Brk} is the break flow area and γ is the ratio of specific heats, which is approximately 1.33 for steam.

The transient, pressure-dependent, critical mass flow rate for the steam would be:

$$\dot{m}_{Brk} = \dot{m}_{Brk,o} \left(\frac{P}{P_o} \right)^{\frac{1+\gamma}{2\gamma}} \quad (A.104)$$

Once again, we find a power law, self-similar in pressure.

A.5.4.4.2 Saturated Liquid

The models typically implemented for the case of saturated liquid choke flow are the homogeneous equilibrium model or the Henry-Fauske model [Ref. 14]. An earlier study of APEX data indicated that the Henry-Fauske model at saturated liquid conditions best fit the APEX data [Ref. 15].

The Henry-Fauske critical flow model for saturated liquid is given by the following set of equations:

$$G_c = \left[\left\{ (v_g)_{Brk} - v_f \right\} \frac{x_{Brk}}{(0.14)(Sfg)_{Brk}} \left(\frac{dS_f}{dP} \right)_{Brk} \right]^{-1/2} \quad (A.105)$$

and

$$\frac{P_{Brk}}{P} = 1 - \frac{v_f G_c^2}{2P} \quad (A.106)$$

In these equations, the parameters with the subscript "Brk" are evaluated at the break plane. All other parameters are evaluated at the system conditions. Thus, P_{Brk} is commonly known as the throat pressure, while P is the stagnation pressure. A typical value of equilibrium quality for the saturated liquid breaks observed in APEX was x_{Brk} equal to 0.03.

The saturated liquid entropy derivative on the right-hand side of equation (A.105) was obtained by taking the derivative of equation (A.67) with respect to pressure. This yielded the following expression for (ds/dP) :

$$\frac{ds_f}{dP} = 0.2 \frac{s_{f,o}}{P} \left(\frac{P}{P_o} \right)^{0.2} \quad (\text{A.107})$$

Equations (A.105) and (A.106) were solved iteratively to obtain the critical flow rates for saturated liquid breaks in APEX and AP1000. Figure A.15 presents the result of this analysis. Furthermore, it indicates that the critical flow model also obeys a power law that is self-similar in pressure. That is:

$$G_c \approx G_{co} \left(\frac{P}{P_o} \right)^{0.7063} \quad (\text{A.108})$$

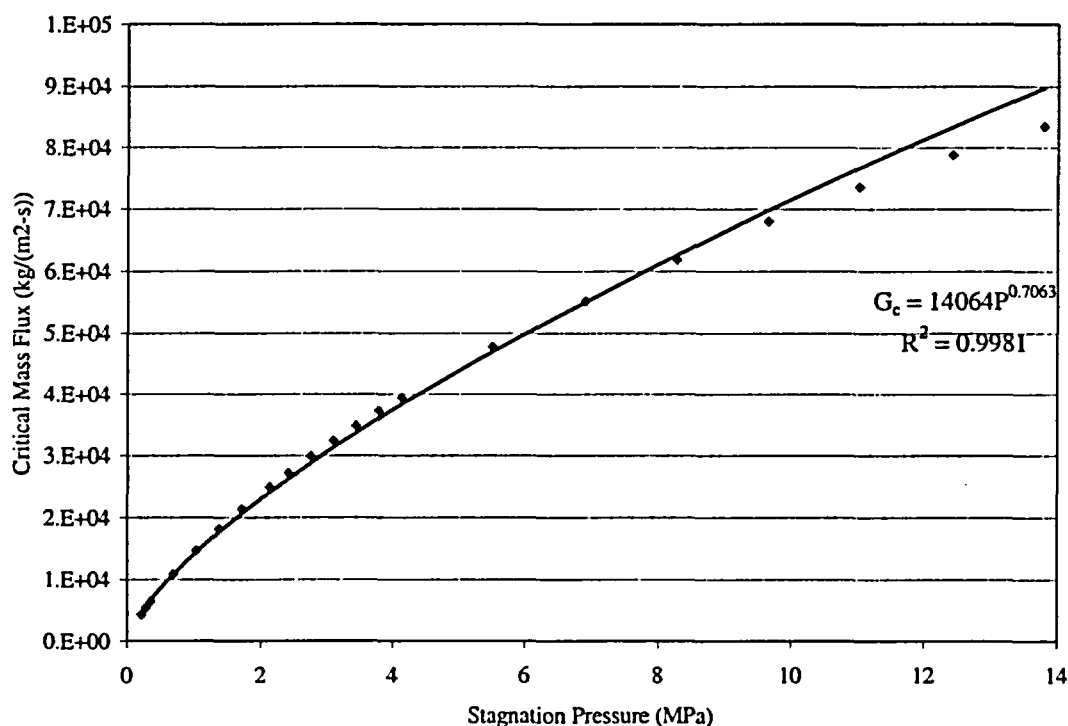


Figure A.15 Critical Mass Flux for Saturated Liquid Breaks as Predicted by the Henry Fauske Model ($x_{Brk} = 0.03$)

Using equation (A.102), the mass flow rate for saturated liquid breaks can be expressed as:

$$\dot{m}_{Brk} \approx \dot{m}_{Brk,o} \left(\frac{P}{P_o} \right)^{0.7063} \quad (A.109)$$

Equations (A.104) and (A.109) served as the closure relations for the top-down scaling dimensionless groups, Π_m , Π_h , Π_r , and the time constant τ_{RCS} .

A.5.5 RCS depressurization and Inventory Scaling Criteria

It is desired that APEX-AP1000 depressurization rate and the rate at which the RCS mass inventory changes be preserved in dimensionless phase space, (P^*, M^*) . That is, the following similarity criteria shall be imposed:

$$\left(\tau_{RCS} \frac{dM^*}{dt} \right)_R = 1 \quad (A.110)$$

$$\left(\tau_{RCS} \frac{dP^*}{dt} \right)_R = 1 \quad (A.111)$$

where:

$$\tau_{RCS,R} = \left[\frac{M_{RCS}}{\dot{m}_{Brk}} \right]_{o,R} \quad (A.112)$$

and the one-half time scale requirement has been set.

If these criteria are preserved and the same initial conditions, $(P^*, M^*)_o$ are imposed in APEX-AP1000,

$$(\tau_{RCS})_R = \frac{1}{2} \quad (A.113)$$

the same process trajectory will result when plotted in dimensionless phase space. Applying these conditions to the dimensionless balance equations given by equations (A.49) and (A.59) means that the following scaling criteria must be on the order of unity.

$$\Pi_{m,R} = \left(\frac{\dot{m}_{INJ,o}}{\dot{m}_{Brk,o}} \right)_R \quad (A.114)$$

$$\left(\frac{\Pi_h}{\Pi_f} \right)_R = \left[\frac{\sum \dot{m}_{DVI,o} \left[h_{DVI} - e + v \left(\frac{\partial e}{\partial v} \right)_{p,o} \right]}{\dot{m}_{Brk,o} P_o \left(\frac{\partial e}{\partial P} \right)_{v,o}} \right]_R \quad (A.115)$$

$$\left(\frac{\Pi_r}{\Pi_\varepsilon} \right)_R = \left[\frac{q_{\text{net},o}}{\dot{m}_{\text{Brk},o} P_o \left(\frac{\partial e}{\partial P} \right)_{v,o}} \right]_R \quad (\text{A.116})$$

$$(\Pi_\varepsilon)_R = \left[\frac{P_o \left(\frac{\partial e}{\partial P} \right)_{v,o}}{\left[h_{\text{Brk}} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o} \right]_R \quad (117)$$

The SBLOCA cases considered in the analysis are the case of saturated vapor at the ADS1-3 location and saturated liquid at the break and ADS4 locations.

A.5.5.1 Saturated Vapor Break Flow Areas

For saturated vapor breaks, the following would be applicable:

$$h_{\text{Brk}} = h_g \quad (\text{A.118})$$

Thus, implementing equations (A.89) through (A.91) yields:

$$\left[h_{\text{Brk}} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o = \frac{v_g h_{fg}}{v_{fg}} \quad (\text{A.119})$$

Similarly:

$$\left[h_{\text{DVI}} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o = \left[\frac{h_{fg} v_f}{v_{fg}} - \Delta h_{\text{sub}} \right]_o \quad (\text{A.120})$$

The injected liquid subcooling is defined as $h_f - h_{\text{DVI}}$. Using these fluid property relations, it is now possible to evaluate equations (A.113) through (A.117). Substituting the critical flow equation for saturated vapor, equation (A.103), and the RCS time constant ratio given by equation (A.110) into (A.111) yields.

$$\left[\frac{M_{\text{RCS}}}{A_{\text{Brk}} [\rho_{go} P_o]^{0.5}} \right]_R = \frac{1}{2} \quad (\text{A.121})$$

The M_{RCS} ratio shall be set such that:

$$M_{\text{RCS},R} = \frac{1}{192} \quad (\text{A.122})$$

Substituting this condition into equation (A.120) and solving for the break area ratio yields:

$$(A_{Brk})_R = \frac{1}{96} \left(\frac{1}{[\rho_{go} P_o]^{1/2}} \right)_R \quad (A.123)$$

A.5.5.2 Saturated Liquid Break Flow Areas

For saturated liquid breaks, the following would be applicable:

$$h_{Brk} = h_f \quad (A.124)$$

Thus, implementing equations (A.89) through (A.91) results in:

$$\left[h_{Brk} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right]_o = \frac{v_f h_{fg}}{v_{fg}} \quad (A.125)$$

Substituting the critical flow equation for saturated liquid, equation (A.109), and the RCS time constant ratio given by equation (A.110), into (A.111) yields:

$$\left[\frac{M_{RCS}}{C_D A_{Brk} P_o^{0.7063}} \right]_R = \frac{1}{2} \quad (A.126)$$

Assuming similar discharge coefficients, substituting equation (A.122) and rearranging, yields the break flow area ratio:

$$(A_{Brk})_R = \frac{1}{96} \left(\frac{1}{P_o^{0.7063}} \right)_R \quad (A.127)$$

Equations (A.123) and (A.127) become identical for the case of fluid property similitude. That is:

$$(A_{Brk})_R = \frac{1}{96} \quad (A.128)$$

A.5.5.3 ADS Valve Flow Area Scaling Ratios

Operation of the ADS is initiated when the CMT liquid level drops below a prescribed setpoint. This typically occurs subsequent to PZR draining. Therefore, most of the flow is single-phase steam. As a result, the ADS1 and ADS2 valves will be scaled in accordance with equation (A.123). That is:

$$(A_{ADS1,2})_R = \frac{1}{96} \left(\frac{1}{[\rho_{go} P_o]^{1/2}} \right)_R \quad (A.129)$$

The opening of the ADS3 valve shall be used to transition to fluid property similitude conditions. This procedure was first implemented in the NRC's AP600 test program to allow actuation of the ADS4 valves at higher operating pressures. The flow area for the APEX ADS3 valve was designed such that:

$$(A_{\text{ADS-3}})_{\text{APEX}} = \frac{1}{96} \Sigma (A_{\text{ADS1,2,3}})_{\text{AP}} 1000 \quad (\text{A.130})$$

The procedure was such that ADS1 and ADS2 would open sequentially as specified by the safety logic. Then ADS1 and ADS2 would be closed and APEX ADS3, representing the sum of flow areas for all three stages, would be opened. Thus the ADS1-3 train would be configured for fluid property similitude and long-term cooling.

The ADS4 valve flow area was sized based on fluid property similitude, as follows:

$$(A_{\text{ADS4}})_R = \frac{1}{96} \quad (\text{A.131})$$

A.5.5.4 DVI Mass Flow Rate Scaling Ratio

All of the injection flow rates will be scaled as follows for the one-half time scale. This is done by preserving the line resistance and relative elevation in the IRWST, CMT, and ACCs. Thus:

$$(\dot{m}_{\text{DVI},o})_R = \frac{1}{96} \quad (\text{A.132})$$

A.5.5.5 Net Power Scaling Ratio

Substituting equation (A.96) into (A.116) and setting the result equal to one yields the net power scaling ratio. Use has been made of the fact that $(P/P_o)_R$ is unity. The core decay power scaling has already been set in Section A.3 to be 1:96.

$$(q_{\text{net},o})_R = [\dot{m}_{\text{Brk}} c_{fo}]_R \quad (\text{A.133})$$

A.5.6 Initial Conditions and Flow Areas

Table A.11 presents the initial conditions for the APEX test facility for a LOCA transient. These parameters will be modified for other transients such as the station blackout.

Table A.11 APEX-AP1000 LOCA Initial Conditions

Parameters	AP1000	APEX	Units	a,b,c
Decay Power (2.8%)				
RCS Pressure				
SG Operating Pressure				
CL Temperature				
SG Operating Pressure				
SG PORV Setpoint (Reference Pressure)				
SG Shell Side Liquid Level				
SG Shell Side Liquid Mass				
SG Shell Side Vapor Mass				
PZR Liquid Volume				
ACC Gas Pressure				

Table A.12 presents the flow areas required for the ADS valves as used for LOCA transients, Table A.13 presents the ADS1 and 2 flow areas for the special case of a transient initiated by the inadvertent opening of the ADS1 valve, Table A.14 presents the scaled break sizes, and Table A.15 presents the numerical values for the RCS time constant and P ratios.

Table A.12 Summary of APEX-AP1000 ADS1-4 Valve Flow Areas for LOCA

Component	Scaling		Units		
	Ratio	AP1000 APEX	AP1000 APEX		
ADS1-2 FLOW AREAS FOR LOCA (SATURATED STEAM)					
ADS1 Single Valve Effective Flow Area (min)				a,b,c	
ADS1 Single Valve Effective Throat I.D.					
ADS1 Two Valves Effective Flow Area (combined)					
ADS1 Two Valves Effective Throat I.D. (combined)					
ADS2 Single Valve Effective Flow Area (min)					
ADS2 Single Valve Effective Throat I.D.					
ADS2 Two Valves Effective Flow Area (combined)					
ADS2 Two Valves Effective Throat I.D. combined					
ADS1-3 FLOW AREAS COMBINED (FLUID PROPERTY SIMILITUDE)					
ADS1,2,3 Single Train Effective Flow Area (min)					
ADS1,2,3 Single Train Effective Throat I.D.					
ADS1,2,3 Two Trains Effective Flow Area (combined)					
ADS1,2,3 Two Trains Effective Throat I.D. (combined)					
ADS4 FLOW AREAS PER HOT LEG (FLUID PROPERTY SIMILITUDE)					
ADS4 Single Train (50% Effective Flow Area)					
ADS4 Single Train Effective Throat I.D.					
ADS4 Two Trains (100% Effective Flow Area)					
ADS4 Two Trains Effective Throat I.D. (combined)					

Table A.13 Summary of APEX-AP1000 ADS1-2 Valve Flow Areas for Inadvertent Opening of ADS

Component	Scaling		Units	
	Ratio	AP1000 APEX	AP1000 APEX	
ADS1-2 FLOW AREAS FOR INADVERTENT ADS OPEN IN TRANSIENT (SATURATED LIQUID)				
ADS1 Single Valve Effective Flow Area (mini)				A,b,c
ADS1 Single Valve Effective Throat I.D.				
ADS1 Two Valves Effective Flow Area (combined)				
ADS1 Two Valves Effective Throat I.D. (combined)				
ADS2 Single Valve Effective Flow Area (mini)				
ADS2 Single Valve Effective Throat I.D.				
ADS2 Two Valves Effective Flow Area (combined)				
ADS2 Two Valves Effective Throat I.D. (combined)				

Table A.14 APEX-AP1000 Break and Steam Generator PORV Sizes. LOCA FLOW AREAS
(Pressure Scaled Two Phase Fluid)

Component	Scaling Ratio	AP1000	APEX	Units
2-INCH COLD LEG BREAK				a,b,c
Flow area				
Diameter				
DOUBLE-ENDED DVI LINE BREAK				
DVI Nozzle Flow Area				
Diameter				
STEAM GENERATOR PORV FLOW AREA (SINGLE-PHASE STEAM)				
*PORV Equivalent Flow Area				
PORV Equivalent Throat Diameter				
*Based on 1.02 x 10 ⁶ lbm/hr at 1200 psia for AP1000				

*Based on 1.02×10^6 lbm/hr at 1200 psia for AP1000

Table A.15 Time Constants and Π Groups for APEX Pressure Scaled LOCAs

Π Group	Saturated Vapor Breaks	Saturated Liquid Breaks	
$(1/\tau_{RCS}), R$			a,b,c
Π_m, R			
$\left(\frac{\Pi_h}{\Pi_e}\right)_R$			
$\left(\frac{\Pi_r}{\Pi_e}\right)_R$			
$(\Pi_e)_R$			

A.5.7 Summary and Conclusions

This section presents the results of the SBLOCA scaling analysis. The goal was to scale the APEX initial conditions and break flow areas such that the RCS depressurization rate and corresponding cooldown rate would be preserved in dimensionless phase space. The two types of break conditions considered were (1) all-saturated vapor at the break, such as the stuck-open ADS1-3, and (2) an all-saturated liquid break, which was the assumed condition for the HL break.

The scaling analysis provided the RCS initial conditions and the break flow areas. All of the Π groups, as shown in Table A.14, were found to have values on the order of 1, with the exception of the fluid property group under pressure-scaled conditions.

An examination of the Π groups ratios indicates that for saturated vapor breaks (i.e., stuck-open ADS1-3) the depressurization and cooldown rate will be reasonably simulated in APEX. Some distortion may occur in simulating the HL break because conditions at the break will likely be two-phase rather than saturated liquid as assumed in the analysis. The validity of this assumption will depend on whether the injection flows keep the break conditions near the saturated liquid state.

For the conditions of fluid property similitude, all of the Π group ratios listed in Table A.14 will be one. Thus, the full-pressure tests that will be performed in APEX to assess the transition from ADS4 operation to IRWST injection are expected to yield depressurization behavior that is similar to the AP1000. The next chapter presents the scaling analysis for the full-pressure ADS4 blowdown phenomena.

A.6 Scaling Analysis of the Full-Pressure ADS4 Blowdown to IRWST Injection Transition Period

The APEX-AP1000 test facility was modified to conduct full-pressure studies of the thermal-hydraulic phenomena that arise during the transition from ADS4 blowdown to the onset of IRWST injection. This transition period was previously studied under full-pressure conditions in the SPES and ROSA-AP600 test facilities. This period was deemed to be very important by analysts because there is a limited amount of liquid available for core cooling while the system depressurizes to the IRWST injection setpoint. Operating the APEX facility under reduced-pressure conditions during this phase of a transient results in distorting the conditions at which the IRWST begins to drain.

In the AP1000, IRWST injection would initiate when the primary system pressure drops below ~ 0.198 MPa (28.7 psia), based on the minimum initial IRWST liquid level. At this pressure, the flow at the ADS4 valves would be still be choked (i.e., essentially single-phase vapor flow) and independent of the ADS4 line resistance. However, for the one-quarter height IRWST in APEX, the onset of flow would not begin until the primary system pressure dropped below ~ 0.125 MPa (18.2 psia). At this pressure, the ADS4 flow would be unchoked and, therefore, the ADS4 flow rate would be dependent on ADS4 line resistance.

In an effort to eliminate the ADS4 flow distortions in APEX during this transition period, a series of full-pressure ADS4 blowdown tests were performed. This required configuring APEX to provide pressure control for ADS4 blowdowns initiating from steady-state conditions, pressuring the IRWST to simulate full-height conditions and adjusting the IRWST line resistance to achieve properly scaled injection flow rates under full-height IRWST conditions. This section presents the scaling analysis performed to design the ADS4 blowdown to IRWST injection transition tests.

A.6.1 Description of the ADS4 Blowdown to IRWST Injection Thermal-hydraulic Phenomena

Figure A.16 presents an overview of the thermal-hydraulic phenomena that arise during a typical ADS4 blowdown. This figure characterizes the phenomena in terms of RPV mixture level (or liquid mass) versus the system pressure. The ADS4 valves open when the liquid volume in either of the two CMTs drops below 20% of its initial volume. At P_{ADS4} , the pressure at which the ADS4 valves open, two-phase fluid choke flow will exist at the ADS4 valves. All of the liquid located above the top of the HLs, (i.e., the entrance to the ADS4 line), will eventually be swept out of the ADS4 valves. The amount of liquid located above the HLs is dependent on the amount of level swell in the core. When the fluid mixture level drops below the top of the HLs, the flow out of the ADS4 valves can be best described as a high-quality vapor choke flow. Liquid boil-off in the core, liquid flashing to vapor, and liquid carryover from the upper plenum will act to reduce the liquid inventory in the RPV. Because there are no other sources of liquid during this phase of the transient, primary system pressure must drop below the IRWST liquid level head pressure, P_{IRWST} , before the RPV mixture level reaches the top of the core. When the primary system pressure drops below P_{IRWST} , less some small check valve cracking pressure, IRWST liquid flow will act to reflood the RPV.

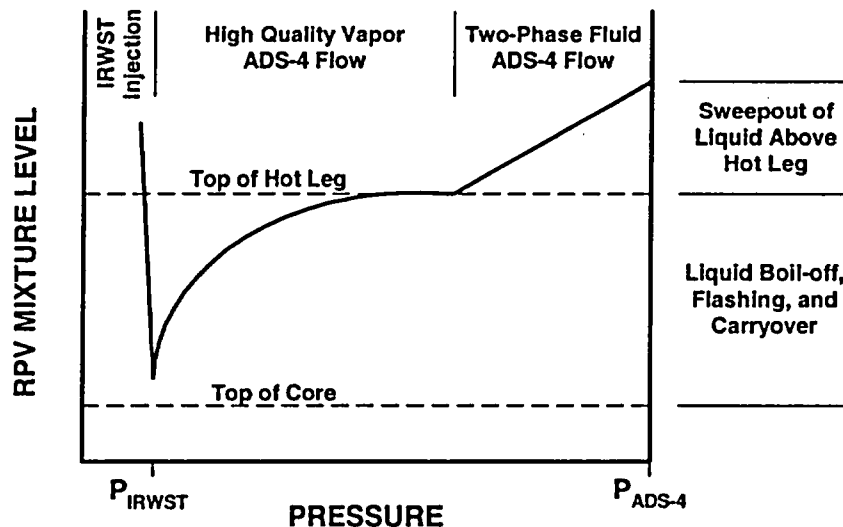


Figure A.16 Description of the Transition from ADS4 Blowdown to the Onset of IRWST Injection

Figure A.17 shows how the thermal-hydraulic phenomena described in this section have been addressed in the top-down and bottom-up scaling analyses. First a top-down scaling analysis was performed to obtain a single governing equation in terms of dP^*/dM^* . Next, a bottom-up scaling analysis was performed to describe the local thermal-hydraulic processes, including critical flow, core fluid boil-off, and core mixture level swell.

A.6.2 Top-Down RCS Depressurization and Mass Inventory Scaling Analysis (Pressure Similitude)

The mass balance equation and depressurization rate equation developed in Section A.5 are directly applicable to this analysis. However, the initial conditions and processes to be examined are specific to the transition period from ADS4 blowdown to IRWST injection under full-pressure conditions. The objective of this analysis is to develop the criteria for preserving the AP1000 depressurization and mass inventory behavior for the transition period as described in dimensionless phase space (M^* , P^*).

The following mass balance equation was developed for the RCS in Section A.5.2.

$$\frac{dM}{dt} = \sum \dot{m}_{in} - \sum \dot{m}_{out} \quad (A.134)$$

During the ADS4/IRWST transition period, there will be no sources of liquid injection; therefore, the first term on the right-hand side of equation (A.134) can be deleted. Furthermore, the only vent paths to be considered in this analysis shall be the ADS4 valves.

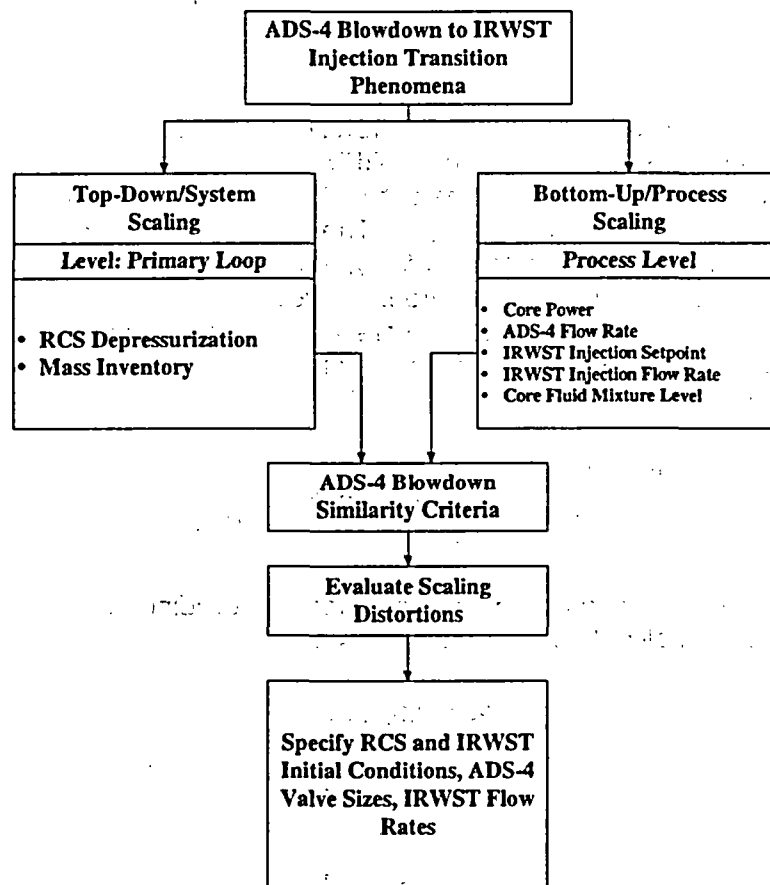


Figure A.17 Scaling Analysis Flow Chart for the Full Pressure ADS4 Blowdown Experiments

Applying these assumptions results in the following equation:

$$\frac{dM}{dt} = -\dot{m}_{ADS4} \quad (A.135)$$

The following depressurization rate equation was also developed for the RCS in Section A.5.2.

$$M \left(\frac{\partial e}{\partial P} \right)_v \frac{dP}{dt} = (\Sigma \dot{m}_{in}) \left[h_{in} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] - (\Sigma \dot{m}_{out}) \left[h_{out} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] + q_{SG} + q_{core} + q_{loss} \quad (A.136)$$

During the ADS4/IRWST transition period, the SGs will be isolated. Therefore, the q_{SG} term can be deleted. The heat loss will be negligible compared to the core decay heat. Therefore, the q_{loss} term can also be neglected. Applying these assumptions and those for the mass balance equation yields:

$$M \left(\frac{\partial e}{\partial P} \right)_v \frac{dP}{dt} = -\dot{m}_{ADS4} \left[h_{ADS4} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] + q_{core} \quad (A.137)$$

It is noted that the key behavior of interest to the transition period can be described in terms of system pressure versus RCS mass inventory (or RPV mixture level) as shown in Figure A.20. The process could also be described in terms of two time scales. The first is the time required for the RCS to depressurize from P_{ADS4} to P_{IRWST} . The second is the time required to deplete the RCS mass inventory from its initial condition, $M_{RCS,o}$, to its final mass inventory state which may or may not be sufficient to keep the core covered. However, rather than working with time scales, a departure from previous analyses, the present analysis was simplified by developing a single governing equation in terms of RCS mass and pressure. This was done by dividing equation (A.137) by the mass balance equation (A.135). The result is:

$$M \left(\frac{\partial e}{\partial P} \right)_v \frac{dP}{dM} = \left[h_{ADS4} - e + v \left(\frac{\partial e}{\partial v} \right)_p \right] - \frac{q_{core}}{\dot{m}_{ADS4}} \quad (A.138)$$

This equation can be expressed in non-dimensional form by dividing each term by its respective initial conditions. The normalized terms are as follows:

$$M = M_{RCS,o} M^+ \quad (A.139)$$

$$P = P_{RCS,o} P^+ \quad (A.140)$$

$$q_{core} = q_{core,o} q_{core}^+ \quad (A.141)$$

$$\dot{m}_{ADS4} = \dot{m}_{ADS4,o} \dot{m}_{ADS4}^+ \quad (A.142)$$

$$\left(\frac{\partial e}{\partial P}\right)_v = \left(\frac{\partial e}{\partial P}\right)_{v,o} \left(\frac{\partial e}{\partial P}\right)_v^* \quad (\text{A.143})$$

$$\left[h_{\text{ADS4}} - e + v \left(\frac{\partial e}{\partial v}\right)_p \right] = \left[h_{\text{ADS4}} - e + v \left(\frac{\partial e}{\partial v}\right)_p \right]_o \left[h_{\text{ADS4}} - e + v \left(\frac{\partial e}{\partial v}\right)_p \right]^* \quad (\text{A.144})$$

Substituting these dimensionless initial conditions into (A.138) and dividing through by $P_o \left(\frac{\partial e}{\partial P}\right)_{v,o}$ yields the non-dimensional governing equation:

$$\left(\frac{\partial e}{\partial P}\right)_v^* \frac{dP^*}{dM^*} = \frac{1}{\Pi_\epsilon} \left[h_{\text{ADS4}} - e + v \left(\frac{\partial e}{\partial v}\right)_p \right]_o - \frac{\Pi_\Gamma}{\Pi_\epsilon} \left(\frac{q_{\text{core}}}{\dot{m}_{\text{ADS4}}} \right)_o \quad (\text{A.145})$$

where the dimensionless property group Π_ϵ is given as in the previous chapter as:

$$\Pi_\epsilon = \frac{P_o \left(\frac{\partial e}{\partial P}\right)_{v,o}}{\left[h_{\text{ADS4}} - e + v \left(\frac{\partial e}{\partial v}\right)_p \right]_o} \quad (\text{A.146})$$

and the power-to-energy flow rate ratio is:

$$\Pi_\Gamma = \frac{q_{\text{core},o}}{\dot{m}_{\text{ADS4},o} \left[h_{\text{ADS4}} - e + v \left(\frac{\partial e}{\partial v}\right)_p \right]_o} \quad (\text{A.147})$$

Hence, to simulate the transition behavior in APEX-AP1000, the dimensionless groups defined in equations (A.146) and (A.147) must be preserved. For the full-pressure conditions proposed for the ADS4 blowdown test series, fluid property similitude reduces the ratio of these groups to:

$$\Pi_{\epsilon,R} = 1 \quad (\text{A.148})$$

and

$$\Pi_{\Gamma,R} = \left(\frac{q_{\text{core},o}}{\dot{m}_{\text{ADS4},o}} \right)_R \quad (\text{A.149})$$

The property group, Π_ϵ in AP1000 and APEX-AP1000 are identical and, therefore, the similarity criterion is automatically satisfied.

A.6.3 Bottom-Up Scaling Analysis

This section describes the scaling analyses performed for the ADS4 blowdown/IRWST transition phenomena. The core power and ADS4 choked flow rate behavior have already been assessed in Section A.5. The core power has been scaled as $[]^{a,b,c}$. Similarly, when fluid property similitude exists, the choked flow conditions at the ADS4 valves are preserved, and the mass flow rate is scaled at $[]^{a,b,c}$ because the ADS4 flow areas have been scaled by $[]^{a,b,c}$. Thus, equation (A.149) becomes:

$$\Pi_{\Gamma,R} = 1 \quad (\text{A.150})$$

which indicates that this dimensionless group will also be preserved in APEX-AP1000.

A.6.3.1 Flashing and Liquid Boil-off Rate

The flashing phenomena is automatically preserved by establishing the initial pressure and subcooling conditions in APEX as those in the AP1000 for the ADS4 blowdown phase. The liquid mass boil-off rate in the core, under steady-state conditions is described as follows:

$$\dot{m}_{\text{Boil-off}} = \frac{q_{\text{core}}}{h_{fg} + h_{\text{subcooled}}} \quad (\text{A.151})$$

For fluid property similitude, the ratio of this equation (i.e., APEX to AP1000) becomes:

$$\dot{m}_{\text{Boil-off},R} = q_{\text{core},R} = \frac{1}{96} \quad (\text{A.152})$$

which is the required value to preserve the one-half time scale requirement. However, it is noted that the volume of the APEX downcomer is large on a scaled basis. Of particular interest to the full-pressure ADS4 blowdown tests is the downcomer volume between the bottom of the CL and the top of the heated fuel elevation. This region represents a source of liquid that resides in the downcomer at an elevation above the top of the heated fuel. For APEX, this region has a length of $[]^{a,b,c}$ and a corresponding volume of $[]^{a,b,c}$. For AP1000, this region has a length of $[]^{a,b,c}$ and a volume of $[]^{a,b,c}$. The length scale ratio is 1:4, as desired. However, the volume scale ratio is 1:100, which is approximately 2 times the desired value of 1:192.

At a system pressure of $[]^{a,b,c}$, the amount of saturated liquid mass that could be contained in this region for AP1000 would be $[]^{a,b,c}$. For the similar region in APEX, this corresponds to $[]^{a,b,c}$.

During the transition period of the ADS4 blowdown, the primary source of water will be the 20% liquid volume remaining in the CMT. For the fluid conditions stated earlier, this corresponds to a volume of $[]^{a,b,c}$ in AP1000 and $[]^{a,b,c}$ in APEX-AP1000. It is desired that a 1:2 boil-off time scale be simulated. Therefore, the following scaling criterion must be preserved:

$$\tau_{\text{Boil-off,R}} = \left(\frac{\rho_f (V_{\text{CMT}} + V_{\text{DC}})(h_{\text{fg}} + h_{\text{subcooled}})}{q_{\text{core}}} \right)_R = 0.5 \quad (\text{A.153})$$

For the case of fluid property similitude and a fixed core power ratio, this criterion becomes:

$$(V_{\text{CMT}} + V_{\text{DC}})_R = \frac{1}{192} \quad (\text{A.154})$$

Because the downcomer volume in APEX is oversized, this criterion can be satisfied by initiating the ADS4 blowdown in APEX with a reduced liquid inventory in the CMT starting the ADS4 blowdown with a 12.5% volume rather than a 20% volume would satisfy this requirement.

A.6.3.2 IRWST Full-Height Liquid Head and Injection Flow Rate

Simulating the full-pressure ADS4 blowdown transition in APEX will require a full-height liquid head in the IRWST. This will be achieved by pressurizing the APEX IRWST to a pressure of []^{a,b,c} to simulate full-height AP1000 conditions. Similarly, the IRWST line resistance shall be increased such that the initial IRWST mass flow rate at the simulated full-height conditions is []^{a,b,c}. Flow tests shall be performed to fine-tune the IRWST line resistance.

A.6.3.3 Core Fluid Mixture Level Swell

The initial liquid mass distribution in the RCS will determine the conditions at which the HL uncovers. As shown in Figure A.20, when the HL uncovers, the ADS4 flow transitions from two-phase choked flow to essentially single-phase vapor choked flow. This choked flow transition is important because the RCS depressurization rate will depend on the type of choked flow conditions at the ADS4 valves.

Properly modeling the initial RCS liquid mass distribution requires preserving the core fluid mixture level swell. The equation for level swell is given by:

$$H_{\text{mix}} = \frac{H_{\text{collapsed}}}{1 - \langle \alpha_c \rangle} \quad (\text{A.155})$$

where H_{mix} is the fluid mixture level, $H_{\text{collapsed}}$ is the collapsed liquid level and $\langle \alpha_c \rangle$ is the average core void fraction. To preserve the level swell in the core, the following similarity criterion must be preserved:

$$\left(\frac{H_{\text{collapsed}}}{H_{\text{mix}}} \right)_R = (1 - \langle \alpha_c \rangle)_R \quad (\text{A.156})$$

which implies that the average core void fraction ratio must also be preserved. That is:

$$\langle \alpha_c \rangle_R = 1 \quad (\text{A.157})$$

The void fraction as a function of position in the core was obtained using the drift-flux relationship [Ref. 15]:

$$\alpha(z) = \frac{j_g(z)}{C_o j(z) + v_{gj}} \quad (\text{A.158})$$

At stagnant loop conditions, j_l is zero, so equation (A.158) becomes:

$$\alpha(z) = \left[C_o + \frac{v_{gj}}{j_g(z)} \right]^{-1} \quad (\text{A.159})$$

The volumetric vapor flux, j_g , was found using the following relation:

$$j_g(z) = \frac{1}{\rho_g a_c h_{fg}} \int_{L_{NB}}^z q'(z) dz \quad (\text{A.160})$$

where L_{NB} is the non-boiling height. The core averaged void fraction, $\langle \alpha_c \rangle$, was obtained by integration as follows:

$$\langle \alpha_c \rangle = \frac{1}{L_c} \int_{L_{NB}}^{L_c} \alpha(z) dz \quad (\text{A.161})$$

APEX-AP1000 will implement a constant axial power profile. Therefore, equation (A.158) is given by:

$$j_g(z) = \frac{q_{core} (z - L_{NB})}{\rho_g a_c h_{fg} L_c} \quad (\text{A.162})$$

Substituting equations (A.157) and (A.160) into (A.159) yields the core averaged void fraction for constant axial power:

$$\langle \alpha_c \rangle = \frac{1}{C_o} \left[1 - \frac{L_2}{C_o \Pi_z (L_c - L_{NB})} \text{Ln} \left(1 + \frac{C_o \Pi_z (L_c - L_{NB})}{L_c} \right) \right] \quad (\text{A.163})$$

where Π_{zuber} is the Zuber number, rearranged as:

$$\Pi_{zuber} = \frac{q_{core}}{\rho_g v_{gj} a_c h_{fg}} \quad (\text{A.164})$$

The AP1000 is assumed to have a chopped cosine shape axial power profile defined as follows.

$$q(z) = \int_{-L_c/2}^z q'_c \cos\left(\frac{\pi z}{L_c}\right) dz \quad (\text{A.165})$$

Integrating equation (A.163) yields:

$$q(z) = q'_c \frac{L_c}{\pi} \left[1 + \sin\left(\frac{\pi z}{L_c}\right) \right] \quad (\text{A.166})$$

Substituting equation (A.164) into equations (A.158) yields:

$$j_g(z) = \frac{q'_c L_c}{\pi \rho_g a_c h_{fg}} \left[1 + \sin\left(\frac{\pi z}{L_c}\right) \right] \quad (\text{A.167})$$

Equation (A.165) was substituted into (A.159) and numerically integrated to obtain the core averaged void fraction for the AP1000. The churn-turbulent drift-flux correlation was used to assess equation (A.157) for both APEX and AP1000. That is:

$$v_{gj} = 1.53 \left[\frac{\sigma g \Delta \rho}{\rho_{\text{liq}}^2} \right]^{1/4} \quad (\text{A.168})$$

Table A.16 presents the data used to calculate the core average void fraction for the case of an ADS4 blowdown from []^{a,b,c} and a decay heat of []^{a,b,c}. The core averaged void fraction was found to be []^{a,b,c} for APEX and 60% for AP1000.

Figure A.18 compares the axial void fraction profiles in AP1000 and APEX-AP1000 for an average subchannel for this ADS4 blowdown case. The difference in void fraction profiles arises because the power profiles have different shapes. The core exit void fractions were calculated to be []^{a,b,c} and []^{a,b,c} for AP1000 and APEX respectively.

Table A.16 Comparison of APEX and AP1000 Core Averaged Void Fractions

Parameter	AP1000	APEX-AP1000	Units	a,b,c
Core Flow Area (a_c)				
Core Heated Length				
Power (2.1% Decay)				
Average Linear Power at Decay Heat				
Pressure				
P_g				
P_l				
σ				
H_g				
H_L				
C_o				
v_{gi}				
$\langle \alpha_c \rangle$				

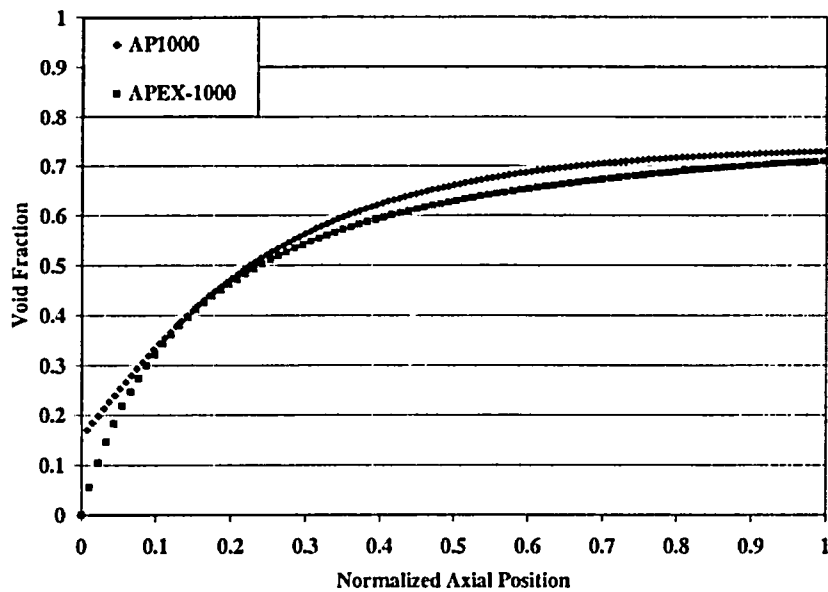


Figure A.18 Comparison of AP1000 and APEX Axial Void Fraction Profiles for an Average Subchannel

A.6.3.4 Initial Conditions for the Full-Pressure ADS4 Blowdown Tests

The following table presents the initial conditions for a full-pressure ADS4 test in APEX-AP1000. The test shall be initiated from steady-state conditions. The decay power and system pressure were selected based on the results of Chapter 15 of the AP1000 Safety Analysis Report. The highest decay power observed while actuating ADS4 was ~2.0% for the DEDVI case. The typical pressure at which ADS4 actuates is []^{a,b,c}.

Table A.17 Proposed Initial Conditions for a Full Pressure ADS4 Blowdown Test In APEX-AP1000

Parameter	AP1000	APEX-AP1000	Units	a,b,c
RCS Pressure				
2% Core Decay Power				
Initial CMT Volume				
ADS4 Flow Areas – 100%				
ADS4 Flow Areas – 50%				
IRWST Nominal Liquid Level				
IRWST Head Pressure				

A.7 Upper Plenum Entrainment Scaling

Top-down component-level and bottom-up process-level scaling analyses have been performed to establish the upper plenum geometry and flow conditions that should be modeled in the APEX-AP1000 integral system test facility. Figure A.19 describes the scaling analysis process.

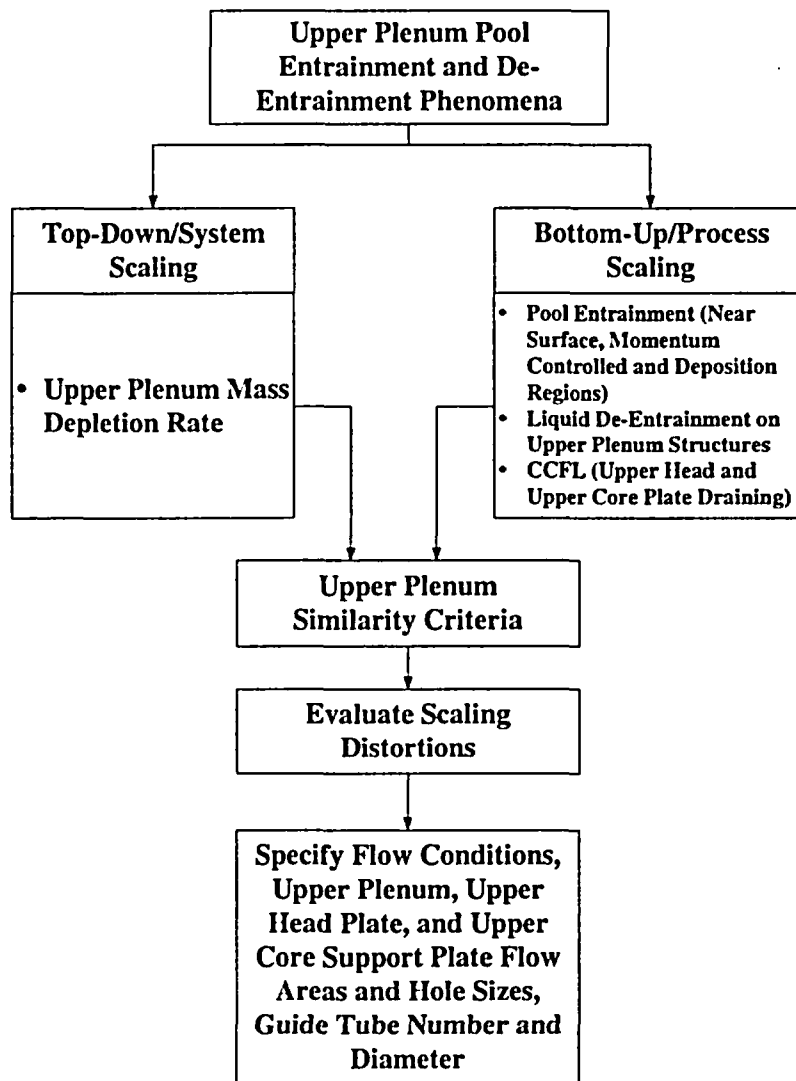


Figure A.19 Upper Plenum Scaling Analysis Flow Chart

The main objective of the analysis was to obtain the scaling ratios that would preserve, on a scaled basis, the rate at which the liquid level in the upper plenum decreases during pool boiling. The top-down scaling analysis resulted in a non-dimensional mass balance equation for the upper plenum control volume. The bottom-up scaling analysis provided the closure relationships for the top-down analysis. In particular, pool boiling entrainment was examined for the near-surface, momentum-dominated and deposition regions of the upper plenum.

A.7.1 Top-Down Scaling Analysis

The control volume shown in Figure A.20 was defined for the upper plenum for the purpose of writing the mass balance equation.

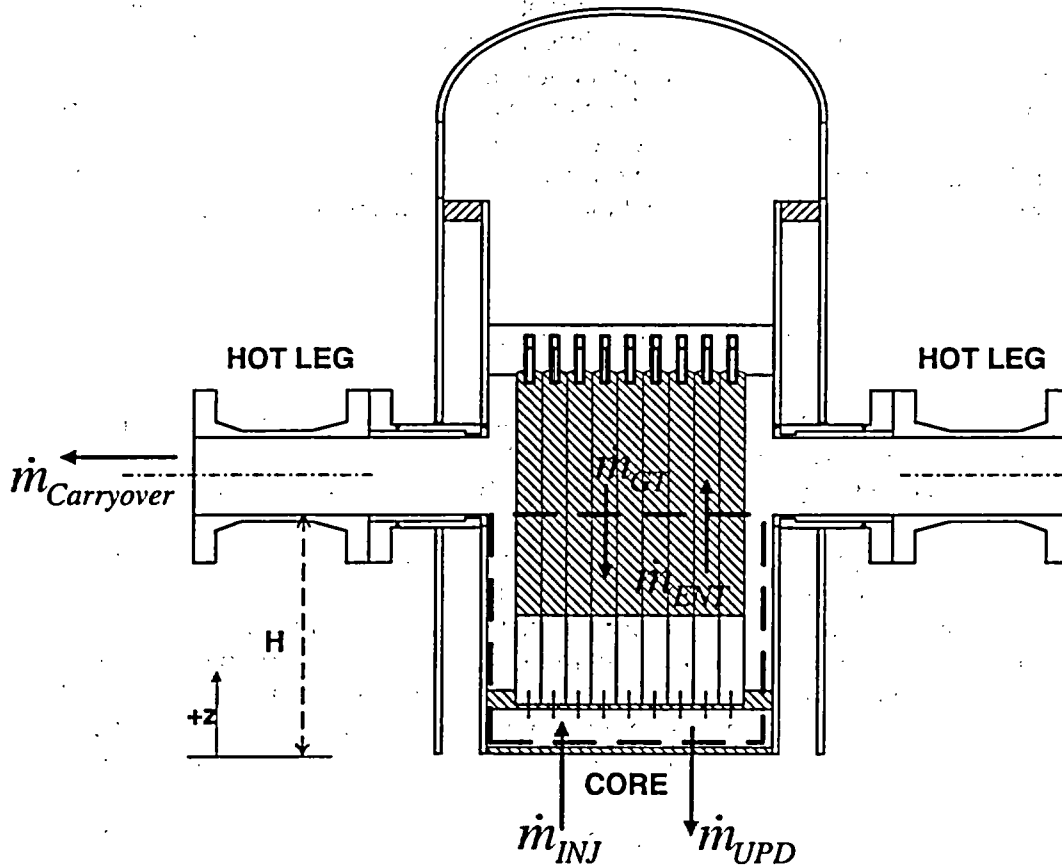


Figure A.20 Upper Plenum Control Volume Located Below the Hot Legs

The *liquid* mass conservation equation for the upper plenum is written as follows:

$$\frac{dM_{UP}}{dt} = \dot{m}_{IN} - \dot{m}_{OUT} \quad (A.169)$$

The upper plenum flow cross-sectional area, a_{UP} , is constant inside the control volume and the liquid is assumed to be incompressible; therefore, liquid density ρ_L is uniform and constant. The vertical upward direction is defined as the z -coordinate. Thus, removing the constants from the derivative on the left-hand side of equation (A.169) yields:

$$a_{UP} \rho_L \frac{dz}{dt} = \dot{m}_{IN} - \dot{m}_{OUT} \quad (A.170)$$

One source of liquid to the control volume is liquid mass flow from the core region due to safety injection. During the later part of ADS4 operation, IRWST injection would be supplying liquid to

the core. A second source of liquid to the upper plenum is de-entrainment on the vertical guide tubes. A third source of liquid mass into the control volume is draining from the upper head through the upper support plate.

The primary path of liquid mass loss from the upper plenum is through the HL. When the liquid level is below the bottom of the HL, pool entrainment results, causing liquid droplets to be carried with the steam out the HL to the ADS4 line. Another source of mass loss is attributable to draining from the upper plenum through the upper core plate back into the core. Loss of upper plenum liquid mass as a result of flashing or boiling as a result of stored energy release from upper plenum structures are not considered applicable during this phase of the transient. Equations for the liquid mass loss and injection terms are presented in the bottom-up scaling analysis. Expanding equation (A.170) to include the individual liquid mass source and sink terms yields:

$$a_{UP} \rho_L \frac{dz}{dt} = \dot{m}_{INJ} + \dot{m}_{GT} - \dot{m}_{ENT} - \dot{m}_{UPD} \quad (A.171)$$

The first term on the right-hand side represents the sum of the DVI injection flows that tend to fill the upper plenum via the downcomer (i.e., CMT, ACC, IRWST, and sump flows). It is the mass flow rate of liquid entering the control volume through the core. The second term on the right-hand side represents the guide tube de-entrainment rate. It is the mass flow rate of liquid that is de-entrained by the upper plenum structure and that eventually drains as a liquid film into the control volume. The third term on the right-hand side is the liquid entrainment rate. It is the mass flow rate of liquid produced by the vapor interaction with the liquid (i.e., near surface, momentum-controlled or deposition pool entrainment). This liquid is carried out of the control volume, where a portion is de-entrained by the guide tubes and the remainder is carried out to the HL. The last term on the right-hand side represents mass flow rate of liquid that drains out of the control volume by gravity through the upper core plate back into the core region.

A.7.1.1 Dimensionless Liquid Mass Balance

Equation (A.171) can be made dimensionless using the following initial and boundary conditions:

$$z_{INJ}^+ = \frac{z}{H} \quad (A.172)$$

where H is the vertical length between the top of the core and the bottom of the HL. The dimensionless injection mass flow rate is given as:

$$\dot{m}_{INJ}^+ = \frac{\dot{m}_{INJ}}{\dot{m}_{INJ,0}} \quad (A.173)$$

The dimensionless guide tube de-entrainment rate is given as:

$$\dot{m}_{GT}^+ = \frac{\dot{m}_{GT}}{\dot{m}_{GT,0}} \quad (A.174)$$

The dimensionless liquid entrainment rate is given as:

$$\dot{m}_{ENT}^+ = \frac{\dot{m}_{ENT}}{\dot{m}_{ENT,O}} \quad (A.175)$$

The dimensionless upper plenum draining rate is given as:

$$\dot{m}_{UPD}^+ = \frac{\dot{m}_{UPD}}{\dot{m}_{UPD,O}} \quad (A.176)$$

Substituting these ratios into equation (A.171) and dividing both sides of the equation by the initial entrainment mass flow rate yields the dimensionless mass balance equation for the upper plenum liquid.

$$\tau_{ENT} \frac{dz^+}{dt} = \Pi_{INJ} \dot{m}_{INJ}^+ + \Pi_{GT} \dot{m}_{GT}^+ - \dot{m}_{ENT}^+ - \Pi_{UPD} \dot{m}_{UPD}^+ \quad (A.177)$$

In this equation, the liquid entrainment reference time scale has been defined as:

$$\tau_{ENT} = \frac{a_{UP} \rho_L H}{\dot{m}_{ENT,O}} \quad (A.178)$$

Thus the dimensionless time coordinate for upper plenum emptying due to liquid entrainment is given by:

$$t^+ = \frac{t}{\tau_{ENT}} \quad (A.179)$$

All of the remaining filling and draining processes are therefore, expressed in terms of the liquid entrainment process. That is, the dimensionless P groups of equation (A.177) are written as:

$$\Pi_{INJ} = \frac{\dot{m}_{INJ,O}}{\dot{m}_{ENT,O}} \quad (A.180)$$

$$\Pi_{GT} = \frac{\dot{m}_{GT,O}}{\dot{m}_{ENT,O}} \quad (A.181)$$

$$\Pi_{UPD} = \frac{\dot{m}_{UPD,O}}{\dot{m}_{ENT,O}} \quad (A.182)$$

Equations (A.178) through (A.182) will be evaluated in the bottom-up scaling analysis.

A.7.1.2 Preserving the Upper Plenum Draining Rate During Integral System Testing

The desired outcome of this scaling analysis is to establish the geometry and flow conditions in APEX that would preserve the upper plenum draining rate when plotted in dimensionless phase space. That is, plotting the upper plenum liquid level history in terms of the dimensionless

spatial coordinate, z^* , and the dimensionless time coordinate, t^* , would yield overlaying curves for the model and the prototype. This condition can be achieved by satisfying the following requirements.

The scenarios are initiated from the same initial condition in dimensionless phase space. In this case, z^* at $t^* = 0$ is 1.

The rate of change (i.e., slope) is preserved in dimensionless phase space. This imposes the following scaling criterion:

$$\left(\frac{dz^*}{dt^*} \right)_R = 1 \quad (\text{A.183})$$

Note that $(z^*)_R$ and $(t^*)_R$ are unity. Satisfying the requirement given by equation (A.183) can only be accomplished by preserving the ratios of the individual P groups on the right-hand side of equation (A.177). The APEX facility transient response was originally designed to operate at one-half time scale ($t_R = 0.5$) which means that the reference time scale ratio, τ_R , must also be one-half to keep $(t^*)_R$ at unity. Because the APEX facility height is fixed at one-quarter scale, and the flow area is roughly fixed at []^{a,b,c}, certain physical limitations have already been established. Nonetheless, minor modifications to the upper plenum structures are possible. To preserve the one-half scale timing of integral system transient behavior, it is desired that:

$$\left(\frac{dz}{dt} \right)_R = \frac{1}{2} \quad (\text{A.184})$$

Substituting equations (A.172) and (A.179) into (A.184) yields:

$$\left(\frac{H}{\tau_{ENT}} \right)_R \left(\frac{dz^*}{dt^*} \right)_R = \frac{1}{2} \quad (\text{A.185})$$

Imposing the requirement given by equation (A.183) yields:

$$\left(\frac{H}{\tau_{ENT}} \right)_R = \frac{1}{2} \quad (\text{A.186})$$

This is a direct result of the one-half time scale requirement. Substituting equation (A.178), assuming fluid property similitude, and rearranging yields the following simple scaling criterion for the upper plenum:

$$\left(\frac{\dot{m}_{ENT,O}}{a_{UP}} \right)_R = \frac{1}{2} \quad (\text{A.187})$$

For the case where liquid entrainment is the dominant mechanism (i.e., the largest mass transfer term on the right-hand side of the balance equation), equation (A.187) coupled with a correlation for liquid entrainment represents the governing scaling criterion. The next section presents the bottom-up scaling analysis and includes liquid entrainment equations that can be used to provide closure to equation (A.187).

A.7.2 Bottom-up Scaling Analysis

This section examines the following upper plenum filling and draining mechanisms:

- pool entrainment
- guide tube de-entrainment
- the effects of counter-current flow limitations (CCFL) on upper plenum draining

The phenomenon of interest to this study is upper plenum pool entrainment. The following section presents a review of the phenomenon and the existing predictive models.

A.7.2.1 Pool Entrainment

The basic equations of pool entrainment will be derived to provide a theoretical context for their application to the scaling analysis. Here, the discussion will consist of a brief derivation of Ishii's pool entrainment equations. Following this derivation, certain questions regarding the application of these equations in scaling the AP1000 experiments will be addressed. In particular, it will be necessary to examine the vertical extent of various entrainment regions, the flow regime in the pool, the question of flooding, the phenomena of re-entrainment from a falling film, and the issue of enhanced deposition as a result of the lateral motion of the flow. In Ishii's pool entrainment model, the entrainment is defined as the ratio of the droplet to vapor mass flux, and represented phenomenologically by the following equation [Ref. 16]:

$$E_{fg}(h, j_g) = \frac{\rho_f j_f}{\rho_g j_g} = \frac{\dot{\epsilon}(j_g)}{\rho_g j_g} \int_0^{D_{max}} f_D(D, j_g) \int_{v_h}^{\infty} g(v_i, D, j_g) dv_i dD \quad (A.188)$$

Here $\dot{\epsilon}$ is the mass flux of droplets at the liquid surface which is a function of the vapor superficial velocity, j_g . As the droplets generated at the surface vary in size from zero to some maximum diameter, a distribution function for the droplet diameters is employed. This function, f_D , gives the fraction of droplets within any given range, dD , and is itself a function of j_g . Obviously, since all the droplets must fall within the range, $0 \leq D \leq D_{max}$:

$$\int_0^{D_{max}} f_D(D, j_g) dD = 1 \quad (A.189)$$

Furthermore, the droplets so generated will have an initial velocity, v_i , which depends upon both the superficial velocity, j_g , and the droplet diameter, D . Hence, a distribution function, g , is needed for the initial velocity, such that:

$$\int_0^{\infty} g(v_i, D, j_g) dv_i = 1 \quad (A.190)$$

As written, equation (A.189) depends upon the maximum droplet diameter to define an upper limit of integration. By using the pool entrainment data to determine various experimental constants, Ishii found the best agreement for:

$$D_{max}^* = 7.24 j_g^{*-1} \quad (A.191)$$

In this equation, the asterisk denotes a dimensionless variable, such that:

$$D^* = \frac{D}{\sqrt{\frac{\sigma}{g \Delta \rho}}} \quad (\text{A.192})$$

and

$$j_g^* = \frac{j_g}{\left[\frac{\sigma g \Delta \rho}{\rho_g^2} \right]^{1/4}} \quad (\text{A.193})$$

With regard to the second integral in equation (A.188), the lower limit, v_h , is the minimum initial velocity required for a droplet of diameter, D , to reach height, h . With regard to its dependence on the droplet diameter, $v_h = 0$, for droplets in the range $0 \leq D \leq D_c$, where the critical diameter, D_c , is the diameter of the largest droplet which can be suspended by vapor drag. Thus, the droplets within this range can reach height h by virtue of drag alone and hence need no initial velocity. On the other hand, droplets in the range $D_c < D \leq D_{max}$ are too large to be suspended by vapor drag and hence fall back into the pool after losing their initial momentum. Consequently, these droplets must possess a minimal initial velocity, v_h , to reach the height in question. With regard to these calculations, the critical droplet diameter, D_c , is first obtained by balancing the weight of the droplet with the vapor drag:

$$g \Delta \rho \pi \frac{D_c^3}{6} = \pi \frac{D_c^2}{4} C_D \frac{1}{2} \rho_g j_g^2 \quad (\text{A.194})$$

where

$$C_D = \frac{10.76}{Re^{1/2}} \quad (\text{A.195})$$

Solving equation (A.194) for the critical diameter subject to the drag relation given by equation (A.195) yields:

$$D_c^* = 4 j_g^* (N_{\mu_f})^{1/3} \quad (\text{A.196})$$

where the viscosity number is given by:

$$N_{\mu_f} = \frac{\mu_g}{(\rho_g \sigma \sqrt{\sigma / g \Delta \rho})^{1/2}} \quad (\text{A.197})$$

As mentioned above, $v_h = 0$ for diameters within the range $0 \leq D \leq D_c$. For diameters within the range $D_c < D \leq D_{max}$, v_h is determined by neglecting drag compared to gravity and calculating the velocity needed to reach height h .

$$v_h = \sqrt{2gh \frac{\Delta \rho}{\rho_f}}; \text{ for } D_c < D \leq D_{max} \quad (\text{A.198})$$

Thus, in terms of dimensionless parameters:

$$v_h^* = 0 ; \text{ for } 0 \leq D^* < D_c^* \quad (\text{A.199})$$

and

$$v_h^* = \sqrt{2h^*} \left[\frac{\rho_g}{\rho_l} \right]^{1/2} ; \text{ for } D_c^* < D^* \leq D_{\max}^* \quad (\text{A.200})$$

Having discussed the basic equation and the limits of integration, it remains to determine expressions for the surface mass flux, $\dot{\epsilon}$, the diameter distribution function, f_D , and the velocity distribution function, g . To this end, observe first of all that near the water surface, v_h goes to zero for all droplet diameters in accordance with equations (A.199) and (A.200). Hence, by virtue of equations (A.188), (A.189), and (A.190):

$$E_{fg}(0, j_g) = \frac{\dot{\epsilon}(j_g)}{\rho_g j_g} \int_0^{D_{\max}^*} f_D(D, j_g) \int_0^\infty g(v_i, D, j_g) dv_i dD = \frac{\dot{\epsilon}(j_g)}{\rho_g j_g} \quad (\text{A.201})$$

Using the limited data available for near surface entrainment, Ishii determined that [Ref. 16]:

$$E_{fg}(0, j_g) = \frac{\dot{\epsilon}(j_g)}{\rho_g j_g} = 4.84 \times 10^{-3} \left[\frac{\rho_g}{\Delta \rho} \right]^{-1.0} \quad (\text{A.202})$$

Thus:

$$\dot{\epsilon}(j_g) = 4.84 \times 10^{-3} \rho_g j_g \left[\frac{\rho_g}{\Delta \rho} \right]^{-1.0} \quad (\text{A.203})$$

To determine the distribution function, f_D , observe that after the droplets in the supercritical range have fallen back into the pool, one is left with droplets in the subcritical range. Since these droplets are sufficiently small to be suspended by vapor drag, they do not fall back into the pool. Consequently, the entrainment above a certain height remains constant except for the phenomenon of deposition on solid surfaces. Moreover, since these droplets are in the range $0 \leq D \leq D_c$, $v_h = 0$ by virtue of equation (A.199), and equation (A.188) can be integrated for a subrange of droplet sizes subject to equation (A.190) to yield:

$$\frac{\dot{\epsilon}(j_g)}{\rho_g j_g} \int_0^D f_D(D, j_g) \int_0^\infty g(v_i, D, j_g) dv_i dD = \frac{\dot{\epsilon}(j_g)}{\rho_g j_g} \int_0^D f_D(D, j_g) dD \quad (\text{A.204})$$

Now, on the basis of experimental data, it has been determined that:

$$\frac{\dot{\epsilon}(j_g)}{\rho_g j_g} \int_0^D f_D(D, j_g) dD = C(D^*)^{1.5} (j_g^*)^{1.5} \quad (\text{A.205})$$

By differentiating this equation with respect to D , one obtains:

$$\frac{\dot{\epsilon}(j_g)}{\rho_g j_g} f_D(D, j_g) = \frac{1.5C}{\sqrt{\sigma/g\Delta\rho}} (D^*)^{0.5} (j_g^*)^{1.5} \quad (\text{A.206})$$

By comparing to the experimental data and utilizing equation (A.203), Ishii obtained:

$$f_D(D, j_g) = \frac{0.077}{\sqrt{\sigma/g\Delta\rho}} (D^*)^{0.5} (j_g^*)^{1.5} \quad (\text{A.207})$$

To obtain the velocity distribution function, Ishii first made a rough model based on the breakup of liquid ligaments to determine the initial velocity of a droplet of diameter D in a vapor stream of superficial velocity j_g . Such a breakup mechanism is consistent only with churn flow in the pool and, therefore, is inapplicable for pools in the bubbly or annular flow regimes. Accordingly, Ishii's entire model is limited to situations where there is churn flow in the pool because the initial velocity distribution derived from this assumption impacts all the subsequent correlations. With respect to this initial velocity, Ishii set up a rough equation based on the above mechanism and utilized experimental data to obtain [Ref. 16]:

$$v_i^* = 75.17 j_g^{*1/4} N_{\mu_f}^{1/4} D^{*-1/4} \left[\frac{\rho_g}{\rho_f} \right]^{1/2} D_H^{*0.21} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.115} \quad (\text{A.208})$$

Moreover, since no information was available on the distribution of initial velocities, Ishii assumed that a single initial velocity characterizes a droplet of a given size, D , such that the distribution reduces to a delta function:

$$g(v_i, D, j_g) = \delta \left(v_i^* - 75.17 j_g^{*1/4} N_{\mu_f}^{1/4} D^{*-1/4} \left[\frac{\rho_g}{\rho_f} \right]^{1/2} D_H^{*0.21} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.115} \right) \quad (\text{A.209})$$

Having determined expressions for all parameters in equation (A.188), the entrainment as a function of height can now be determined. To this end, observe from equation (A.208) that the initial velocity of a given droplet decreases with increasing size. Nonetheless, since there is a maximum droplet size, even the heaviest droplets will possess a minimal initial velocity and, therefore, will rise a definite height before falling back into the pool. Thus, there will be no fall out before a minimum height is attained, so there will be a near-surface region where the entrainment is constant. Above this height, entrainment will decrease as first the heavier and then the lighter droplets within the supercritical range fall back into the pool. This second region is, therefore, called the momentum-controlled region because the entrainment at any given height is dependent upon the droplets having sufficient initial momentum to reach the height in question. Finally, after all the supercritical droplets have fallen out of the flow, the entrainment will consist only of those droplets small enough to be suspended by the vapor drag. Thus, above a certain height the droplets stop falling back into the pool and are taken out of the flow entirely as a result of deposition on solid surfaces. For this reason, the third region is referred to as the deposition-controlled region.

The extent of the near-surface region can be determined by setting the initial velocity of the largest droplets equal to the initial velocity, v_h , needed to attain a particular height, h , and then solving for this height. The velocity of the largest droplets can be obtained by substituting the maximum diameter from equation (A.50) into equation (A.208). As usual, v_h is given by equation (A.200):

$$\sqrt{2h^*} \left[\frac{\rho_g}{\rho_f} \right]^{1/2} = 75.17 j_g^{1/4} N_{\mu_f}^{1/4} \left[7.24 j_g^{-1} \right]^{-1/4} \left[\frac{\rho_g}{\rho_f} \right]^{1/2} D_H^{*0.21} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.115} \quad (A.210)$$

From this relation the near surface region can be shown to extend from:

$$0 \leq h^* \leq 1.038 \times 10^3 j_g^* N_{\mu_f}^{1/2} D_H^{*0.42} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.23} \quad (A.211)$$

where the upper limit on h^* is obtained by solving equation (A.210). Within this region, v_h is effectively zero since $v_h < v_i$ for all droplet sizes. Thus, using equations (A.188) and (A.202), the entrainment becomes:

$$E_{fg}(h, j_g) = \frac{\dot{\epsilon}(j_g)}{\rho_g j_g} \int_0^{D_{max}} f_D(D, j_g) \int_{v_h}^{\infty} g(v_i, D, j_g) dv_i dD = \frac{\dot{\epsilon}(j_g)}{\rho_g j_g} = 4.84 \times 10^{-3} \left[\frac{\rho_g}{\Delta\rho} \right]^{-1.0} \quad (A.212)$$

Above the near-surface region is the momentum-controlled region where the heavier droplets within the supercritical range progressively fall back into the pool. The lower limit for this region is given by the right-hand side of equation (A.211). The upper limit is determined by the point at which all the supercritical droplets have fallen out of the stream so that only subcritical droplets remain. To determine this limit, it is first necessary to substitute equation (A.196) into equation (A.208) to get the initial velocity of a critically sized droplet and then to set the resulting expression equal to the initial velocity, v_h , given by equation (A.200). When these steps are performed, the following expression is obtained:

$$\sqrt{2h^*} \left[\frac{\rho_g}{\rho_f} \right]^{1/2} = 75.17 j_g^{1/4} N_{\mu_f}^{1/4} \left[4 j_g (N_{\mu_f})^{1/3} \right]^{-1/4} \left[\frac{\rho_g}{\rho_f} \right]^{1/2} D_H^{*0.21} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.115} \quad (A.213)$$

On the basis of this relation and equation (A.196), the momentum-controlled region can be shown to extend from:

$$1.038 \times 10^3 j_g^* N_{\mu_f}^{1/2} D_H^{*0.42} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.23} \leq h^* \leq 1.413 \times 10^3 N_{\mu_f}^{1/3} D_H^{*0.42} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.23} \quad (A.214)$$

To determine the entrainment as a function of height within these limits, it is first necessary to determine the diameter of the largest supercritical droplet having the initial velocity needed to reach the point in question. Denoting this diameter D_h , substituting the variable D_h into equation (A.208), and setting the result equal to equation (A.200), yields the following expression:

$$\sqrt{2h^*} \left[\frac{\rho_g}{\rho_f} \right]^{1/2} = 75.17 j_g^{*1/4} N_{\mu_t}^{1/4} [D_h^*]^{-1/4} \left[\frac{\rho_g}{\rho_f} \right]^{1/2} D_H^{*0.21} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.115} \quad (\text{A.215})$$

In this expression, D_h should not be confused with the hydraulic diameter D_H . If equation (A.215) is solved for D_h , one obtains:

$$D_h^* = \frac{(75.17)^4}{2^2} \frac{j_g^*}{h^{*2}} N_{\mu_t} D_H^{*0.84} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.46} \quad (\text{A.216})$$

Now, since all droplets within the range $D_h < D \leq D_{max}$ lack sufficient initial momentum to reach height h , only diameters within the range $0 \leq D \leq D_h$ remain within the flow. Moreover, since all droplets remaining within the flow have initial velocities greater than or equal to v_h , v_h is effectively zero for these droplets. Hence, the entrainment at height h is given by:

$$E_{fg}(h, j_g) = \frac{\dot{e}(j_g)}{\rho_g j_g} \int_0^{D_h} f_D(D, j_g) \int_{v_h}^{\infty} g(v_i, D, j_g) dv_i dD = \frac{\dot{e}(j_g)}{\rho_g j_g} \int_0^{D_h} f_D(D, j_g) dD \quad (\text{A.217})$$

Utilizing equations (A.202) and (A.207), and switching to dimensionless coordinates yields:

$$E_{fg}(h, j_g) = 4.84 \times 10^{-3} \left[\frac{\rho_g}{\Delta\rho} \right]^{-1.0} \int_0^{D_h^*} 0.077 (D^*)^{0.5} (j_g^*)^{1.5} dD^* \quad (\text{A.218})$$

Finally, integrating this equation subject to the expression for D_h given by equation (A.216) yields the entrainment as a function of height in the momentum-controlled region:

$$E_{fg}(h, j_g) = 5.417 \times 10^6 \frac{j_g^{*3}}{h^{*3}} N_{\mu_t}^{1.5} D_H^{*1.25} \left[\frac{\rho_g}{\Delta\rho} \right]^{-0.31} \quad (\text{A.219})$$

Above the momentum-controlled region lies the deposition-controlled region, which only droplets within the subcritical diameter range can reach. Since these droplets can be suspended entirely by vapor drag, $v_h = 0$ for these droplets in accordance with equation (A.191). Hence, the entrainment is given by:

$$E_{fg}(h, j_g) = \frac{\dot{e}(j_g)}{\rho_g j_g} \int_0^{D_c} f_D(D, j_g) \int_{v_h}^{\infty} g(v_i, D, j_g) dv_i dD = \frac{\dot{e}(j_g)}{\rho_g j_g} \int_0^{D_c} f_D(D, j_g) dD \quad (\text{A.220})$$

where D_c is the diameter of a critically sized droplet. Utilizing equations (A.202) and (A.207), and switching to dimensionless coordinates yields:

$$E_{fg}(h, j_g) = 4.84 \times 10^{-3} \left[\frac{\rho_g}{\Delta\rho} \right]^{-1.0} \int_0^{D_c^*} 0.077 (D^*)^{0.5} (j_g^*)^{1.5} dD^* \quad (\text{A.221})$$

Integrating this equation subject to the expression for D_c given by equation (A.196) gives the entrainment in the deposition-controlled region:

$$E_{fg}(h, j_g) = 1.988 \times 10^{-3} j_g^*{}^3 N_{\mu_f}^{1/2} \left[\frac{\rho_g}{\Delta\rho} \right]^{-1.0} \quad (\text{A.222})$$

As written, equation (A.222) predicts that entrainment remains constant with height. However, because of deposition on solid surfaces, the entrainment will decrease. Ishii makes the case that the deposition rate should be proportional to the entrainment itself, so that the entrainment decreases exponentially with height. On the basis of experimental data, Ishii determines an exponential attenuation term and adjusts the leading constant to yield:

$$E_{fg}(h, j_g) = 7.13 \times 10^{-4} j_g^*{}^3 N_{\mu_f}^{1/2} \left[\frac{\rho_g}{\Delta\rho} \right]^{-1.0} \exp(-0.205 (h/D_H)) \quad (\text{A.223})$$

Then, to ensure a smooth transition at the boundary and hence consistency among his equations, Ishii sets equation (A.223) for the deposition-controlled region equal to equation (A.219) for the momentum-controlled region to obtain the following equation for the transition height [Ref. 16]:

$$h^* \exp(-0.068 (h^*/D_H^*)) = 1.97 \times 10^3 N_{\mu_f}^{1/3} D_H^{*0.42} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.23} \quad (\text{A.224})$$

When the deposition term is small, the equation can be approximated as:

$$h^* = 1.97 \times 10^3 N_{\mu_f}^{1/3} D_H^{*0.42} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.23} \quad (\text{A.225})$$

The entrainment correlations, E_{fg} , listed above can be expressed in terms of mass flow rate using the following definition:

$$E_{fg} = \frac{\rho_f j_f}{\rho_g j_g} \quad (\text{A.226})$$

and the liquid mass continuity equation:

$$\dot{m}_{ENT} = \rho_f j_f a_{up} \quad (\text{A.227})$$

Substituting equation (A.226) into (A.227) yields:

$$\dot{m}_{ENT} = \rho_g j_g E_{fg} a_{up} \quad (\text{A.228})$$

This places the entrainment equations in the form needed to evaluate the dimensionless groups obtained in the top-down scaling analysis.

In summary, based on Ishii's pool entrainment model, the following entrainment relations are predicted [Ref. 16]:

Near-Surface Region:

$$0 \leq h^* \leq 1.038 \times 10^3 j_g^* N_{\mu_t}^{1/2} D_H^{*0.42} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.23} \quad (\text{A.229})$$

$$E_{fg}(h, j_g) = 4.84 \times 10^{-3} \left[\frac{\rho_g}{\Delta\rho} \right]^{-1.0} \quad (\text{A.230})$$

$$\dot{m}_{ENT} = 4.84 \times 10^{-3} \Delta\rho j_g a_{up} \quad (\text{A.231})$$

Momentum-Controlled Region:

$$1.038 \times 10^3 j_g^* N_{\mu_t}^{1/2} D_H^{*0.42} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.23} \leq h^* \leq 1.97 \times 10^3 N_{\mu_t}^{1/3} D_H^{*0.42} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.23} \quad (\text{A.232})$$

$$E_{fg}(h, j_g) = 5.603 \times 10^6 \frac{j_g^{*3}}{h^{*3}} N_{\mu_t}^{1.5} D_H^{*1.25} \left[\frac{\rho_g}{\Delta\rho} \right]^{-0.31} \quad (\text{A.233})$$

$$\dot{m}_{ENT} = 5.603 \times 10^6 \rho_g a_{up} \frac{j_g^{*4}}{h^{*3}} \left[\frac{\sigma g \Delta\rho}{\rho_g^2} \right]^{.25} N_{\mu_t}^{1.5} D_H^{*1.25} \left[\frac{\rho_g}{\Delta\rho} \right]^{-0.31} \quad (\text{A.234})$$

Deposition-Controlled Region:

$$1.97 \times 10^3 N_{\mu_t}^{1/3} D_H^{*0.42} \left[\frac{\rho_g}{\Delta\rho} \right]^{0.23} \leq h^* \quad (\text{A.235})$$

$$E_{fg}(h, j_g) = 7.13 \times 10^{-4} j_g^{*3} N_{\mu_t}^{1/2} \left[\frac{\rho_g}{\Delta\rho} \right]^{-1.0} \exp(-0.205 (h/D_H)) \quad (\text{A.236})$$

$$\dot{m}_{ENT} = 7.13 \times 10^{-4} \rho_g a_{up} j_g^{*4} \left[\frac{\sigma g \Delta\rho}{\rho_g^2} \right]^{.25} N_{\mu_t}^{1/2} \left[\frac{\rho_g}{\Delta\rho} \right]^{-1.0} \exp(-0.205 (h/D_H)) \quad (\text{A.237})$$

As previously mentioned, these equations are built upon a particular entrainment mechanism under the assumed conditions of churn flow in the pool. Thus, the validity of these equations hinges upon the satisfaction of this initial assumption.

A.7.2.2 Upper Plenum Liquid Entrainment Rate Scaling Criteria

The upper plenum geometry and flow conditions can be determined by substituting the entrainment correlations into the scaling criterion given by equation (A.187).

Near-Surface Region:

Substituting equation (A.231) into (A.187) and assuming fluid property similitude, yields the following relation:

$$j_{g,R} = \frac{1}{2} \quad (A.238)$$

This ratio is established by controlling the core power and fixing the upper plenum flow area. Performing a simple steady-state energy balance for the core yields:

$$\rho_g j_g a_{UP} (h_{fg} - \Delta h_{SC}) = \dot{q} \quad (A.239)$$

where Δh_{SC} is the core subcooling, and \dot{q} is the core power. Rearranging and substituting into equation (A.238) yields:

$$\left(\frac{\dot{q}}{a_{UP}} \right)_R = \frac{1}{2} \quad (A.240)$$

Currently, the APEX upper plenum flow area, a_{UP} , ratio is approximately equal to $j^{a,b,c}$. Thus, the core power scaling ratio becomes:

$$\dot{q}_R = \frac{1}{96} \quad (A.241)$$

The requirements for liquid entrainment in the near-surface region can be easily met.

Momentum-Controlled Region:

Substituting equation (A.234) into equation (A.187) and assuming fluid property similitude yields:

$$\left(\frac{j_g^4 D_H^{1.25}}{h^3} \right)_R = \frac{1}{2} \quad (A.242)$$

Fixing $j_{g,R}$ to 1:2 and h_R to 1:4 yields the following scaling ratio for the hydraulic diameter of the upper plenum:

$$D_{H,R} = \left(\frac{1}{8} \right)^{0.8} = 0.1895 \quad (A.243)$$

This new scaling criterion shall be applied in the upper plenum design section.

Deposition-Controlled Region:

Substituting equation (A.237) into equation (A.187) and assuming fluid property similitude yields:

$$\left[j_g^4 \exp\left(-.205 \frac{h}{D_H}\right) \right]_R = \frac{1}{2} \quad (\text{A.244})$$

The form of this criterion requires that it be assessed numerically for the model and the prototype.

A.7.2.3 *Scaling Criterion for Lateral De-Entrainment*

A study of droplet de-entrainment on vertical tubes in droplet cross-flow was performed by Dallman and Kirchner at Los Alamos Scientific Laboratory in 1980 [Ref. 17]. The study included both analytical and experimental research. Droplets of a known size were sprayed perpendicular to vertical conduits situated in a draft induced wind tunnel. The two geometries examined were square channels (76.2 mm square) and cylindrical tubes (25.4 mm, 63.5 mm, and 101.6 mm diameters). The air velocities were varied from 0 m/s to 14 m/s and the liquid droplet velocities were varied from 10 m/s to 15 m/s. It was found that the de-entrainment efficiency for a single tube was only weakly dependent on the tube diameter, air velocity, droplet mean velocity, total liquid flow rates for air velocities below 14 m/s, and droplet mass flux rates greater than 2 kg/(m²-s). In fact, the de-entrainment rate was nearly a constant value of 0.19 for cylinders and 0.27 for square tubes for this range. That is:

$$\eta_l = 0.19 \text{ (For Cylinders)} \quad (\text{A.245})$$

and

$$\eta_l = 0.27 \text{ (For a 76.2 mm Square Tube)} \quad (\text{A.246})$$

The authors cited the work of Chen [Ref. 18] as providing a method of extrapolating the single tube data to an array of tubes. Namely, the de-entrainment efficiency for horizontal droplet flow through "k" rows of identical vertical tubes with a constant diameter to pitch ratio is:

$$\eta_k = A[1 - C(1 - \eta_l(1 + 4.5(D/P)^2)^k] \quad (\text{A.247})$$

where C is a geometric factor dependent on pitch to diameter ratios. The constant A is unity for a staggered array with no line of sight through the array. Equation (A.247) indicates that preserving the upper plenum guide tube de-entrainment efficiency requires preserving the guide tube diameter to pitch ratio and the number of guide tube rows. Therefore, the first criterion can be written as:

$$(D/P)_R = 1 \quad (\text{A.248})$$

For the diameter-to-pitch ratios in this study, very high entrainment efficiencies (i.e., greater than 90%) are achieved with just three staggered rows of guide tubes. Therefore, the number of guide tube rows beyond three does not contribute much to the de-entrainment process. Furthermore, an examination of the AP1000 upper plenum structure geometry reveals the following [Refs. 16, 17, and 18]:

- (1) The upper core plate includes a significant number of holes at its periphery. De-entrainment of liquid from the peripheral holes will occur on the core barrel walls, because there are no guide tubes to impede the flow.
- (2) There are several []^{a,b,c} diameter flow holes located adjacent to each HL. No de-entrainment will occur at those sites. Thus, the entrainment efficiency at those sites is zero. Modeling of those flow holes in the APEX test facility will be important.
- (3) Liquid from the central internal flow holes will be de-entrained at a relatively high de-entrainment efficiency (i.e., on the guide tubes). Thus, the flow through the peripheral flow holes will dominate the behavior.
- (4) The flow path of least resistance for the fluid is radially outward toward the periphery of the upper internals.

The upper plenum can be effectively divided into two zones: a peripheral zone that exhibits no de-entrainment and an internal guide tube zone with a relatively high de-entrainment efficiency. Rather than preserving the row numbers, the scaling approach shall be to preserve the flow area averaged de-entrainment efficiency for the internal guide tube zone. That is, the following scaling criterion will be applied:

$$\eta_{\text{eff},R} = 1 \quad (\text{A.249})$$

Effective De-Entrainment Efficiency

For purpose of this analysis, the AP1000 guide tube bundle has been divided into five flow zones, from $i = 4$ at the center of the upper plenum to $i = 0$ at the periphery of the upper plenum. The total liquid mass flow rate entering the flow zones through the upper core plate and traveling to the periphery of the guide tube bundle is given by:

$$\dot{m}_{\text{Periphery}} = \sum \dot{m}_i (1 - \eta_k)_i \quad (\text{A.250})$$

where k represents the number of guide tube rows between a flow zone and the guide tube bundle periphery. For the AP1000, the upper plenum flow zones have been selected such that $k = i$. Dividing by the total liquid mass flow rate through the upper core plate yields the fraction of entrained liquid reaching the periphery. One minus this value yields the equation for the desired effective de-entrainment efficiency. That is:

$$\eta_{\text{eff}} = 1 - \frac{\sum \dot{m}_i (1 - \eta_k)_i}{\dot{m}_{\text{UCP}}} \quad (\text{A.251})$$

Substituting equation (A.247) into (A.251) yields:

$$\eta_{eff} = 1 - \sum \left(\frac{\dot{m}_i}{\dot{m}_{UCP}} \right) [1 - A(1 - C\Phi^k)]_i \quad (A.252)$$

where:

$$\Phi = 1 - \eta_i [1 + 4.5(D/P)^2] \quad (A.253)$$

Furthermore, for the case of a constant inlet mass flux, ρv , equation (A.253) becomes a flow area averaged de-entrainment efficiency:

$$\eta_{eff} = 1 - \sum \left(\frac{a_i}{a_{UCP}} \right) [1 - A(1 - C\Phi^k)]_i \quad (A.254)$$

For the case of A and C equal to 1, and $i = k$, this equation reduces to:

$$\eta_{eff} = 1 - \sum \left(\frac{a_i}{a_{UCP}} \right) \Phi^i \quad (A.255)$$

Equations (A.247) and (A.249) shall be used to help scale the lateral de-entrainment phenomenon.

A.7.2.4 *Scaling Criterion for the Upper Core Plate*

The two key phenomena to be preserved by scaling the upper core plate flow holes are:

- Upper plenum flow distribution
- Counter-current flooding limitation (CCFL) at the core upper support plate holes.

Flow through the upper core plate at the guide tube bundle periphery will dominate the entrainment behavior in the upper plenum. In particular, the flow area directly adjacent to the HLs has unimpeded access to the HLs. Thus, preserving the flow distribution in the upper core plate will be essential to proper simulation of the entrainment behavior in the upper plenum. The following scaling criterion will be implemented:

$$\left(\frac{a_{Periphery}}{a_{UCP}} \right)_R = 1 \quad (A.256)$$

Similarly, the upper core plate flow area at the entrance to the HLs shall also be preserved as follows:

$$\left(\frac{a_{HL}}{a_{UCP}} \right)_R = 1 \quad (A.257)$$

Preserving the counter-current flooding behavior in the upper core plate requires that the Kutateladze number flooding limit, defined in terms of j_g^* in this analysis, be preserved in APEX. That is:

$$\frac{j_g}{\left[\frac{\sigma g \Delta \rho}{\rho_g^2} \right]^{1/4}} = 4 \quad (\text{A.258})$$

For the condition of fluid property similitude, properly matching the Kutateladze number requires that j_g in APEX match that in AP1000. That is:

$$(j_{g,UCP})_R = 1 \quad (\text{A.259})$$

Thus, the flow area of the APEX upper core plate must be scaled as 1:96, as follows:

$$(a_{UCP})_R = \frac{1}{96} \quad (\text{A.260})$$

Furthermore, the minimum upper core plate hole diameter must be greater than ~2.0 inches, so that the onset of the flooding behavior is not dependent on the hole diameter.

A.7.2.5 *Scaling Criterion for the Upper Support Plate*

The upper support plate separates the upper plenum from the reactor vessel head. The plate provides support for the control rod guide tubes and includes 12 []^{a,b,c} diameter holes that permit the upper head to drain into the upper plenum. During the pool entrainment process, it is expected that the upper head will be empty of liquid. Nonetheless, it has been included to document the scaling basis for this component.

Because the flow area represented by the drain holes is quite small, the flooding behavior and flow distribution cannot both be simultaneously preserved. Since the upper head is essentially a dead-ended volume (there is a small bypass flow path from the upper head to the upper downcomer), flooding behavior will not be as important as the flow distribution. That is, CCFL is not expected to occur in the plate. The dominant phenomenon will be the pressurized draining of the upper head as a result of the flashing of liquid during a depressurization event. As a result, the drain hole number and distribution will be preserved and the flow area will be scaled as follows:

$$(a_{USP})_R = \frac{1}{48} \quad (\text{A.261})$$

A.7.2.6 Design of APEX Upper Plenum Guide Tube Bundle, Upper Core Plate, and Upper Support Plate

Based on the top-down and bottom-up scaling analyses presented in the previous sections, the following scaling approach was adopted for the upper plenum guide tubes, upper core plate, and upper support plate:

- Preserve the upper plenum hydraulic diameter ratio using equation (A.243).
- Preserve the local upper plenum subchannel hydraulic diameter ratio using equation (A.243).
- Preserve the total upper plenum flow area based on []^{a,b,c} flow area scaling.
- Preserve the guide tube diameter to pitch ratio using equation (A.248).
- Preserve the effective de-entrainment efficiency for the guide tube bundle using equation (A.249).
- Preserve the upper core plate flow area distribution using equations (A.256) and (A.257).
- Preserve the vapor volumetric flux, j_g , in the upper core plate holes using equation (A.260).
- Preserve the upper support plate flow distribution and flow area using equation (A.261).

With regard to the scaling basis for the upper plenum guide tube bundle, the momentum-controlled entrainment scaling criterion given by equation (A.243) has been selected to guide the modification to the APEX upper internals. The basis for this selection is as follows. The near surface entrainment rates can be properly simulated in APEX solely by maintaining j_{gR} at a constant value of 0.5. In that sense, no modification to the facility would be needed. However, the momentum-controlled entrainment rates can only be matched by preserving both the j_{gR} and the hydraulic diameter ratios. It will be shown that the deposition-controlled region is both unimportant and not achievable in the one-quarter length scale APEX facility.

Figure A.21 depicts the upper core plate geometry. There are a total of 13 flow holes. The six holes on the periphery are 1.91 inch in diameter and represent approximately 37% of the total upper core plate flow area, compared to 38% in the AP1000. The flow holes at the entrance of each HL represent 6.2% of the total flow area as in the AP1000.



Figure A.21 APEX Upper Core Plate Geometry

Figure A.22 illustrates the APEX upper core plate guide tube pitch and diameter. Figure A.23 presents the APEX upper support plate flow hole location. Table A.18 presents the revised upper plenum geometry design based on matching the scaling criteria given above.

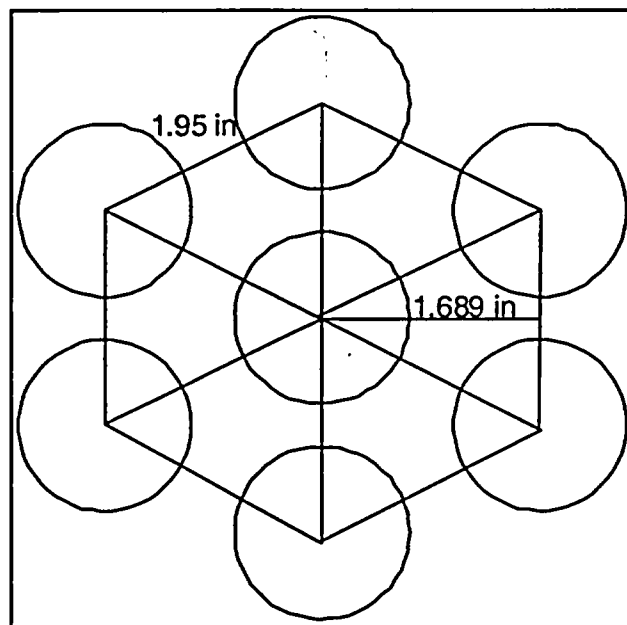


Figure A.22 APEX Upper Plenum Guide Tube Pitch and Diameter

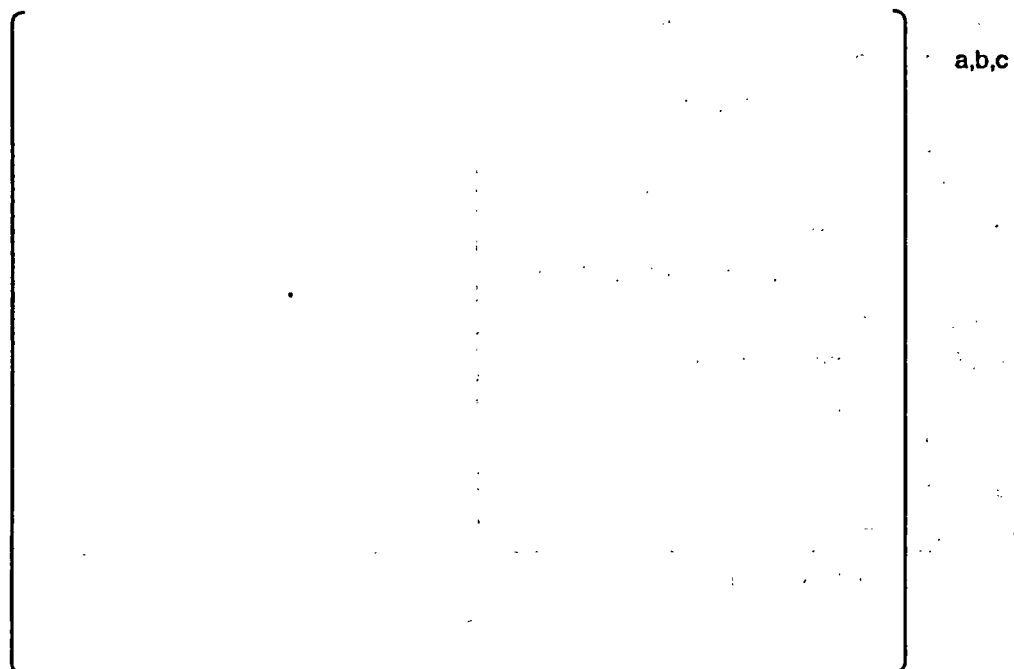


Figure A.23 APEX Upper Support Plate Flow Hole Locations

Table 18 Comparison of the APEX and AP1000 Upper Plenum Geometries

Component	AP1000	APEX	Units	a,b,c
UPPER PLENUM				
Core Barrel Inside Diameter				
Length*				
Flow Area with Internals				
Total Wetted Perimeter				
Total Hydraulic Diameter				
SUPPORT COLUMNS				
Number				
Diameter				
GUIDE TUBES				
Number				
Pitch				
Equivalent Diameter				
Pitch-to-Diameter Ratio				
Subchannel Flow Area				
Subchannel Wetted Perimeter				
Subchannel Hydraulic Diameter				
UPPER CORE PLATE				
Number of Large Thru Holes				
Total Thru Hole Flow Area				
Number of Guide Tube Flow Holes				
Total Guide Tube Flow Area				
Number of Support Column Flow Holes				
Total Support Column Flow Area				
Total Upper Core Plate Flow Area				
Peripheral Flow Area				
Ratio of Peripheral Flow Area to Total Area				
HL Entrance Flow Area				
Ratio of HL Entrance Flow Area to Total Area				
UPPER SUPPORT PLATE				
Number of Holes				
Hole Diameter				
Total Flow Area				
*Bottom of HL to Top of Active Fuel				

A.7.2.7 Assessment of Pool Entrainment Limiting Conditions

This section examines the limiting conditions for the APEX entrainment tests. A core power of 1 MW in APEX represents a 2.8% decay power in the AP1000. The greatest vapor generation rates would be achieved at saturation conditions at 1 atmosphere. These conditions would produce an upper plenum vapor volumetric flux, j_g , of 11.2 m/s and 5.7 m/s in AP1000 and APEX, respectively. Applying these conditions to the entrainment transition and rate correlations presented in the previous section results in Figure A.24.

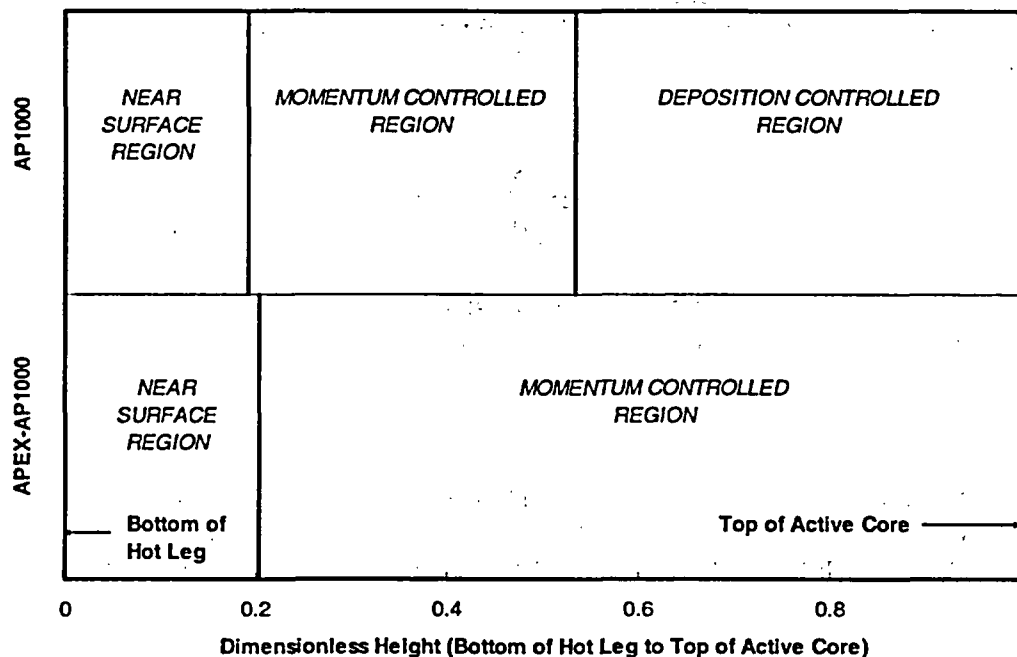


Figure A.24 Assessment of AP1000 and APEX Upper Plenum Pool Entrainment Regimes for a 2.8% Core Decay Power at Atmospheric Pressure

This figure shows how the different pool entrainment regions would exist in the upper plenums for the prescribed set of conditions. As the level drops below the HL, both the AP1000 and APEX upper plenums would exhibit entrainment characteristic of the near surface region. The entrainment rates that would be observed in APEX in this region are well-scaled, as is the transition to the momentum-controlled region. ***It is very important to note that the entrainment rates in the near surface region are a factor of 150 times greater than the entrainment rates generated in the momentum-controlled region.***

The figure shows that well-scaled entrainment behavior in APEX is expected to a depth of about 18.9 cm (0.55 in terms of dimensionless height in Figure A.24) below the HL. Below this depth, APEX is in the momentum-controlled region, whereas AP1000 would be in the deposition-controlled region at the equivalent scaled depth. ***It is also important to note that the entrainment rates in the momentum-controlled region are a factor of 4-6 times greater than the entrainment rates generated in the deposition-controlled region.***

With regard to the test facility scaling, the entrainment rate is well-scaled for depths to approximately the middle of the upper plenum. Below this depth, the APEX entrainment rates will range from 4 to 16 times greater, on a scaled basis, than what would be expected in the AP1000. Thus, the APEX facility will conservatively simulate the entrainment behavior when the level is below the midpoint of the upper plenum.

In general, relative to the near-surface region and momentum-controlled region entrainment rates, the deposition-controlled region entrainment rates are quite small.

On the basis of the conditions prescribed earlier, some preliminary calculations can be made to narrow down the flow conditions in the problem. First, since it is imperative that churn flow exists in the pool, it is necessary to determine if the flow is between the limits of bubbly and annular flow. For bubbly flow, Ishii gives the limit as [Ref. 17]:

$$j_g^* = 0.325 \left[\frac{\rho_g}{\rho_f} \right]^{1/2} = 0.008 \quad (\text{A.262})$$

where the previous density values have been substituted into Ishii's formula to give the numerical result. For annular flow, the criterion is given by [Ref. 17]:

$$j_g^* = 3.1 \quad (\text{A.263})$$

For these conditions, the value of j_g^* was found to be 1.75 for AP1000, and 0.89 for APEX. Thus, the j_g^* values fall between these limits for both the model and the prototype. Thus, churn flow exists in the pool for both systems over the full range of operating conditions, making Ishii's equations applicable to the analysis.

The next issue to be resolved is whether the flooding criterion is exceeded. After all, if the flooding criterion is exceeded, all of the liquid will be quickly expelled from the pool as a rising film, making the entrainment of droplets irrelevant. As is well known, the flooding criterion depends upon the diameter of the channel. For diameters in the range $3 \leq D_H^* \leq 20$, Ishii restates the Wallis criterion in the following form [Ref. 14]:

$$\frac{j_g^*}{\sqrt{D_H^*}} = 0.5 \quad (\text{A.264})$$

Furthermore, for diameters within the range $D_H^* \geq 30$, Ishii gives the Kutateladze criterion as [Ref. 17]:

$$j_g^* = 4 \quad (\text{A.265})$$

The dimensionless hydraulic diameters, D_H^* , for AP1000 and APEX were for these conditions were found to be 135 and 29, respectively. Using equation (A.248) for APEX and AP1000 or equation (A.247) for APEX, the criterion indicates that flooding in the upper plenum will not occur for the 2.8% power conditions described.

The next question to be addressed is whether the deposition on the wall is sufficiently large that one must consider re-entrainment from a falling film back into the vapor. In addressing this question, observe that only a fraction of the droplets are taken out of the flow by deposition. Furthermore, only a fraction of this fraction is re-entrained from the film back into the flowing vapor. Consequently, since only a fraction of the liquid removed by deposition is re-entrained back into the flow, it would seem that conservative results could be obtained by ignoring deposition in the first place. The only objection to this conservatism would be if deposition removes large droplets from the flow which are replaced by smaller droplets as a result of re-entrainment. Since this effect could shift the droplet distribution to subcritical diameters that are more easily carried by the vapor, the entrainment might be increased at large heights. However, a second and quite convincing argument is as follows. Since the data used by Ishii were based on flow in tubes, the phenomena of deposition and re-entrainment was necessarily present in the experiments themselves and, therefore, already included in the correlations. Given this fact, the equations may be used straightforwardly without having to account for this added effect.

A.7.3 Evaluation of Scale Distortion

Properly simulating the upper plenum pool entrainment process requires that the following ratios be on the order of unity:

$$t_R^* = \left(\frac{\dot{m}_{ENT,O} t}{a_{UP} \rho_L H} \right)_R \quad (A.266)$$

$$\Pi_{INJ,R} = \left(\frac{\dot{m}_{INJ,O}}{\dot{m}_{ENT,O}} \right)_R \quad (A.267)$$

$$\Pi_{GT,R} = \left(\frac{\dot{m}_{GT,O}}{\dot{m}_{ENT,O}} \right)_R \quad (A.268)$$

$$\Pi_{UPD,R} = \left(\frac{\dot{m}_{UPD,O}}{\dot{m}_{ENT,O}} \right)_R \quad (A.269)$$

The numerical values for each of the non-dimensional ratios are presented in Table A.17 for the near-surface entrainment and momentum-controlled entrainment regions. The data obtained from the assessment of limiting conditions presented in the previous section were used in the evaluation. The desired timescale ratio, t_R , of 0.5 was used to assess equation (A.266). All of the injection flow rates have been scaled to 1:96. Furthermore, equation (A.269) can be interpreted as the ratio of effective de-entrainment efficiencies. That is:

$$\Pi_{GT,R} = \eta_{eff,R} \quad (A.270)$$

The facility has been scaled to match the onset of upper plenum draining behavior when CCFL conditions are present at the upper core plate flow holes.

The ratio of the gravity-driven draining rates for the APEX and AP1000 upper plenums is given by:

$$(\dot{m}_{UPD,O})_R = [a_{UCP} (H_{UP} - h)^{1/2}]_R \quad (A.271)$$

Table A.19 indicates that the APEX-AP1000 upper plenum geometry and long-term cooling operating conditions match the pool entrainment scaling criterion very well with the exception of $P_{UPD,R}$.

Table A.19 Ratio of Π Groups for Near Surface and Momentum Controlled Upper Plenum Entrainment

Non-Dimensional Ratio	Near Surface	Momentum Controlled	a,b,c
$(t^*)_R$			
$\Pi_{inj,R}$			
$\Pi_{GT,R}$			
$\Pi_{UPD,R}$			
$(j_g^*)_R$			

A.7.3.1 Impact of Reduced Flow Area in the Upper Core Plate

The greatest source of distortion will be the upper plenum draining rate with a Π ratio of 0.5. This distortion arises because matching the flooding behavior at the upper core plate required reducing the upper core plate flow area such that the Kutateladze number was identically preserved. This delayed draining effect is conservative relative to core cooling. In addition, the vapor jetting behavior at the upper core plate produces a local vapor volumetric flux j_g equivalent to what would be observed in the AP1000. Preserving a 1:1 vapor velocity in a 1:4 length upper plenum will produce conservative results. It is expected that the proposed set of upper internals will overestimate the amount of entrained liquid on a scaled basis. This is a conservative feature of the experiment.

A.8 Summary and Conclusions

This document presents the scaling analysis performed to guide the OSU APEX-AP1000 test facility modifications. The purpose of the test program is to provide high-quality benchmark data for the reactor safety analysis codes. Previous testing in APEX has demonstrated that all of the thermal-hydraulic phenomena observed in the large-scale AP600 facilities such as ROSA-AP600 or SPES were also observed in APEX, thereby providing a broad data base for code assessment. However, the most faithful representation of the AP600 phenomena was for the very long-term cooling phase, which occurs at low system pressure. The APEX-AP1000 test program will be modified to include full-pressure ADS4 blowdown tests to investigate the transition period that leads to the onset of IRWST injection. This scaling analysis provides the basis for the following plant modifications:

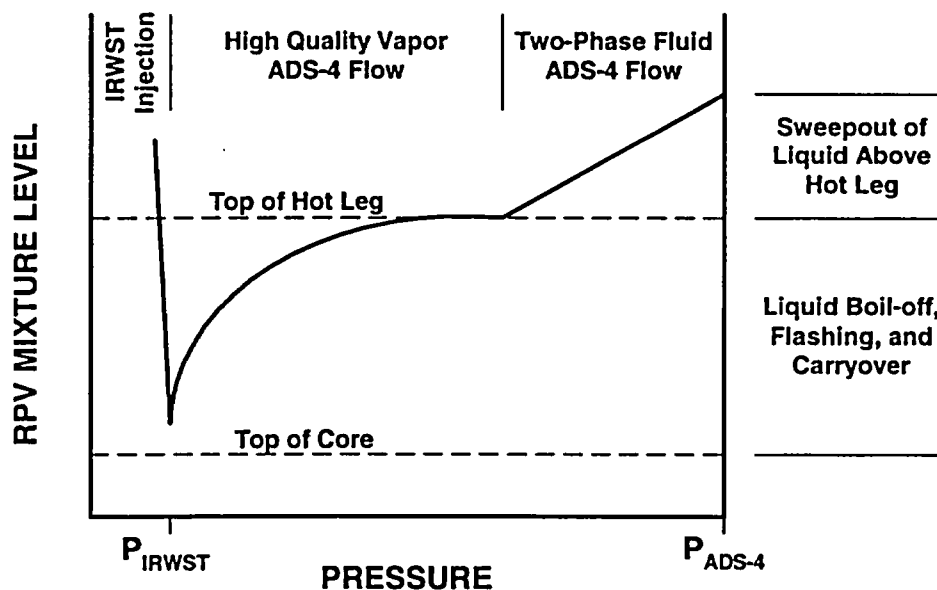
Component	Modification to APEX
Reactor Power	Increase core power by 67%. (Maximum of 1MW).
PZR	Increase PZR volume. Reduce PZR Surge Line Diameter.
CMTs	Increase CMT volumes by 25%. Reduce line resistance to 64% of original value.
IRWST	Increase IRWST liquid level.
ADS4	Increase ADS4 flow area by 76%. Reduce line resistance to 28% of original value.
PRHR HX	Increase PRHR flow capacity by 74% by reducing line resistance. No change in surface area/tube number required for testing.
Containment Sump Flood-Up Elevation	Change flood-up elevation in primary sump tank.

The following paragraphs briefly summarize the results of the study.

- (1) The original AP600 Scaling Analysis, WCAP-14270, which was performed in support of the design of the existing Advanced Plant Experiment (APEX) facility at OSU was found to be applicable to the APEX-AP1000 design for two reasons. First, the thermal-hydraulic phenomena to be studied fell within the scope of the original AP600 test program, with the exception of upper plenum behavior. Second, the AP1000 is geometrically similar to the AP600. As a result, all of the tank volumes, flow areas, and line resistance scaling ratios found in WCAP-14270 were used in the present study.
- (2) An NRC PZR surge line study by Di Marzo and Bessette was used to guide the modifications to the APEX-AP1000 PZR surge line. The reduced line diameter is expected to produce a better simulation of the PZR draining behavior.
- (3) The RCS depressurization scaling analysis represents a more comprehensive approach than that implemented in the original AP600 study. Nonetheless, the similarity criteria derived in this report resulted in scaling ratios that were identical to those in the original

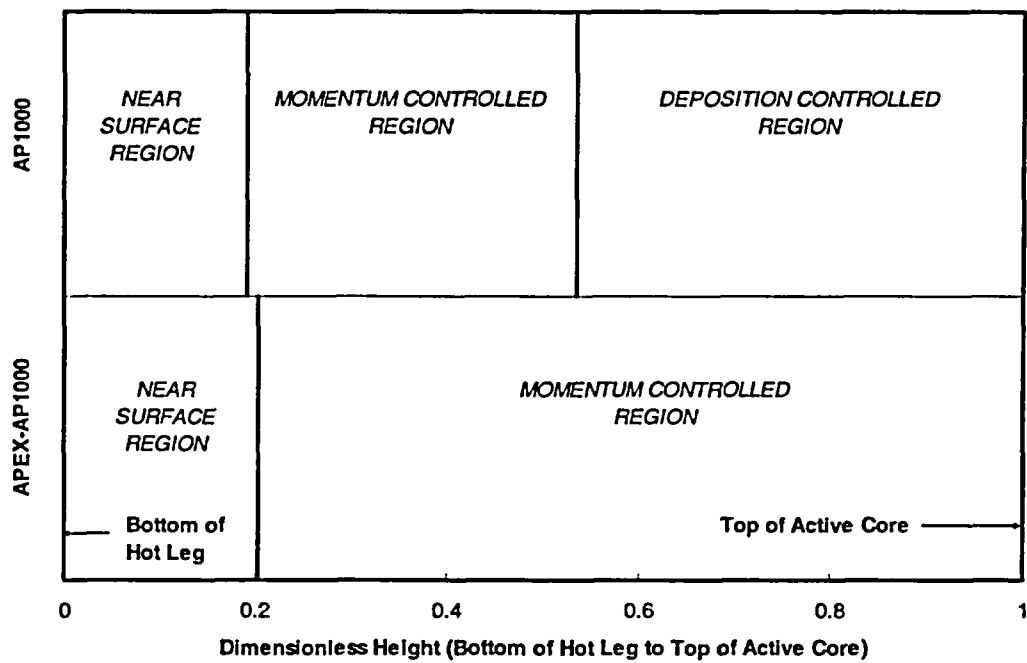
study. It was found that the characteristic time ratios for AP1000 would be well-matched in APEX-AP1000. The greatest distortion (a factor of 2) was the result of pressure-scaled fluid properties.

- (4) A scaling analysis has been performed to design the APEX-AP1000 to simulate the important phenomena that occur during the transition from ADS4 blowdown to the onset of IRWST injection. The key phenomena have been identified and described, and the scaling analysis indicates that full-pressure ADS4 blowdown tests can be performed using the modified APEX-AP1000 test facility. Chapter 15 of the Westinghouse AP1000 Safety Analysis Report indicates that ADS4 actuation typically occurs near 100 psia. The maximum decay power, ~2.0%, at the time of ADS4 valve opening was calculated for the DEDVI break. These initial conditions will be examined as part of the testing. The AP1000 core axial void fraction profile and core averaged void fraction were shown to be preserved in APEX-AP1000.



- (5) A detailed pool entrainment scaling analysis has been performed to design the upper plenum components in APEX-AP1000. The analysis indicates that well-scaled entrainment behavior in APEX is expected to a depth of about 18.9 (0.55 in terms of dimensionless height) cm below the HL. Below this depth, APEX is in the momentum-controlled region, whereas AP1000 would be in the deposition-controlled region at the equivalent scaled depth. It was found that the entrainment rates in the near-surface region are a factor of 150 times greater than those generated in the momentum-controlled region, which are a factor of 4-6 times greater than those generated in the deposition-controlled region. Thus, the APEX facility will conservatively simulate the entrainment behavior when the level is below the midpoint of the upper plenum. In addition, the vapor volumetric flow rate ratio, $(j_{g,R})$, at the upper core plate holes has been set to unity to preserve the Kutateladze number. This adds an additional conservatism to the pool entrainment process because the local vapor jets at

the upper core plate holes will extend into the upper plenum, thereby increasing liquid entrainment.



APPENDIX B.

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APPENDIX B. APEX COMPONENT DIMENSIONS, CONTROL LOGIC, AND SETPOINTS

B.1 Component Dimensions

Tables B.1 through B.11 contain detailed component dimensions (and, in some cases, thermocouple locations) for the reactor pressure vessel (RPV), pressurizer (PZR), steam generators (SGs), in-containment refueling water storage tank (IRWST), core makeup tanks (CMTs), accumulators (ACCs), primary and secondary sumps, and safety system line dimensions and resistances. Figure B.1 is a map of the thermocouples in the RPV downcomer.

Table B.1 Reactor Pressure Vessel Components

Component	No.	Dimensions	Reference	a,b,c

Table B.1 Reactor Pressure Vessel Components

Component	Dimension	Reference

a,b,c



a,b,c

Figure B. 1 Thermocouple Map of Downcomer

Table B.2 Thermocouple Legend for Figure B.1

a,b,c	Thermocouple			Thermocouple		
	Map Number	Tag Number	Radial Position	Map Number	Tag Number	Radial Position

Table B.3 Pressurizer Components

a,b,c	Component		Dimensions	Reference
	No.			

Table B.4 Steam Generators (Each) Components

Component	No.	Dimensions	Reference	a,b,c

Table B.5 IRWST Components

Component	No.	Dimensions	Reference

Table B.6 Core Makeup Tank Components

Component	No.	Dimensions	Reference

Table B.7 Accumulator Components

Component	No.	Dimensions	Reference

a,b,c

Table B.8 Primary Sump Components

Component	No.	Dimensions	Reference

a,b,c

Table B.9 Secondary Sump Components

Component	No.	Dimensions	Reference	a,b,c

Table B.10 Summary of Safety System Line Dimensions

Name	Material	Data and Dimensions	Location and Connections (Valves and Equipment)

B.2 Control Logic and Controller Setpoints

Tables B.12 through B.23 contain detailed control logic and setpoints for station blackouts; SBLOCAs; LBLOCAs; inadvertent ADS initiation; full-pressure ADS initiation; automatic actuation of PRHR and CMT on "S" signal; automatic actuation of ADS1-4 on CMT level or timers; automatic control of SG pressure, liquid water level, feedwater flow, and main steam flow; automatic control of PZR pressure and level; programmed reactor decay power and control of core exit temperatures; and programmed CVS and RNS pump flow rates.

Table B.12 Station Blackout Routine Logic

Step	Condition	a,b,c

Table B.13 Small-Break LOCA Routine Logic

Step	Condition	a,b,c

Table B.14 Large-Break LOCA Routine Logic (Much the same as Small-Break LOCA routine logic except the test initialization)

Step	Condition	a,b,c

Table B.15 Inadvertent ADS Initiation Routine Logic

Step	Condition	a,b,c

Table B.16 Full-Pressure ADS Routine Logic

Step	Condition	a,b,c

Natural Circulation Routine

This routine permits operation of the reactor controller in manual or automatic mode, with or without RCPs and with no "S" signal or automatic trip functions. This routine allows flexibility to custom-tailor a test without requiring extensive re-programming.

The setpoint in Table B.17 show each bi-stable device and its associated set/reset points. Most of these values can be readily modified by the operator and, in some cases, vary among the different logic routines. The table contains the tag name of the device, the specific point (e.g., HH for High High), the set/reset points applicable to the logic routine, and the logic diagram sheet number(s) showing the device.

Table B.17 APEX Controller Set Point Values for Natural Circulation Routine

Routine	Trip	Reset	Action(s)
a,b,c			

Table B.17 APEX Controller Set Point Values for Natural Circulation Routine

Routine	Trip	Reset	Action(s)
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a,b,c

Table B.17 APEX Controller Set Point Values for Natural Circulation Routine

Routine	Trip	Reset	Action(s)

a,b,c

Table B.17 APEX Controller Set Point Values for Natural Circulation Routine

Routine	Trip	Reset	Action(s)

a,b,c

Table B.18 Automatic Actuation of PRHR and CMT on "S" signal

Conditions (And)	Actions	a,b,c

Table B.19 Automatic Actuation of ADS 1-4 on CMT Level or Timers

Conditions	Actions	a,b,c

**Table B.20 Automatic Control of SG Pressure, Liquid Water Level,
Feedwater Flow, and Main Steam Flow**

Input Signal	Output signal to	a,b,c

Table B.21 Automatic Control of PZR Pressure and Level

Input Signal	Output signal to	a,b,c

Table B.22 Programmed Reactor Decay Power and Control of Core Exit Temps

Input Signal	Output signal to	a,b,c

Table B.23 Programmed CVS and RNS Pump Flow Rates

Input Signal	Output signal to	a,b,c

APPENDIX C.

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APPENDIX C. TEST TRANSIENT PLOTS AND SEQUENCE OF EVENTS

This appendix contains transient plots, facility configuration, and sequence of events for tests NRC-AP1000-01, 02, 03, 04, 05, 06, 10, and 11. Facility information can be found in Chapter 3 and Appendix B of this report. The main purpose of the APEX-AP1000 confirmatory testing was to examine the performance of passive safety systems.

C.1 NRC-AP1000-01

The purpose of this test was to determine the impact on passive safety system behavior that resulted from a DEDVI break with a major failure of ADS system. It was similar in intent to Test NRC-26, which was run for AP600 design certification, in the sense that in NRC-26, a major failure of the ADS system was simulated. However, Test NRC-26 included delayed core heatup to simulate containment failure, and was configured for a smaller 1-inch CL break, and the delayed core heatup in NRC-26 resulted in a heater rod temperature excursion. Test NRC-AP1000-01 was run with a larger DEDVI break without delayed core heatup. The core remained covered during the long-term cooling period of Test NRC-AP1000-01. Both Test NRC-26 and Test NRC-AP1000-01 experienced short periods of CMT refill as a result of condensation-induced pressure drops. A similar test in the ROSA-AP600 facility also investigated a similar scenario. In Test ROSA AP-CL-05, there was no refilling during CMT draining. The difference in ROSA and APEX CMT behavior was attributed to the use of two separate CMT-PBLs (APEX) instead of one (ROSA) and the reduced height scale of APEX (permitting liquid to be drawn through the PBL into the CMTs, which further enhanced condensation).

Test NRC-AP1000-01 simulated a DEDVI break with complete failure of ADS1, 2, and 3. Table C.1 summarizes the facility configuration. This test was defined as a beyond-DBA scenario because of the multiple valve failures. All four ADS4 valves were available and, therefore, this test investigated the ability of the ADS4 system to accomplish system depressurization. The PRHR HX was inactive during this test. The APEX facility models both trains of the AP1000 ADS1, 2, and 3 lines located at the top of the PZR after a flow nozzle that models the scaled choked flow area of the AP1000.

Table C.1 Facility Configuration for Test NRC-AP1000-01

Component	Configuration
ADS1	Failed Shut
ADS2	Failed Shut
ADS3	Failed Shut
ADS4-1 (non-PZR side)	100% ADS4-1 flow
ADS4-2 (PZR-side)	100% ADS4-2 flow
Break	DEDVI Line 1

Table C.2 summarizes the sequence of events for Test NRC-AP1000-01. After the break was opened at zero seconds, the PZR, CMTs, and ACC1 immediately began to inject. However, all Side 1 injection flows (ACC1 and CMT1 in Figure C.3), went out the DEDVI Line 1 break. The core collapsed liquid level reached a relative minimum at []^{a,b,c} as shown in Figures C.1 and C.2. The ACC2 injection began at []^{a,b,c} as shown in Figure C.4. The ADS4 valves opened just before the minimum RPV liquid level at around []^{a,b,c}.

The RPV two-phase level dropped near the bottom of the HL at around []^{a,b,c}; however, as a result of CMT2 injection, the water level in the core began to rise at around []^{a,b,c}. At []^{a,b,c} CMT2 refilled as a result of condensation-induced pressure drop. At []^{a,b,c}, IRWST injection through DVI line 2 began, and the RPV liquid level began to increase.

The RPV two-phase mixture level remained high throughout the entire test, dropping briefly below the bottom of the HL between []^{a,b,c} as shown in Figure C.5. This high liquid level can also be seen by examining the HL liquid level plots in Figure C.6.

At approximately []^{a,b,c}, liquid began to preferentially entrain through the non-PZR side ADS4-1 line as shown in Figure C.7. From about []^{a,b,c} on, the flow quality in the non-PZR ADS4-1 line remained constant at approximately 0.05, while the PZR side ADS4-2 line remained constant at approximately 0.4. The core remained covered during the entire test as shown in Figure C.8.

Table C.2 Sequence of Events for Test NRC-AP1000-01

Time (s)	Event	a,b,c



Figure C.1 Vessel Wide Range Collapsed Water Level



Figure C.2 Core Upper Half and Lower Half Collapsed Water Levels

a,b,c

Figure C.3 Accumulator, CMT, and IRWST Flows to DVI1

a,b,c

Figure C.4 Accumulator, CMT, and IRWST Flows to DVI2



Figure C.5 Upper Plenum Two-Phase Level



Figure C.6 Hot Leg Collapsed Water Levels



Figure C.7 ADS4 Flow Qualities



Figure C.8 Core Heater Rod Temperatures

C.2 NRC-AP1000-02

The objectives of Test NRC-AP1000-02 were to determine system behavior during a loss of shutdown cooling, if the RCS would pressurize sufficiently to prevent IRWST injection, and if CCFL would prevent the PZR from draining. In this test, a loss of RNS cooling was simulated after the reactor had been shutdown for 24 hours. The RCS was at []^{a,b,c} with an initial PZR level of []^{a,b,c}. The ADS3 valve was opened (which simulated two trains of ADS1, 2, and 3 in AP1000) venting the RCS to the IRWST. The SG secondary sides were assumed to have been drained for maintenance. The ACCs and CMTs were assumed to be unavailable. One ADS4 valve was failed on demand. The facility configuration for this test is given in Table C.3.

Table C.3 Facility Configuration for Test NRC-AP1000-02

Component	Configuration
ADS1	Failed Shut
ADS2	Failed Shut
ADS3	Open to vent primary system
ADS4-1 (non-PZR side)	1 out of 2 Failed Open
ADS4-2 (PZR-side)	100% ADS4-2 flow
ACCs	Unavailable
CMTs	Unavailable
RNS Cooling	Unavailable
Break	None

Table C.4 summarizes the sequence of events for this test. The test was started by increasing reactor power to 320 kW. When both HL liquid levels decreased to approximately ½-inch, one IRWST valve and one ADS4 valve were opened after a []^{a,b,c} time delay. ADS4B was opened at around []^{a,b,c}, which caused a rapid depressurization of the primary system and the IRWST began injecting makeup water by []^{a,b,c} as shown in Figure C.9. The sump recirculation valves were opened at []^{a,b,c}, as shown by a sharp increase in IRWST injection flow rate, and the facility transitioned into long-term cooling mode.

As the heater rod power was increased in the beginning of the test, the RPV liquid level dropped significantly []^{a,b,c} as water was boiled off and released out of the open ADS3 valve as shown in Figure C.10. After ADS4 actuation, the RPV level increased as IRWST injection was provided to the core. This same trend is shown in Figure C.11, which plots the RPV mixture level. During the entire transient, the core never uncovered, and the mixture level was always above the level of the upper core plate. Figure C.14 plots the core collapsed liquid levels from the lower core plate to the mid-core spacer grid (LDP-109) and from the mid-core spacer grid to the upper-core spacer grid (LDP-110).

Figure C.12 plots the HL levels on the PZR and non-PZR sides of the plant. At around []^{a,b,c}, when the HL levels dropped to ½-inch, ADS4B was opened. The HL liquid levels

briefly continued to drop, but quickly turned around as makeup water was provided from the IRWST, and the decrease in pressure caused the RPV mixture level to swell. At no time during the transient were the HLs emptied.

One of the objectives of this test was to determine if the PZR would be able to drain as a result of CCFL. Figure C.13 plots PZR level versus time and shows that the PZR drained slowly from about []^{a,b,c} as primary water was boiled off and the steam exited the open ADS3 valve. When the ADS4B valve was actuated, the PZR quickly drained and remained empty until about []^{a,b,c} when the plant refilled as a result of IRWST injection. Figure C.15 plots core heater rod temperatures, and no high rod temperature excursion was experienced during the entire test.

Table C.4 Sequence of Events for Test NRC-AP1000-02

Time (s)	Event	a,b,c



Figure C.9 IRWST (Lines 1 and 2) Injection Flow Rates



Figure C.10 RPV Collapsed Liquid Level

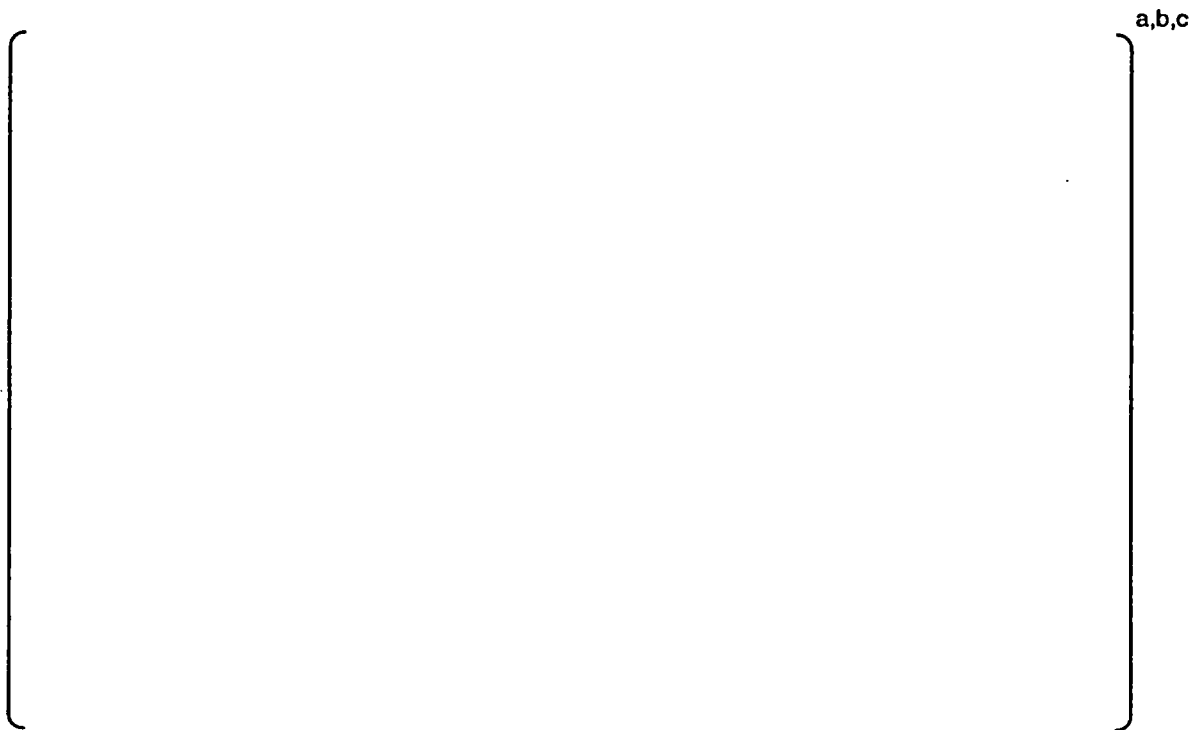


Figure C.11 RPV Mixture Level



Figure C.12 Hot Leg Collapsed Liquid Levels



Figure C.13 PZR Collapsed Liquid Level



Figure C.14 Core Collapsed Liquid Levels

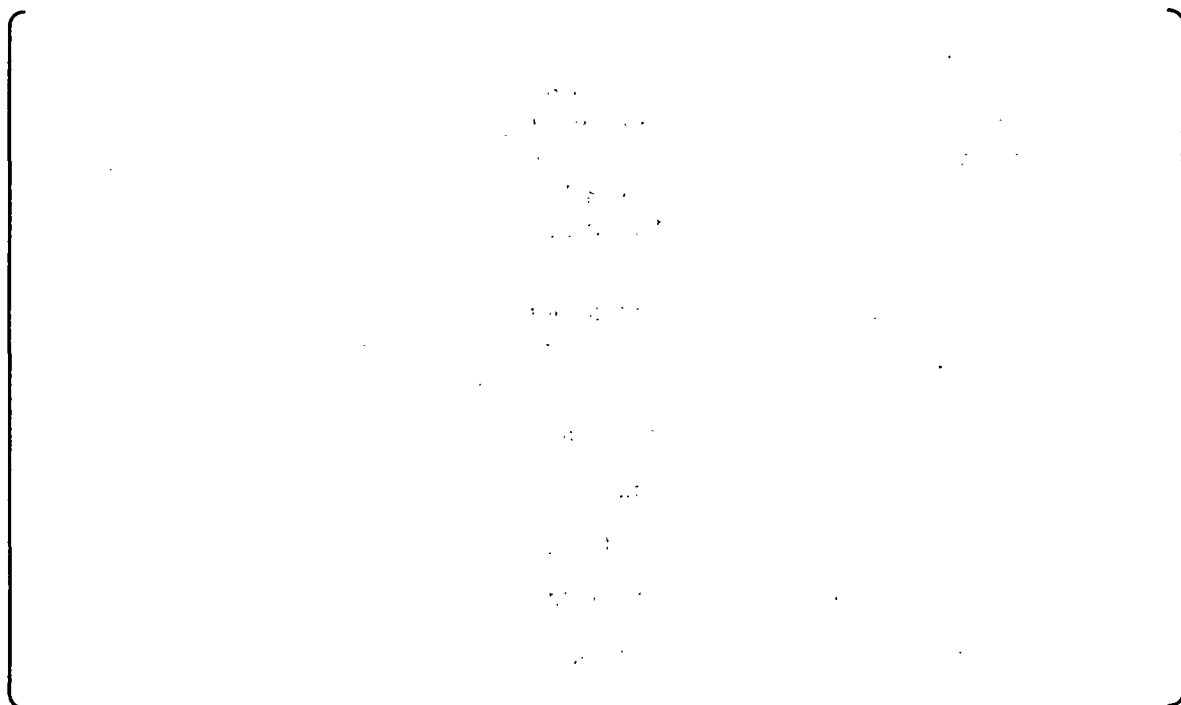
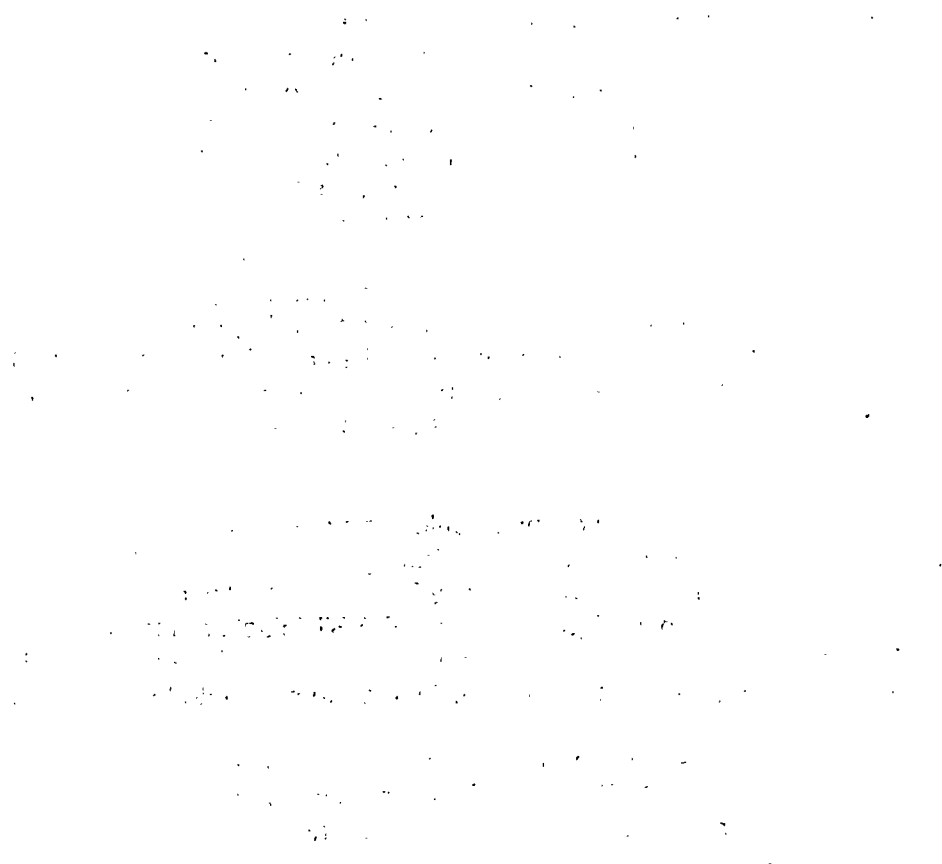


Figure C.15 RPV Heater Rod Temperatures



C.3 NRC-AP1000-03

This test simulated a DEDVI DVI line 1 break with two of the four ADS4 valves failed closed (ADS4-2 closed and ADS4-1 opened), with the purpose of investigating a major failure of the ADS system. Both failed ADS4 valves were on the PZR side of the plant. Table C.5 summarizes the facility configuration. This test is similar in intent to NRC-10, which was conducted for AP600 design certification. In NRC-10, failure of three of the four ADS4 valves produced core uncover and heatup for a 1-inch CL break.

Table C.5 Facility Configuration for Test NRC-AP1000-03

Component	Configuration
ADS1	Normal actuation
ADS2	Normal actuation
ADS3	Normal actuation
ADS4-1 (non-PZR side)	100% ADS4-2 flow
ADS4-2 (PZR side)	Failed Shut
Break	DEDVI Line 1

Table C.6 summarizes the sequence of events for NRC-AP1000-03. Similar to NRC-AP1000-01, this DEDVI test depressurized quickly, causing a low inventory in the vessel as shown in Figure C.16, indicating that the break (rather than early actuation of the ADS1, 2, and 3 valves) was responsible for the initial rapid depressurization and mass loss. CMT1 began draining out of the DVI line 1 break immediately after the break opened. ADS1, 2, and 3 were opened in sequence from []^{a,b,c}, further depressurizing the plant. ACC2 was injecting by []^{a,b,c}, while ACC1 and CMT1 emptied by []^{a,b,c}. All Side 1 injection flow (ACC1, CMT1, and IRWST Line 1) was lost out of the DEDVI break. At []^{a,b,c}, the ADS4-1 valve was opened. Coupled with CMT2 and ACC2 injection, the vessel inventory increased until these two tanks were completely emptied by []^{a,b,c}. As shown in Figure C.19, there was a period []^{a,b,c} when there was no injection flow to the core. This delay in IRWST injection was also experienced in NRC-AP600-10 and is attributable to a known scaling distortion related to the reduced IRWST head, which is an artifact of the one-quarter height scaling in APEX and is conservative in nature.

The RPV two-phase water level dropped below the bottom of the HL from []^{a,b,c} as shown in Figure C.20. IRWST injection increased from []^{a,b,c}, and the core water level rose to a relative maximum at approximately []^{a,b,c}. Then the vessel inventory decreased slowly over time, as shown in Figure C.16, as IRWST injection decreased until emptying at []^{a,b,c}. Sump recirculation began at about []^{a,b,c}, thus ending the IRWST injection phase, as shown in Figure C.21, and transitioning the plant into long-term cooling mode.

The HL water levels are shown in Figure C.22. HL2 emptied from []^{a,b,c} and refilled from []^{a,b,c} while CMT2 and ACC2 injected water into the RPV. When CMT2 and ACC2 emptied at approximately []^{a,b,c}, HL2 was empty from []^{a,b,c}. IRWST injection raised the HL levels from []^{a,b,c}, but as injection flow decreased, the HL2

liquid level began to decrease until it emptied for the last time at approximately []^{a,b,c}. This is the time that IRWST injection ceased and sump recirculation began. Enough water was recirculated through the core that the quality out the ADS4-1 line was not unity (~0.8), as shown in Figure C.23. During this time, the RPV two-phase level was well below the bottom of the HL, as shown in Figure C.20, and a fair amount of water remained in HL1, as shown in Figure C.22. This behavior illustrates the importance of upper plenum and HL entrainment on passive safety system performance.

Figure C.24 depicts the PZR wide range level. After the initial blowdown, substantial PZR injection began at approximately []^{a,b,c} and it ceased to inject water into the primary system at []^{a,b,c}.

Several small heater rod temperature spikes are shown in Figure C.25. The first spike at around []^{a,b,c} corresponded to the lowest vessel level experienced during the test, which is shown in Figure C.16. This spike occurred when all CMTs and ACCs were empty before IRWST injection flow began. The next significant temperature spike occurs at around []^{a,b,c} when the core water level was low during sump recirculation. However, even though the vessel level was low at certain times during the test, the core still remained covered. Consequently, these temperature spikes were most likely caused by relatively large voids in the core coming into contact with specific thermocouples and do not represent an "average" core temperature, but local "warm spots".

Table C.6 Sequence of Events for Test NRC-AP1000-03

Time (s)	Event	a,b,c

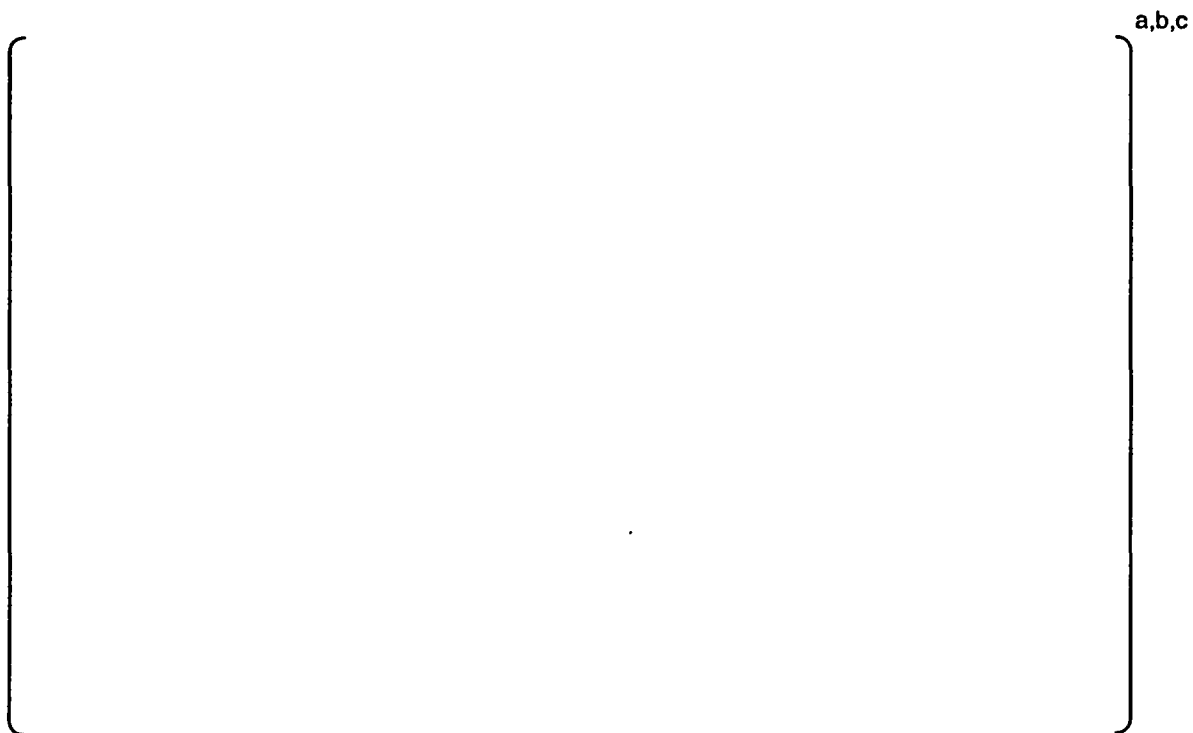


Figure C.16 Vessel Wide Range Collapsed Water Level



Figure C.17 Core Upper Half and Lower Half Collapsed Water Levels



Figure C.18 Accumulator, CMT, and IRWST Flows to DVI1



Figure C.19 Accumulator, CMT, and IRWST Flows to DVI2



Figure C.20 RPV Two-Phase Level



Figure C.21 Sump Recirculation Flows



Figure C.22 Hot Leg Collapsed Water Levels



Figure C.23 ADS4-1 (Non-Pressurizer Side) Flow Quality

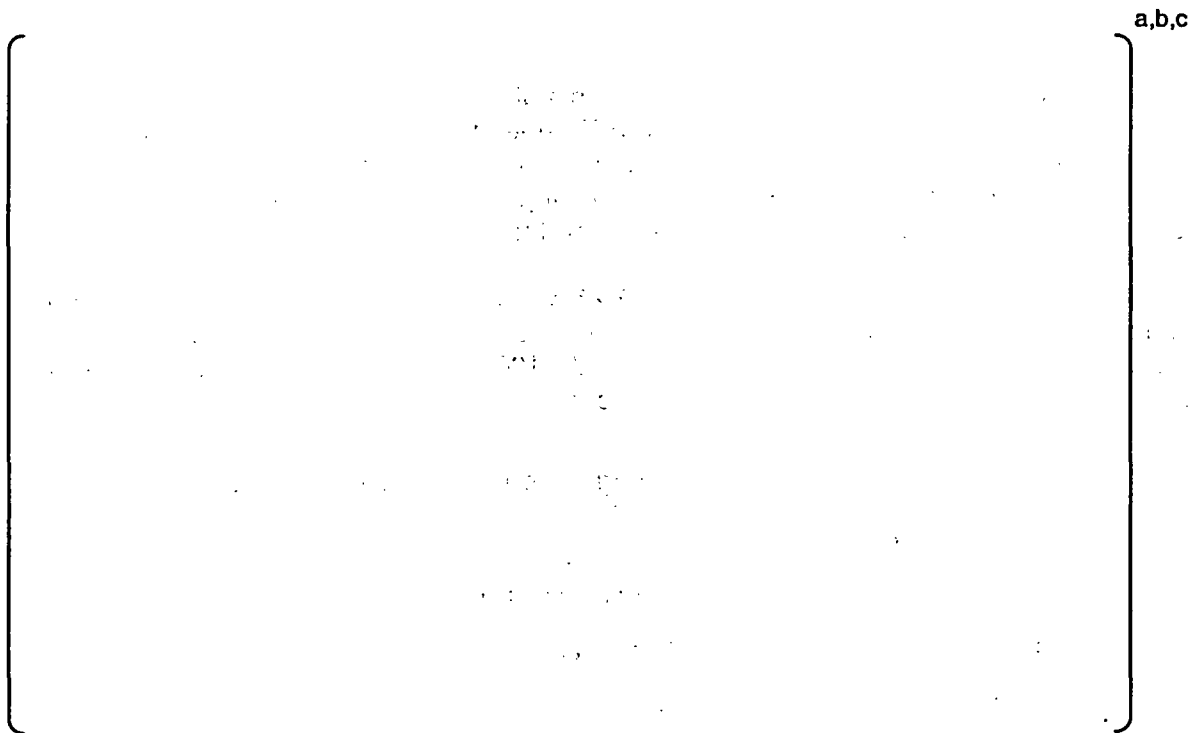


Figure C.24 Pressurizer Wide Range Collapsed Water Level

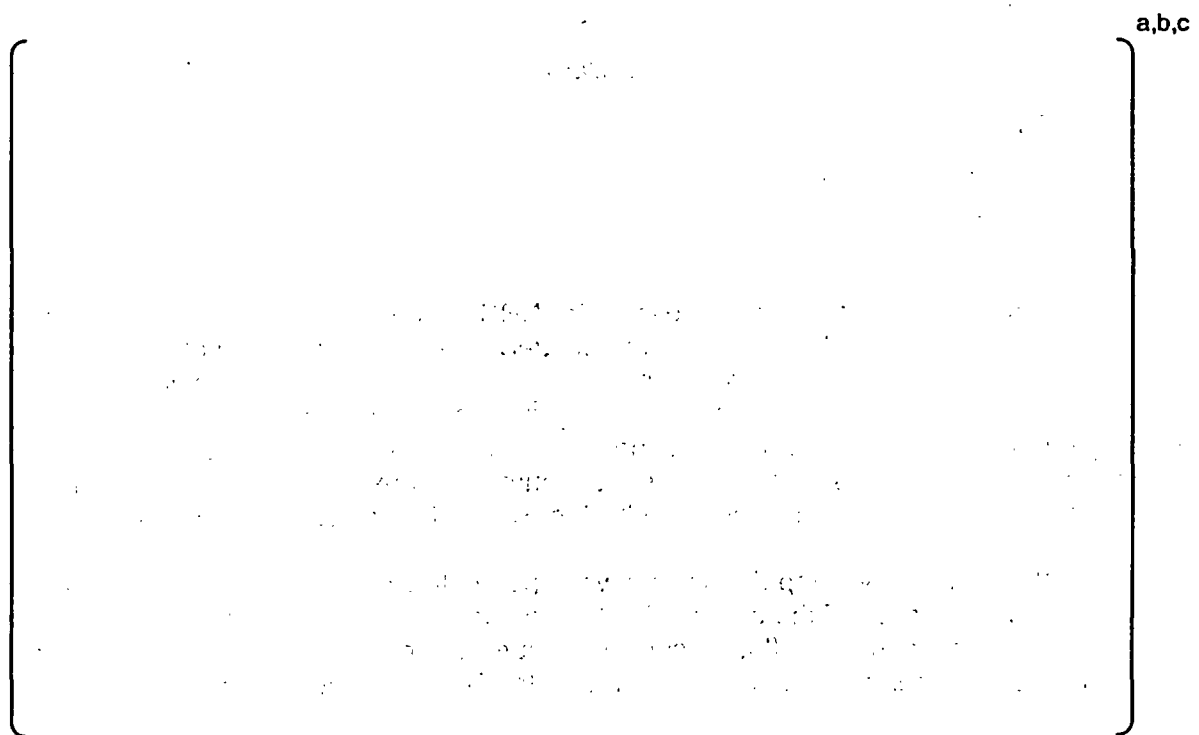


Figure C.25 Core Heater Rod Temperatures

C.4 NRC-AP1000-04

Test NRC-AP1000-04 was a beyond-DBA test simulating a 1-inch CL break with one ADS4-1 valve failed shut (50% line flow) on the non-PZR side of the plant. In addition, CMT1, ACC1, sump recirculation line 1, and IRWST injection line 1 were unavailable. Table C.7 summarizes the facility configuration for this test. Upon reaching 30 minutes of steady-state long-term cooling, the primary sump drain valve was opened to simulate a degraded containment sump.

This test was similar in intent to NRC-AP600-27, where a similar break size with a degraded sump was simulated, in part, to determine the impact on long-term cooling as a result of depleting the primary sump inventory. In NRC-AP1000-04 and both AP600 tests, the two-phase level in the core remained above the heater rods.

Table C.7 Facility Configuration for Test NRC-AP1000-04

Component	Configuration
ADS1	Normal actuation
ADS2	Normal actuation
ADS3	Normal actuation
ADS4-1 (non-PZR side)	50% ADS4-1 flow
ADS4-2 (PZR side)	100% ADS4-2 flow
CMT1	Unavailable
ACC1	Unavailable
Sump Recirculation Line 1	Unavailable
IRWST Injection Line 1	Unavailable
Break	1-inch bottom of CL 4

Table C.8 summarizes the sequence of events for NRC-AP1000-04. The break was opened at zero seconds, causing the CMTs to inject immediately and, during the initial blowdown, the RPV vessel inventory dropped to a relative minimum at around []^{a,b,c} as shown in Figures C.26 and C.27. The ACC2 injection began at []^{a,b,c} as shown in Figure C.28. The RPV inventory remained relatively low until around []^{a,b,c} IRWST injection began, and the inventory in the RPV increased to a relative maximum at approximately []^{a,b,c}. This was around the same time IRWST injection reached maximum flow as shown in Figure C.28.

At []^{a,b,c} the primary sump drain valve was opened to simulate a degraded sump (ending the IRWST injection phase of the transient), which created an increase in IRWST flow shown in Figure C.28. Primary sump overflow occurred at approximately []^{a,b,c} and water was recirculated from the sump, to the IRWST, through the DVI2 line and into the RPV.

From []^{a,b,c} the two-phase RPV level never dropped below the bottom of the HL and remained high until test termination at []^{a,b,c} as shown in Figure C.29. The HL liquid levels also remained high after the initial plant blowdown as shown in Figure C.30.

High HL and two-phase RPV levels provided an increased amount of water for liquid entrainment out of the ADS4 valves. In Figure C.31, the quality out of ADS4-1 was very low (< 0.04) compared to ADS4-2 quality ([]^{a,b,c}), illustrating a preference to entrain liquid through the non-PZR side HL. This same preference was also observed in Test NRC-AP1000-01. This preferential entrainment to one side of the plant was unique, but did not raise any safety concerns and this phenomenon is currently being investigated in conjunction with thermal-hydraulic code development and assessment activities.

The PZR began to drain at []^{a,b,c} and emptied by []^{a,b,c} as shown in Figure C.32. Adequate injection was provided by CMT2, ACC2, and the PZR during the initial blowdown to keep the heater rods covered. A 1-inch CL break along with a degraded sump did not challenge the passive safety systems enough to uncover the heater rods. The core remained adequately cooled during the entire test, as shown in Figure C.34.

Table C.8 Sequence of Events for Test NRC-AP1000-04

Time (s)	Event	a,b,c



Figure C.26 Vessel Wide Range Collapsed Water Level

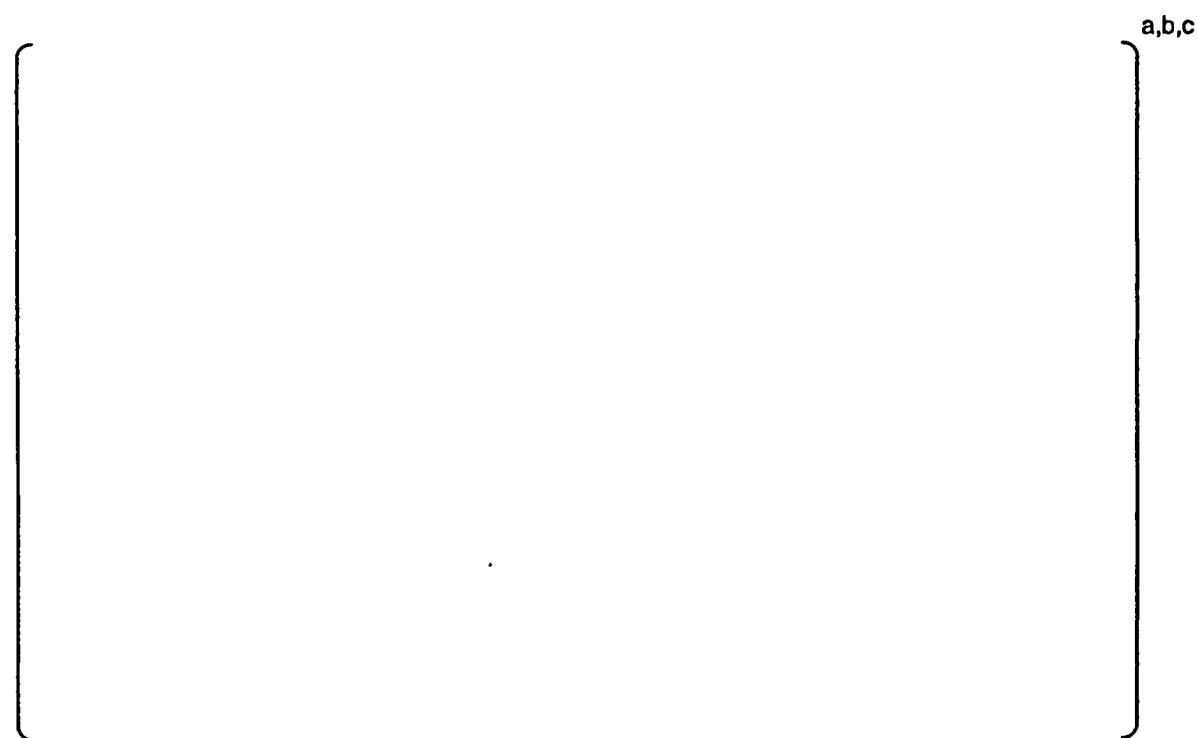


Figure C.27 Core Upper Half and lower Half Collapsed Water Levels



Figure C.28 Accumulator, CMT, and IRWST Flows to DVI2

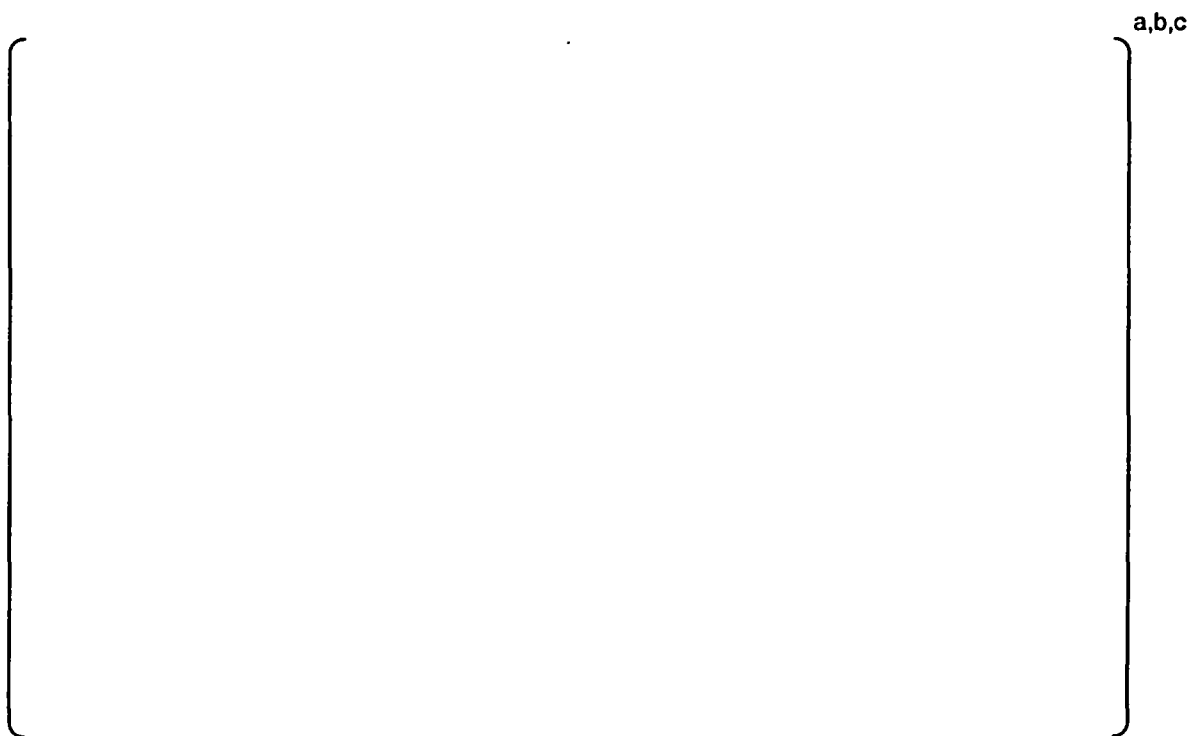


Figure C.29 Upper Plenum Two-Phase Level

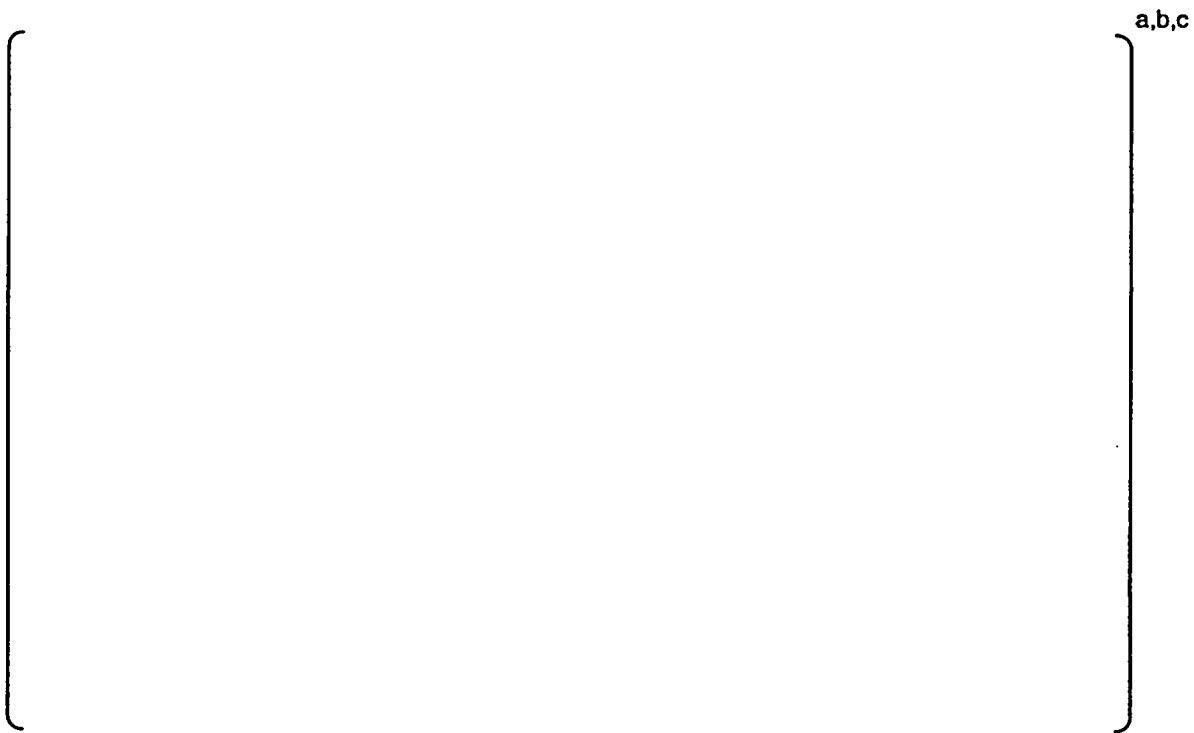


Figure C.30 Hot Leg Collapsed Water Levels



Figure C.31 ADS4 Flow Qualities



Figure C.32 Pressurizer Wide Range Collapsed Water Level



Figure C.33 Core Heater Rod Temperatures

C.5 NRC-AP1000-05

This simulated a double-ended guillotine break of a DEDVI with two of the four ADS4 valves failed closed (ADS4-1 closed and ADS4-2 opened). Both ADS4 valves on the non-PZR side were failed closed. Table C.9 summarizes the facility configuration. This test compliments Test NRC-AP1000-03, in which the only difference was in the location of the valve failure. In NRC-AP1000-03, both failed valves were on the PZR side.

Table C.9 Facility Configuration for Test NRC-AP1000-05

Component	Configuration
ADS1	Normal actuation
ADS2	Normal actuation
ADS3	Normal actuation
ADS4-1 (non-PZR side)	Failed shut
ADS4-2 (PZR side)	100% ADS4-2 flow
Break	DEDVI Line 1

Table C.10 summarizes the sequence of events for this test. When the break opened at zero seconds, CMT1, CMT2, and ACC2 immediately began to discharge out the break. By []^{a,b,c}, CMT1, ACC1, and ACC2 were completely empty. Figures C.36 and C.37 depict the flow from the ACCs, CMTs, and IRWST. The vessel inventory was low from approximately []^{a,b,c}.

The vessel inventory increased slightly, as shown in Figure C.38, as CMT2 injection was prolonged, but after CMT2 emptied at []^{a,b,c}, no injection water was provided to the core. The RPV water level in the core began to drop at approximately []^{a,b,c} into the test.

With no flow from the IRWST, HL1 emptied at []^{a,b,c} while water continued to be entrained out the ADS4-2 line, as shown in Figure C.40. A significant water level in HL2 was maintained until []^{a,b,c}. The flow quality in ADS4-2 throughout most of the test remained fairly low (~0.5), even when the RPV two-phase level dropped below the bottom of the HLs. The minimum level that the two-phase probe can measure is approximately 2 inches above the upper core plate. Thus, the LT-120 measurement could not decrease after it "bottomed" at []^{a,b,c}.

By []^{a,b,c} the PZR had still not drained due to CCFL, as shown in Figure C.41, and the heater rods began to uncover. At []^{a,b,c} a heater rod temperature excursion was observed, as shown in Figure 4.9, and the heater rod power was shut off at []^{a,b,c}. Immediately after the heater rods were turned off, IRWST injection flow began.

The results of this test illustrate the sensitivity of ADS4 valve failure on core coolability. In this test, IRWST injection never began through DVI Line 2 as water was lost out ADS4-2 as a result of upper head and HL liquid entrainment.

Table C.10 Sequence of Events for Test NRC-AP1000-05

Time (s)	Event	a,b,c



Figure C.34 Vessel Wide Range Collapsed Water Level

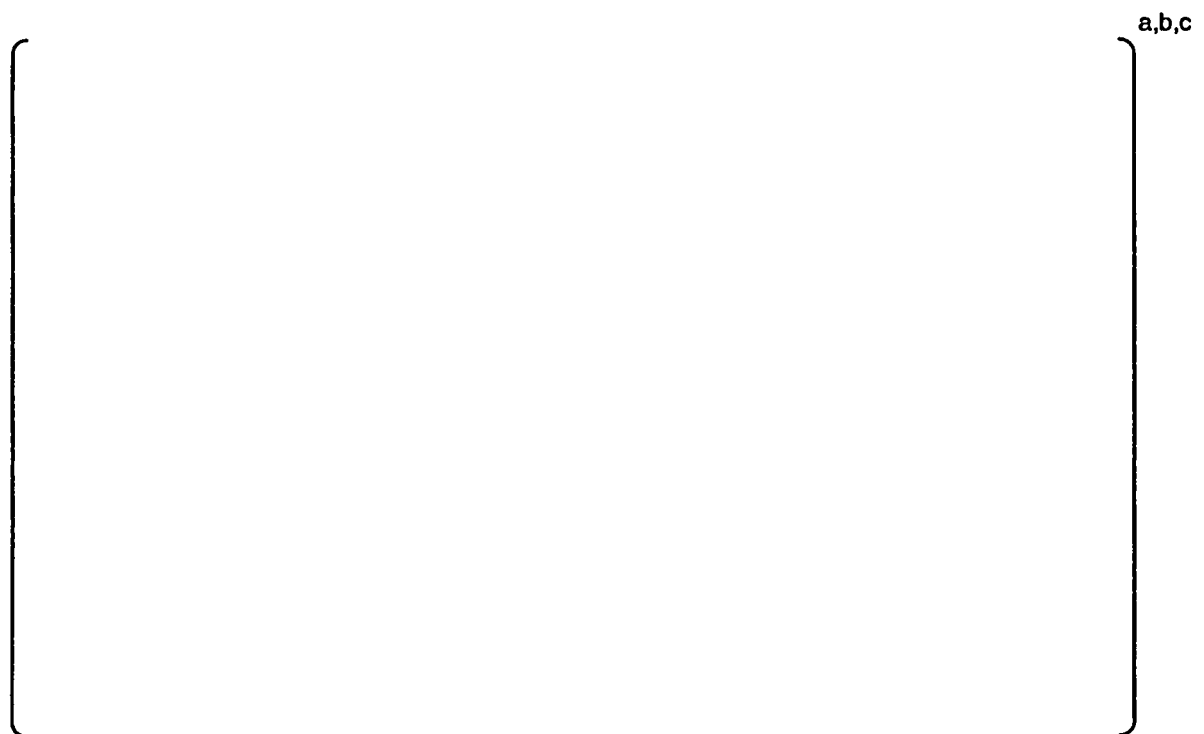


Figure C.35 Core Upper Half and Lower Half Collapsed Water Levels

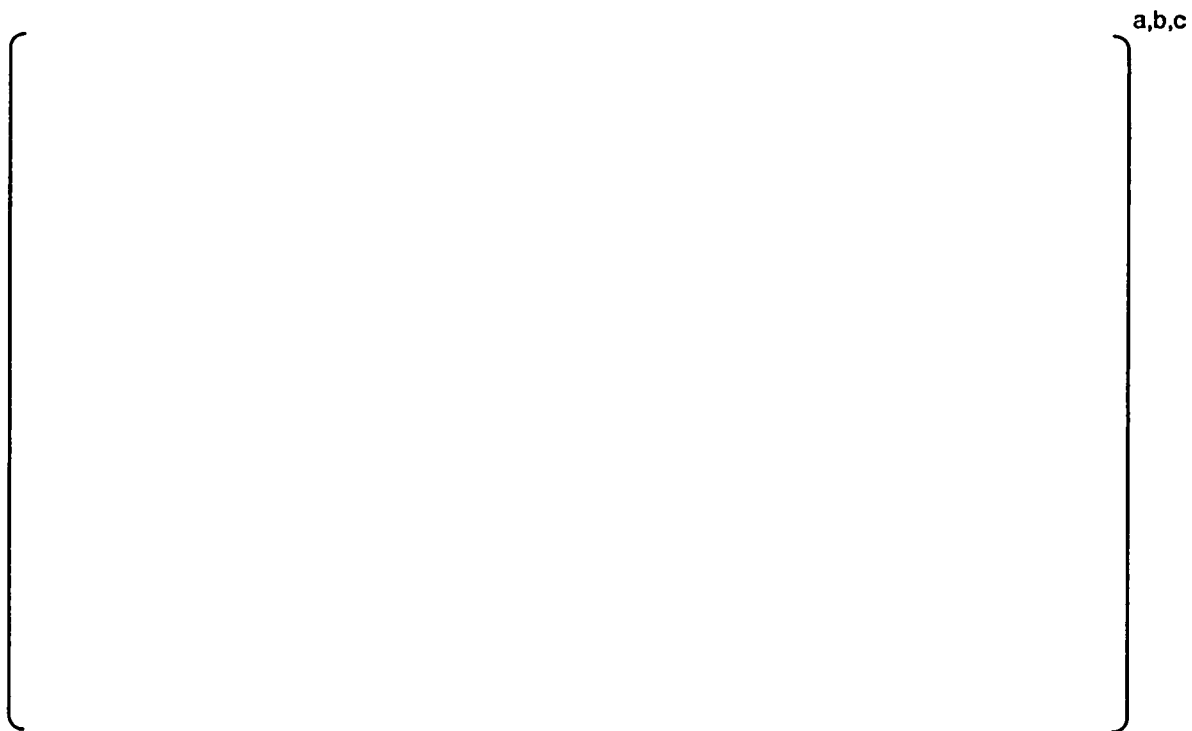


Figure C.36 Accumulator, CMT, and IRWST Flows to DVI1



Figure C.37 Accumulator, CMT, and IRWST Flows to DVI2



Figure C.38 Upper Plenum Two-Phase Level



Figure C.39 Hot Leg Collapsed Water Levels



Figure C.40 ADS4-2 (Pressurizer Side) Flow Quality



Figure C.41 Pressurizer Wide Range Collapsed Water Level



Figure C.42 Core Heater Rod Temperatures

C.6 NRC-AP1000-06

The purpose of this test was to investigate a significant failure of the ADS4 system for a small CL break. It is similar in intent to Test NRC-10, which was conducted for AP600 design certification. In NRC-10, a 1-inch CL break was simulated with three of the four ADS4 valves failed closed. The AP600 test indicated that a failure of three of the four ADS4 valves to open resulted in a significant delay in the start of IRWST injection. The liquid level dropped below the top of the core, and a temperature excursion was observed. This result did not agree with those of the ROSA counterpart, Test AP-CL-07. The difference in the APEX and ROSA results was attributed to the reduced elevation head available for IRWST injection in APEX.

Test NRC-AP1000-06 simulated a 2-inch equivalent diameter break at the bottom of CL4. This was a beyond-DBA test, with two of the four ADS4 valves failed closed. Table C.11 summarizes the facility configuration. Both of the failed valves were on the ADS4-1 line, which connects to the HL without the PZR. The PRHR HX was inactive during this test.

Table C.11 Facility Configuration for Test NRC-AP1000-06

Component	Configuration
ADS1	Normal actuation
ADS2	Normal actuation
ADS3	Normal actuation
ADS4-1 (non-PZR side)	Failed shut
ADS4-2 (PZR side)	100% ADS4-2 flow
Break	2-inch bottom of CL

Test NRC-AP1000-06 investigated a larger break size than NRC-10, but failed two of the four ADS4 valves. Similar to NRC-10, the water level dropped below the top of the core, and a temperature excursion occurred. Table C.12 summarizes the sequence of events for NRC-AP1000-06. Figure C.43 shows the vessel wide range collapsed water level, which remained above the top of the core until shortly after []^{a,b,c}, which is when the ACCs emptied. As the ACC flows decreased, the collapsed water level in the top half of the core decreased rapidly, as shown in Figure C.44. Figures C.45 and C.46 depict the flow from the ACCs, CMTs, and IRWST.

The CMTs both emptied by []^{a,b,c}. The system had not depressurized sufficiently to begin IRWST injection, so from this time until the test was terminated at []^{a,b,c}, there was no injection flow to the vessel. The two-phase level, shown in Figure C.47, remained above the bottom of the HLs until approximately []^{a,b,c}, as indicated by the two-phase level probe (LT-120). The two-phase level continued to decrease, and the upper plenum emptied at []^{a,b,c} (based on LDP-112). The minimum level that the two-phase probe can measure is approximately 2 inches above the upper core plate. Thus, the LT-120 measurement could not decrease after it "bottomed" at []^{a,b,c}.

Figure C.48 depicts the HL levels. Of particular interest, is the difference in levels at approximately []^{a,b,c}. The HL on the non-PZR side (HL1) emptied shortly before the two-phase level dropped below the bottom of the HLs. A level in the PZR side HL (HL2) remained even after the upper plenum emptied at []^{a,b,c}. Figure C.49 depicts the PZR water level, which remained high following ADS4 opening at []^{a,b,c}.

Flow quality to the ADS4-2 line, is low ($x < 0.1$) immediately following valve opening at []^{a,b,c} as shown in Figure C.49. The quality increased rapidly from approximately 0.1 to 0.4 shortly after accumulator injection stopped, and then increased again after the CMTs emptied. The quality increased from approximately 0.8 as the two-phase level dropped below the bottom of the HL, and remained less than 0.9 even after the upper plenum became empty at []^{a,b,c}.

At []^{a,b,c}, a core temperature excursion was observed, as shown in Figure C.51. The core power was manually scrammed. IRWST injection began immediately after to prevent heater rod damage.

Table C.12 Sequence of Events for Test NRC-AP1000-06

Time (s)	Events	a,b,c



Figure C.43 Vessel Wide Range Collapsed Water Level



Figure C.44 Core Upper Half and Lower Half Collapsed Water Levels



Figure C.45. Accumulator, CMT, and IRWST Flows to DVI1



Figure C.46 Accumulator, CMT, and IRWST Flows to DVI2

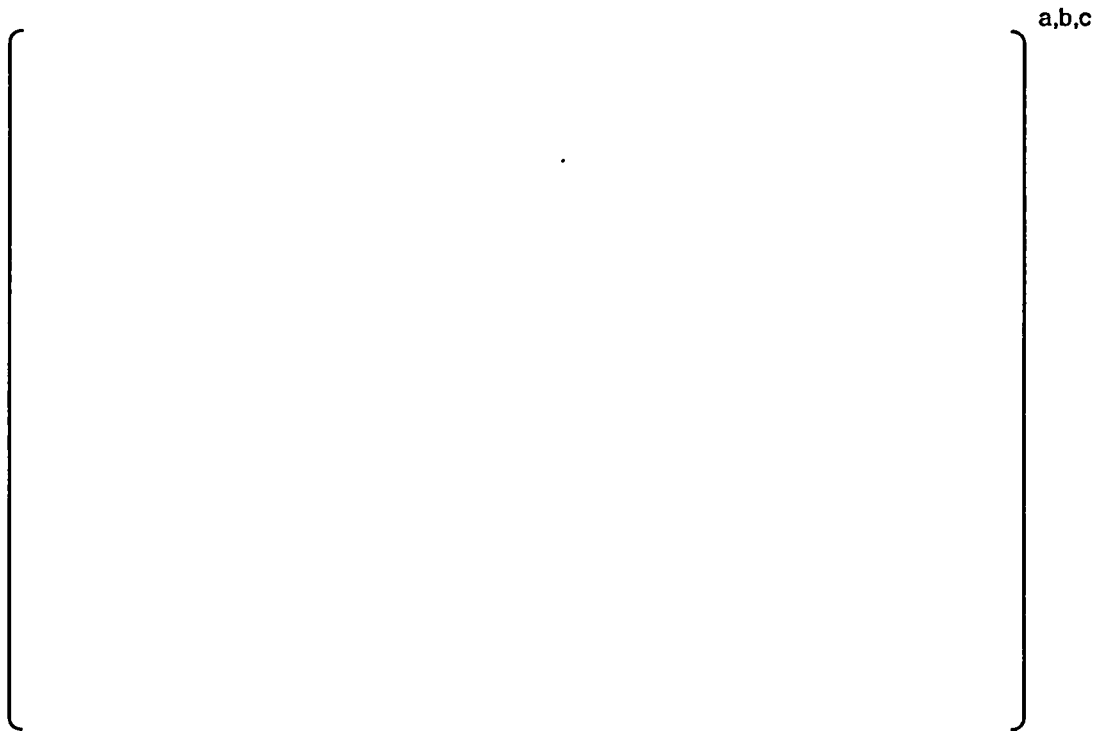


Figure C.47 Upper Plenum Two-Phase Level from Level Transmitter



Figure C.48 Hot Leg Collapsed Water Levels



Figure C.49 ADS4-2 Flow Quality



Figure C.50 Pressurizer Wide Range Collapsed Water Level

C.7 NRC-AP1000-10

The objective of this test was to obtain thermal-hydraulic data for PRA verification of a simulated AP1000 2-inch CL break off the bottom of CL4. The test was initiated from normal operating temperature and pressure. For this test, ADS1-3 and one of the four ADS4 valves failed to open on the non-PZR side of the plant. In addition, a []^{a,b,c} sharp edge orifice was installed in each SG PORV line. The SG PORVs were allowed to cycle between []^{a,b,c} (open) and []^{a,b,c} (closed) to help remove decay heat during the initial blowdown stage of the transient. The IRWST sump recirculation set point was changed from []^{a,b,c}. The test was terminated after 30 minutes of steady-state long-term cooling. Table C.13 shows the facility configuration for this test.

Table C.13 Facility Configuration for Test NRC-AP1000-10

Component	Configuration
ADS1	Failed shut
ADS2	Failed shut
ADS3	Failed shut
ADS4-1 (non-PZR side)	50% ADS4-1 flow
ADS4-2 (PZR side)	100% ADS4-2 flow
Break	2-inch bottom of CL 4

Table C.14 summarizes the sequence of events for this test. The break was initiated at zero seconds, and the CMTs immediately began to drain, as shown in Figures C.52 and C.53. The ACCs began to inject around []^{a,b,c} and, shortly afterward at []^{a,b,c}, the ADS4 valves opened. This caused the plant to further depressurize and increased ACC injection flow rates considerably, as shown in Figures C.52 and C.53.

Between []^{a,b,c}, there was a noticeable oscillation of IRWST injection flow rate (Figures C.52 and C.53), core liquid level (Figure C.54), and ADS4 line flow qualities (Figure C.59). The RPV pressure was very close to atmospheric by []^{a,b,c} (Figure C.58), and the HLs were almost completely flooded (Figure C.56). This oscillatory behavior is consistent with separate effects experiments run in ATLATS, which investigated the intermittent nature of liquid entrainment from the HLs into the vertical ADS4 lines.

The RPV liquid level reached a maximum around []^{a,b,c}, and then began to slowly decrease as the IRWST injection flow rate decreased. Oscillations were experienced again from []^{a,b,c}, because the core exit flow returned to saturated conditions as IRWST injection flow was considerably decreased. These RSOs are consistent with previous AP600 testing, and are described in Section 4.1.4 of this report. The plant entered long-term cooling at []^{a,b,c} when the sump recirculation lines were opened. Figure C.60 plots the RPV heater rod temperature and shows that the core remained adequately cooled during the entire test.

Table C.14 Sequence of Events for Test NRC-AP1000-10

Time (s)	Events	a,b,c

Source: NRC, "AP1000 Design Basis Accident Analysis," NRC Report NUREG-1806, Rev. 1, 2007.



Figure C.52 Side 1 Injection Flow Rates (ACC1, CMT1, and IRWST Line 1)



Figure C. 53 Side 2 Injection Flow Rates (ACC2, CMT2, and IRWST Line 2)

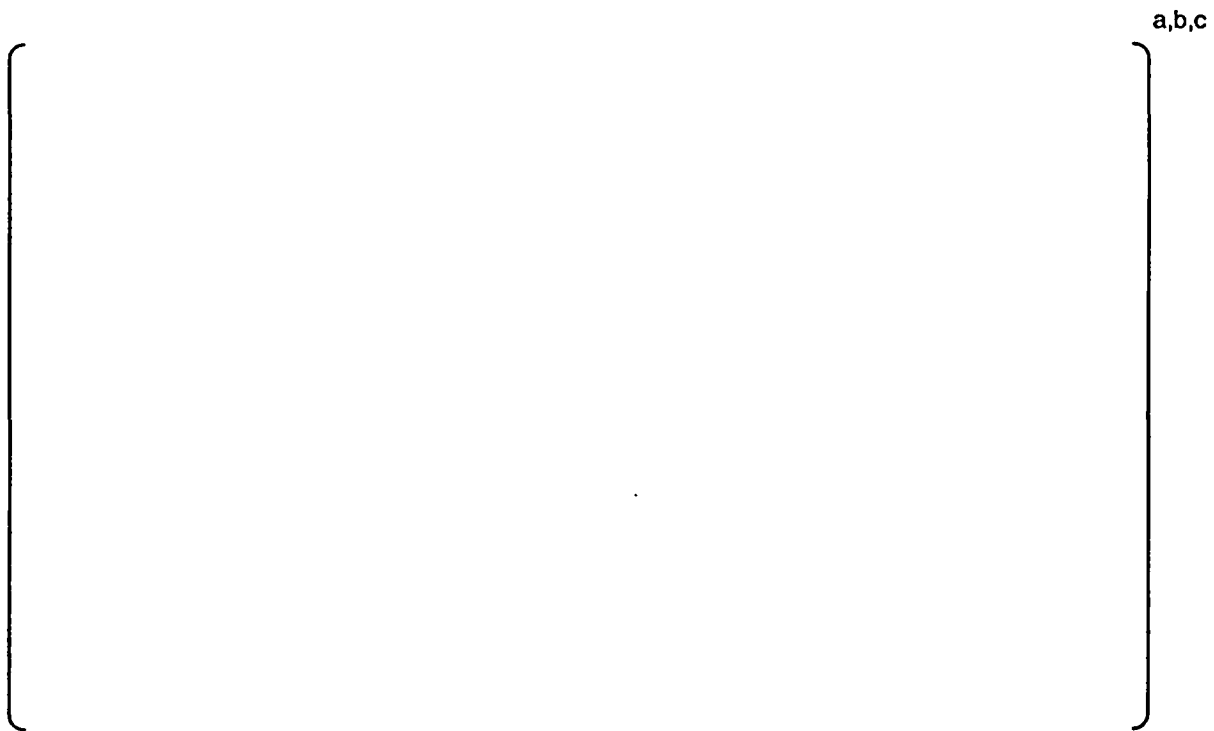


Figure C.54 RPV Collapsed Liquid Level



Figure C.55 RPV Mixture Level



Figure C. 56 Hot Leg Collapsed Liquid Levels



Figure C.57 Core Collapsed Liquid Levels



Figure C.58 PZR Wide Range Collapsed Liquid Level



Figure C.59 ADS4 Flow Qualities



Figure C.60 RPV Heater Rod Temperatures

C.8 NRC-AP1000-11

The objectives of this test were to (1) evaluate long-term PRHR HX operation including heatup of the IRWST to saturated temperature, (2) determine the effect of system behavior caused by ADS1-3 discharge to the saturated liquid inside the IRWST, and (3) determine the effects on long-term cooling caused by the injection of saturated liquid into the RPV from the IRWST.

The control logic was modified to simulate station blackout (loss of all AC power). The core was operated at reduced power (600 kW) and with a modified decay power curve to preserve integrated energy. The SG PORVs were set to cycle between []^{a,b,c}. When the SG wide range level decreased to []^{a,b,c}, an "S" signal was generated to open CMT injection valves and the PRHR HX outlet valve. The ADS was actuated []^{a,b,c} after initiation of the "S" signal. Table C.15 summarizes the facility configuration for this test.

Table C.15 Facility Configuration for Test NRC-AP1000-11

Component	Configuration
ADS1	Normal operation
ADS2	Normal operation
ADS3	Normal operation
ADS4-1 (non-PZR side)	50% ADS4-1 flow
ADS4-2 (PZR side)	100% ADS4-2 flow
Break	None

Table C.16 summarizes the sequence of events for this test. The main feed pump was tripped at zero seconds, and the RCP coastdown command was given at 1 sec. For the next []^{a,b,c}, the SG PORVs cycled open and closed. The plant slowly depressurized for about []^{a,b,c} as shown in Figure C.61. The CMTs began to inject at a low flow rate around []^{a,b,c} (Figures C.62 and 63).

At []^{a,b,c} ADS1-3 stages began to open, causing a rapid depressurization of the plant (Figure C.61). The ACCs began injecting about []^{a,b,c} later, and CMT injection flow increased significantly. Another jump in the ACC injection flow rate occurred at []^{a,b,c}, after ADS4 valve actuation. IRWST injection began by []^{a,b,c}, the CMTs and ACCs were emptied, illustrating about a 10-minute overlap in passive safety injection flow.

The RPV collapsed liquid level remained high until ADS actuation, when it dropped just below the top of the core, as shown in Figure C.64. However, the two-phase mixture level remained well above the bottom of the HL throughout the entire test (Figure C.65).

As the SG PORVs cycled open and closed between []^{a,b,c}, removing decay heat from the core, the RPV collapsed liquid level decreased (Figure C.64), while the PZR level increased, as shown in Figure C.67, as steam boiled off in the core filled the PZR. At about []^{a,b,c}, the PZR was completely filled (Figure C.67) and the primary system began to

pressurize (Figure C.61). At this time, the primary system went "solid" and the RPV liquid level remained constant (Figures C.64 and 65).

The last phase of the transient, sump recirculation cooling, began upon reaching a low level in the IRWST corresponding to the containment sump flood-up elevation. The PRHR HX and CMT operation were capable of removing core decay energy (Figure C.69) during the prolonged operation expected for a station blackout. The ADS1-4 blowdown was not affected by the saturated conditions inside the IRWST.

Table C.14 Sequence of Events for Test NRC-AP1000-11

Time (s)	Events	a,b,c



Figure C.61 RPV Head Pressure



Figure C.62 Side 1 Safety Injection Flow (ACC1, CMT1, and IRWST Line 1)



Figure C.63 Side 2 Safety Injection Flow (ACC2, CMT2, IRWST Line 2)



Figure C. 64 RPV Collapsed Liquid Level

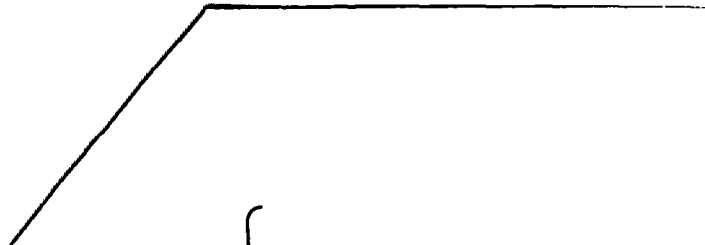


Figure C.65 RPV Mixture Level



Figure C.66 Hot Leg Collapsed Liquid Levels



Figure C.67 PZR Wide Range Collapsed Liquid Level



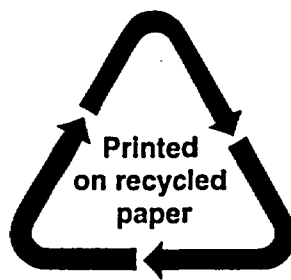
a,b,c

Figure C.68 Core Collapsed Liquid Levels

a,b,c

Figure C.69 RPV Heater Rod Temperatures

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